SONA COLLEGE OF TECHNOLOGY, SALEM-5

(An Autonomous Institution)

B.E-Mechatronics Engineering

CURRICULUM and SYLLABI

[For students admitted in 2018-2019]

B.E / B.Tech Regulation 2015R

Approved by BOS and Academic Council meetings

SONA COLLEGE OF TECHNOLOGY, SALEM – 636 005 (An Autonomous Institution)

Courses of Study for BE/BTech Semester I under Regulations 2015R (CBCS)

Branch: Mechatronics

| S.No. | Course Code | Course Title | L | Т | P | С | Group code | | |
|-------|-----------------------------|--|-------|-------|------|----|---------------|--|--|
| | | Theory | | | | | | | |
| 1 | U15ENG101AR | Technical English – I | 2 | 0 | 2 | 3 | HS | | |
| 2 | U15MAT102AR | Mathematics – I | 3 | 2 | 0 | 4 | BS | | |
| 3 | U15PHY103AR | Engineering Physics | 3 | 0 | 0 | 3 | BS | | |
| 4 | U15CHE104AR | Engineering Chemistry | 3 | 0 | 0 | 3 | BS | | |
| 5 | U15CPR105AR | U15CPR105AR Programming in C | | 0 | 0 | 3 | ES | | |
| 6 | U15EGR106AR | Engineering Graphics ¹ | 2 | 2 | 0 | 3 | ES | | |
| | | Practical | | | | | | | |
| 7 | U15PCL107AR | Physics and Chemistry Laboratory-I ² | 0 | 0 | 2 | 1 | BS | | |
| 8 | U15CPL108AR | C Programming Laboratory | 0 | 0 | 2 | 1 | ES | | |
| 9 | U15EPL109R | Engineering Practices Laboratory ³ | 0 | 0 | 2 | 1 | ES | | |
| | | | Total | l Cre | dits | 22 | | | |
| | Optional Language Elective* | | | | | | | | |
| 10 | U15OLE1101 | French | | | | | | | |
| 11 | U15OLE1102 | German | 0 | 0 | 2 | 1 | HS | | |
| 12 | U15OLE1103 | Japanese | | | | | | | |

^{*} Students may opt for foreign languages viz., German/French/Japanese with additional one credit (over and above the CGPA calculation).

Approved by

| HOD- First Year Dr. M. Renuga | Chairperson BOS/Civil & HOD-Civil Dr. R. Malathy | Chairperson BOS/EEE & HOD-EEE Dr. S. Padma | Chairperson BOS/ Mechanical & Mechatronics HOD-Mechanical Dr. D. Senthilkumar | Chairperson BOS/ FT & HOD-FT Dr. G. Gunasekaran |
|-------------------------------------|---|---|---|--|
|-------------------------------------|---|---|---|--|

¹ The examination will be conducted for 3 hours through written and practical modes.

² Laboratory classes on alternate weeks for Physics and Chemistry. The lab examination will be conducted separately for 50 marks each with 2 hours duration.

³ The lab examination will be conducted separately for Group A (Civil & Mechanical) and Group B (Electrical & Electronics) with 50 marks each with 1 ½ hours duration.

SONA COLLEGE OF TECHNOLOGY, SALEM – 636 005 (An Autonomous Institution)

Courses of Study for BE / B Tech Semester II under Regulations 2015R (CBCS) Branch: Mechatronics

| S.No. | Course Code | Course Title | L | Т | P | С | Group code | | |
|-----------|--|--|------|-------|------|----|---------------|--|--|
| | | Theory | | | | | | | |
| 1 | U15ENG201AR | Technical English –II | 2 | 0 | 2 | 3 | HS | | |
| 2 | U15MAT202AR | Mathematics – II | 3 | 2 | 0 | 4 | BS | | |
| 3 | U15PHY203FR | Physics For Mechatronics Engineering | 3 | 0 | 0 | 3 | BS | | |
| 4 | U15CHE205ER | Chemistry For Mechatronics Engineering | 3 | 0 | 0 | 3 | BS | | |
| 5 | 5 U15MEA206R Basic Mechanical and Electrical Engineering | | 3 | 0 | 0 | 3 | ES | | |
| 6 | U15GE207R | Engineering Mechanics | 2 | 2 | 0 | 3 | ES | | |
| Practical | | | | | | | | | |
| 7 | U15PCL208AR | Physics and Chemistry Laboratory – II# | 0 | 0 | 2 | 1 | BS | | |
| 8 | U15MEC209R | Manufacturing Technology Laboratory – I | 0 | 0 | 2 | 1 | ES | | |
| 9 | U15CDL210R | Computer Aided Drafting Laboratory | 0 | 0 | 2 | 1 | ES | | |
| | | | Tota | l Cre | dits | 22 | | | |
| | | Optional Language Elective* | | | | | | | |
| 10 | U15OLE1201 | French | | | | | HS | | |
| 11 | U15OLE1202 | German | 0 | 0 0 | 2 | 1 | | | |
| 12 | U15OLE1203 | Japanese | | | | | | | |

^{*}Students may opt for foreign languages viz., German/French/Japanese with additional one credit (over and above the CGPA calculation).

Approved by

| HOD-First Year Dr. M. Renuga | Chairperson BOS/ Mechatronics & HOD-Mechatronics Dr. P. Suresh | Member Secretary, Academic Council Dr. R. Shivakumar | Chairperson, Academic Council & Principal Dr. S.R.R. Senthilkumar |
|---------------------------------|---|--|---|
|---------------------------------|---|--|---|

^{*}Laboratory classes on alternate weeks for Physics and Chemistry. The lab examination will be conducted separately for 50 marks each with 2 hours duration.

Sona College of Technology, Salem

(An Autonomous Institution)

Courses of Study for B.E/B.Tech. Semester III under Regulations 2015R (CBCS)

Branch: Mechatronics Engineering

| S.No | Course Code | Course Title | Lecture | Tutorial | Practical | Credit | | | |
|------|---------------|--|---------|----------|-----------|--------|--|--|--|
| | | Theory | | | | | | | |
| 1 | U15MAT301DR | Transforms and Boundary Value Problems | 3 | 2 | 0 | 4 | | | |
| 2 | U15MC301R | Fluid Mechanics and Machinery | 3 | 0 | 0 | 3 | | | |
| 3 | U15MC302 | Strength of Materials | 3 | 0 | 0 | 3 | | | |
| 4 | U15MC303R | Manufacturing Technology | 3 | 0 | 0 | 3 | | | |
| 5 | U15MC304R | Electrical Machines and Drives | 3 | 0 | 0 | 3 | | | |
| 6 | U15MC305R | Electron Devices and Circuits | 3 | 0 | 0 | 3 | | | |
| | | Practical | | | | | | | |
| 7 | U15MC306R | Fluid Mechanics and Strength of Materials Laboratory | 0 | 0 | 4 | 2 | | | |
| 8 | U15MC307R | Electron Devices and Circuits Laboratory | 0 | 0 | 2 | 1 | | | |
| 9 | U15MC308R | Electrical Machines and Drives Laboratory | 0 | 0 | 4 | 2 | | | |
| 10 | U15GE301R | Soft Skill and Aptitude – I | 0 | 0 | 2 | 1 | | | |
| | Total Credits | | | | | | | | |

Approved By

Chairman, Mechatronics Engineernig BoS Dr.P.Suresh Member Secretary, Academic Council Dr.R.Shivakumar

Chairperson, Academic Council & Principal Dr.S.R.R.Senthil Kumar

Copy to:-

HOD/Mechatronics Engineering, Third Semester BE MCT Students and Staff, COE

03-6-2019 Regulations-2015R

Sona College of Technology, Salem

(An Autonomous Institution)

Courses of Study for B.E/B.Tech. Semester IV under Regulations 2015R (CBCS)

Branch: Mechatronics Engineering

| S.No | Course Code | Course Title | Lecture | Tutorial | Practical | Credit | | |
|---------------|-------------|--|---------|----------|-----------|--------|--|--|
| | | Theory | | | | | | |
| 1 | U15MAT401DR | Statistics and Numerical Methods | 3 | 2 | 0 | 4 | | |
| 2 | U15CHE405R | Environmental science and Engineering | 3 | 0 | 0 | 3 | | |
| 3 | U15MC401R | Applied hydraulics and pneumatics | 3 | 0 | 0 | 3 | | |
| 4 | U15MC402R | Theory of machines | 3 | 0 | 0 | 3 | | |
| 5 | U15MC403R | Sensors and Instrumentation | 3 | 0 | 0 | 3 | | |
| 6 | U15MC404R | Microprocessors and microcontrollers | 3 | 0 | 0 | 3 | | |
| | | Practical | | | | | | |
| 7 | U15MC405R | Hydraulics and pneumatics Laboratory | 0 | 0 | 4 | 2 | | |
| 8 | U15MC406R | Sensors and Instrumentation Laboratory | 0 | 0 | 2 | 1 | | |
| 9 | U15MC407R | Microprocessors and Microcontroller Laboratory | 0 | 0 | 4 | 2 | | |
| 10 | U15GE401R | Soft Skills and Aptitude – II | 0 | 0 | 2 | 1 | | |
| Total Credits | | | | | | | | |

Approved By

Chairperson, Mechatronics Engineering, BoS Dr.P.Suresh Member Secretary, Academic Council Dr.R.Shivakumar Chairperson, Academic Council & Principal Dr.S.R.R.Senthil Kumar

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HOD/ Mechatronics Engineering, Fourth Semester BE MCT Students and Staff, COE

09.12.2019 Regulations-2015R

Sona College of Technology, Salem (An Autonomous Institution)

Courses of Study for B.E/B.Tech. Semester V under Regulations 2015R (CBCS)

Branch: Mechatronics Engineering

| S. No | Course Code | Cour | rse Title | Lecture | Tutorial | Practical | Credit |
|-------|-------------|----------------------------|---|---------|----------|----------------------|--------|
| | | | Theory | | | | |
| 1 | U15MC501R | Computer Aided Design ar | nd Manufacturing | 3 | 0 | 2 | 4 |
| 2 | U15MC502R | Thermodynamics and Hear | t Transfer | 3 | 0 | 0 | 3 |
| 3 | U15CS508R | Object Oriented Programm | Object Oriented Programming and Data Structures | | 0 | 0 | 3 |
| 4 | U15MC503R | Embedded Systems and In | bedded Systems and Internet of Things | | | 0 | 3 |
| 5 | U15MC504R | Industrial Automation | | 3 | 0 | 0 | 3 |
| | U15MC901R | | Control Systems | | | | |
| 6 | U15MC902R | Professional Elective-1 | Industrial Drives | 3 | 0 | 0 | 3 |
| | U15MC903R | | Additive Manufacturing | | | | |
| | 1 | | Practical | 1 | | | |
| 7 | U15MC505R | Embedded Systems and In | ternet of Things Laboratory | 0 | 0 | 4 | 2 |
| 8 | U15MC506R | Industrial Automation Lab | oratory | 0 | 0 | 4 | 2 |
| 9 | U15MC507R | Mini Project-I | Mini Project-I | | 0 | 2 | 1 |
| 10 | U15GE501R | Soft Skills and Aptitude – | III | 0 | 0 | 2 | 1 |
| | • | • | | • | | Total Credits | 25 |

Approved By

Chairperson, Fashion Technology BoS Dr.P.Suresh Member Secretary, Academic Council Dr.R.Shivakumar

Chairperson, Academic Council & Principal Dr.S.R.R.Senthil Kumar

Copy to:-

HOD/ Mechatronics Engineering, Fifth Semester BE MCT Students and Staff, COE

13.05.2020 Regulations-2015R

Sona College of Technology, Salem

(An Autonomous Institution)

Courses of Study for B.E/B.Tech. Semester VI under Regulations 2015R (CBCS)

Branch: Mechatronics Engineering

| S. No | Course Code | | Course Title | Lecture | Tutorial | Practical | Credit |
|-------|--------------------|-------------------------------|--------------------------------------|---------|----------|-----------|--------|
| | | | Theory | | | | 1 |
| 1 | U15MC601R | Python programming | | 3 | 0 | 0 | 3 |
| 2 | U15MC602R | Power Electronics | ower Electronics | | | 2 | 4 |
| 3 | U15MC603R | Automotive Electronics | | 3 | 0 | 0 | 3 |
| 4 | U15MC604R | Artificial Intelligence | | 3 | 0 | 0 | 3 |
| 5 | noc21-me55 | Professional Elective: | Principles of Mechanical Measurement | - 3 | 0 | 0 | 3 |
| | noc21-ee05 | (NPTEL) | Control Engineering | 3 | U | 0 | 3 |
| | U15CE1004R | | Municipal Solid Waste Management | | | | |
| | U15EE1001R | | Electric Mobility | | | | |
| | U15EE1006R | | Renewable Energy Systems | | | | |
| | U15FT1001R | | Fundamentals of Fashion Design | | | | |
| 6 | U15IT1003R | Open Elective | Problem solving Techniques Using | 3 | 0 | 0 | 3 |
| | 013111003K | | Java Programming | | | | |
| | U15IT1005R | | Introduction to Database Technology | | | | |
| | U15ME1002R | | Renewable Energy Sources | | | | |
| | U15ME1004R | | Industrial Safety | | | | |

| Practical | | | | | | | | | |
|-----------|------------|---------------------------------|---|---|---------------|----|--|--|--|
| 7 | U15MC605R | Python Programming Laboratory | 0 | 0 | 4 | 2 | | | |
| 8 | U15ENG601R | Communication Skills Laboratory | 0 | 0 | 2 | 1 | | | |
| 9 | U15MC606R | Mini Project-II | 0 | 0 | 2 | 1 | | | |
| 10 | U15GE601BR | Soft Skill and Aptitude – IV | 0 | 0 | 2 | 1 | | | |
| | | | | | Total Credits | 24 | | | |

Approved By

Chairperson, Mechatronics Engineering BoS Dr.P.Suresh

Member Secretary, Academic Council Dr.R.Shivakumar

Chairperson, Academic Council & Principal Dr.S.R.R.Senthil Kumar

Copy to:-

HOD/ Mechatronics Engineering, Sixth Semester BE MCT Students and Staff, COE

Sona College of Technology, Salem

(An Autonomous Institution)

Courses of Study for B.E/B.Tech. Semester VII 2015R (CBCS)

Branch: Mechatronics Engineering

| S. No | Course Code | | Course Title | Lecture | Tutorial | Practical | Credit | Total Contact Hours |
|-------|-------------|-------------|--|---------|----------|-----------|--------|------------------------|
| | | | Theory | | | | | |
| 1 | U15GE701R | Professiona | al Ethics and Human Values | 3 | 0 | 0 | 3 | 45 |
| 2 | U15MC701R | Robotics | | 3 | 0 | 0 | 3 | 45 |
| 3 | U15MC702R | Micro Elec | tro Mechanical Systems | 3 | 0 | 0 | 3 | 45 |
| 4 | U15MC904R | Elective | Image Processing and Computer vision | 3 | 0 | 0 | 3 | 45 |
| 5 | U15MC905R | Elective | Industrial Engineering | 3 | 0 | 0 | 3 | |
| 3 | U15MC906R | Elective | Total quality management | 3 | U | U | 3 | 45 |
| | U15CS1004R | | Mobile Application Development | | | | | |
| | U15EC1008R | | Mobile Technology and its Applications | | | | | |
| | U15EE1004R | | Energy Conservation and Management | | | | | |
| | U15EE1006R | | Renewable Energy Systems | | | | | |
| | U15EE1007R | Open | Innovation, IPR and Entrepreneurship | | | | | |
| 6 | O13EE1007K | Elective | Development | 3 | 0 | 0 | 3 | 45 |
| | U15IT1003R | Elective | Problem Solving Techniques Using Java | | | | | |
| | 013111003K | | Programming | | | | | |
| | U15ME1004R | | Industrial Safety | | | | | |
| | U15ME1005R | | Maintenance Engineering | | | | | |
| | U15ME1010R | | 3D Printing | | | | | |

Page 1 of 2

| | | Practical | | | | | | | |
|---|---------------|-----------------------------|---|---|---|-----|----|--|--|
| 7 | U15MC703R | Robotics Laboratory | 0 | 0 | 4 | 2 | 60 | | |
| 8 | U15MC704R | Image Processing Laboratory | 0 | 0 | 3 | 1.5 | 45 | | |
| 9 | U15MC705R | Technical Seminar | 0 | 0 | 3 | 1.5 | 45 | | |
| | Total Credits | | | | | | | | |

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Chairperson, Mechatronics Engineering BoSDr.P.Suresh

Member Secretary, Academic Council Dr.R.Shivakumar Chairperson, Academic Council & Principal Dr.S.R.R.Senthil Kumar

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HOD/ Mechatronics Engineering, Seventh Semester BE MCT Students and Staff, COE

Page 2 of 2

Sona College of Technology, Salem (An Autonomous Institution)

Courses of Study for B.E/B.Tech. Semester VIII 2015R (CBCS)

Branch: Mechatronics Engineering

| S. No | Course Code | Course Title | Lecture | Tutorial | Practical | Credit | Total Contact Hours | | | |
|-------|---------------|--------------|---------|----------|-----------|--------|---------------------------|--|--|--|
| | Practical | | | | | | | | | |
| 1 | U15MC801R | Project Work | 0 | 0 | 24 | 12 | 360 | | | |
| | Total Credits | | | | | | | | | |

Approved By

Chairperson, Fashion Technology BoS

Dr.P.Suresh

Member Secretary, Academic Council Dr.R.Shivakumar Chairperson, Academic Council & Principal Dr.S.R.R.Senthil Kumar

Copy to:-

HOD/ Mechatronics Engineering, Eighth Semester BE MCT Students and Staff, COE

10.12.2021 Regulations-2015R

SONA COLLEGE OF TECHNOLOGY, SALEM – 636 005 (An Autonomous Institution)

Courses of Study for BE/BTech Semester I under Regulations 2015R (CBCS)

Branch: Mechatronics

| S.No. | Course Code | Course Title | L | Т | P | С | Group code |
|-----------------------------|--|---|---|---|---|---|---------------|
| Theory | | | | | | | |
| 1 | U15ENG101AR | Technical English – I | | 0 | 2 | 3 | HS |
| 2 | U15MAT102AR | Mathematics – I | | 2 | 0 | 4 | BS |
| 3 | U15PHY103AR | Engineering Physics | | 0 | 0 | 3 | BS |
| 4 | U15CHE104AR | Engineering Chemistry | | 0 | 0 | 3 | BS |
| 5 | U15CPR105AR | Programming in C | | 0 | 0 | 3 | ES |
| 6 | U15EGR106AR | Engineering Graphics ¹ | 2 | 2 | 0 | 3 | ES |
| Practical | | | | | | | |
| 7 | U15PCL107AR Physics and Chemistry Laboratory-I ² | | 0 | 0 | 2 | 1 | BS |
| 8 | U15CPL108AR | C Programming Laboratory | | 0 | 2 | 1 | ES |
| 9 | U15EPL109R | Engineering Practices Laboratory ³ | 0 | 0 | 2 | 1 | ES |
| Total Credits 22 | | | | | | | |
| Optional Language Elective* | | | | | | | |
| 10 | U15OLE1101 | French | | | | | |
| 11 | U15OLE1102 | German | 0 | 0 | 2 | 1 | HS |
| 12 | U15OLE1103 | Japanese | | | | | |

^{*} Students may opt for foreign languages viz., German/French/Japanese with additional one credit (over and above the CGPA calculation).

Approved by

| HOD- First Year Dr. M. Renuga | Chairperson BOS/Civil & HOD-Civil Dr. R. Malathy | Chairperson BOS/EEE & HOD-EEE Dr. S. Padma | Chairperson BOS/ Mechanical & Mechatronics HOD-Mechanical Dr. D. Senthilkumar | Chairperson BOS/ FT & HOD-FT Dr. G. Gunasekaran |
|-------------------------------------|---|---|---|--|
|-------------------------------------|---|---|---|--|

¹ The examination will be conducted for 3 hours through written and practical modes.

² Laboratory classes on alternate weeks for Physics and Chemistry. The lab examination will be conducted separately for 50 marks each with 2 hours duration.

³ The lab examination will be conducted separately for Group A (Civil & Mechanical) and Group B (Electrical & Electronics) with 50 marks each with 1 ½ hours duration.

U15ENG101AR - TECHNICAL ENGLISH I

L T P C M 2 0 2 3 100

Course Outcomes

At the end of the course, the students will be able to,

- 1. frame sentences correctly, both in written and spoken forms of language with accuracy and fluency.
- 2. develop and demonstrate listening skills for academic and professional purposes.
- 3. draw conclusions on explicit and implicit oral information.
- 4. develop effective reading skills and reinforce language skills required for using grammar and building vocabulary.
- 5. read for gathering and understanding information, following directions and giving responses.

UNIT I - FOCUS ON LANGUAGE

- General Vocabulary
- Prefixes and Suffixes
- Active and Passive Voices
- Adjectives, Comparative Adjectives
- Prepositions and Dependent Prepositions
- Collocations
- Tenses
- Modal Verbs and Probability

UNIT II - LISTENING -I

- Listening to conversations, welcome speeches, lectures and description of equipment.
- Listening to different kinds of interviews (face-to-face, radio, TV and telephone interviews).
- Understanding short conversations or monologues.
- Taking down phone messages, orders, notes etc.
- Listening for gist, identifying topic, context or function.

UNIT III - LISTENING - II

- Listening comprehension, entering information in tabular form.
- Intensive listening exercises and completing the steps of a process.
- Listening exercises to categorise data in tables.
- Listening to extended speech for detail and inference.

UNIT IV - READING -I

- Understanding notices, messages, timetables, advertisements, graphs, etc.
- Reading passages for specific information transfer.
- Reading documents for business and general contexts and interpreting graphical representations.
- Error correction, editing mistakes in grammar, vocabulary, spelling, etc.
- Oral reading poetry and prose excerpts, general and technical articles, and anecdotes.

UNIT V - READING -II

- Reading passage with multiple choice questions, reading for gist and reading for specific information, skimming for comprehending the general idea, meaning and contents of the whole text.
- Short reading passage: gap-filling exercise related to grammar, testing the understanding of prepositions, articles, auxiliary verbs, modal verbs, pronouns, relative pronouns and adverbs.
- Short reading passage with multiple choice questions, gap-filling exercise testing the knowledge of vocabulary, collocations, dependent prepositions, grammatical structures.
- Short reading passages for sentence matching exercises, picking out specific information in a short text.

Total: 45 Hours

Listening test will be conducted for 20 marks internally and evaluated along with Technical English – I in the End Semester Valuation.

Reading test will be conducted for 20 marks internally and evaluated by internal examiners.

TEXTBOOK

1. Technical English – I & II, Dr. M. Renuga, et al. Sonaversity, Sona College of Technology, Salem, Revised edition, 2016.

EXTENSIVE READING

- 1. The Story of Amazon.com- Sara Gilbert, published by Jaico
- 2. The Story of Google Sara Gilbert, published by Jaico

REFERENCE BOOKS

- 1. Norman Whitby, Business Benchmark Pre-Intermediate to Intermediate, Students Book, Cambridge University Press, 2006.
- 2. A Course in Communication Skills, P. Kiranmai Dutt, Geetha Rajeevan, C. L. N. Prakash, published by Cambridge University Press India Pvt. Ltd.

U15MAT102AR - MATHEMATICS - I

(Common to Civil, Mech, Mechatronics, EEE, IT and FT Branches)

L T P C M 3 2 0 4 100

Course Outcomes

At the end of the course, the students will be able to,

- 1. find the Eigen values and Eigen vectors of a real matrix and discuss their properties, reduce a real symmetric matrix from quadratic form to canonical form.
- 2. explain the three dimensional Cartesian coordinates and discuss the problems in straight line, plane and sphere.
- 3. describe curvature and find the radius of curvature, circle of curvature, evolutes, involutes and envelope of curves.
- 4. explain functions of several variables and find the Taylor's series expansion, Jacobians, maximum and minimum values of function of several variables.
- 5. describe the double and triple integrals, discuss the change of order of integration and find the area and volume by multiple integrals.

UNIT I – MATRICES 9+6

Characteristic equation – Eigen values and Eigen vectors of a real matrix – properties – statement of Cayley – Hamilton theorem and its applications – orthogonal transformation of symmetric matrix to diagonal form – quadratic form – reduction of quadratic form to canonical form by orthogonal transformation.

UNIT II – THREE DIMENSIONAL ANALYTICAL GEOMETRY 9+6

Direction cosines and ratios, angle between two lines – equation of plane, angle between two planes – equation of the straight line, coplanar lines, skew lines – equation of a sphere, plane section of a sphere, tangent plane, orthogonal spheres.

UNIT III - DIFFERENTIAL CALCULUS AND ITS APPLICATIONS

9+6

Curvature in Cartesian coordinates, centre and radius of curvature, circle of curvature – evolutes, envelopes, evolute as the envelope of normals.

UNIT IV - FUNCTIONS OF SEVERAL VARIABLES

9+6

Partial derivatives, total differentiation – differentiation of implicit functions – Taylor's expansion – maxima and minima, constrained maxima and minima by Lagrange's multiplier method – Jacobians – properties.

UNIT V - MULTIPLE INTEGRALS

9+6

Evaluation of double integrals in Cartesian and polar coordinates – change of order of integration – change of variables from Cartesian to polar coordinates – area as double integral – evaluation of triple integrals in Cartesian coordinates – volume as triple integral in Cartesian coordinates.

Total: 75 Hours

TEXT BOOKS

- 1. B.S.Grewal, "Higher Engineering Mathematics", Khanna Publishers, New Delhi, 43rd Edition, 2014.
- 2. T. Veerarajan, "Engineering Mathematics" (I Year), Tata McGraw Hill, 4th Edition, 2011.

REFERENCE BOOKS

- 1. P.Kandasamy, K.Thilagavathy and K.Gunavathy, "Engineering Mathematics", (for first year), S. Chand and Co., Ltd., Revised Edition 2011.
- 2. E.Kreyszig, "Advanced Engineering Mathematics", International Student Version, Wiley, 10th Edition, 2015.
- 3. S. Jayabharathi, "Mathematics I", Sonaversity, Revised Edition, 2017.
- 4. N. P. Bali and M. Goyal, "Engineering Mathematics", University Science Press, New Delhi, 9th Edition, 2011.

U15PHY103AR - ENGINEERING PHYSICS

(Common to B.E. Mech, Mechatronics, Civil, EEE, CSE & B.Tech. IT, FT Branches)

L T P C M 3 0 0 3 100

Course Outcomes

At the end of the course, the students will be able to,

- 1. design acoustically good buildings and describe the applications of ultrasonic waves in the field of non-destructive testing
- 2. classify lasers and explain its applications in the field of medicine, engineering and technology.
- 3. elucidate the principle of optical fibre communication, applications and the devices involved in the transmission and reception of data.
- 4. illustrate the dual nature of matter and radiation and its applications.
- 5. analyze crystal structures and the significance of defects in crystals.

UNIT I - ACOUSTICS AND ULTRASONICS

9

Classification of sound, Pitch, Loudness, Intensity level, Phon, Timbre, Reverberation, Reverberation time – Sabine's formula and its importance (no derivation) – Sound absorbing materials - Absorption Coefficient and its determination – Factors affecting acoustics of buildings and their remedies — Production of ultrasonic waves by magnetostriction and piezoelectric methods – acoustic grating – Acoustic impedance - Non Destructive Testing – Ultrasonic flaw detector – A scan display - Sonogram (block diagram).

UNIT II - LASERS

9

9

Principle of spontaneous and stimulated emission – Population inversion - Pumping – Einstein's A and B coefficients derivation – Basic requirements of a laser - Types of lasers

- Nd:YAG laser, CO₂ and Semiconductor lasers (homojunction & heterojunction)
- Qualitative applications Lasers in welding, heat treatment and cutting Medical applications (qualitative) holography construction and reconstruction.

UNIT III – FIBRE OPTICS AND APPLICATIONS

Principle and propagation of light in optical fibers – Numerical aperture and acceptance angle – Types of optical fibres (material, refractive index, mode) – Double Crucible Technique of fibre drawing – Splicing – Loss in optical fibre – attenuation, dispersion

and bending - Fibre optic communication system (Block diagram) — Fibre optic sensors - temperature and displacement sensor - Endoscope.

UNIT IV – QUANTUM PHYSICS

9

Introduction – Compton Effect theory and experimental verification – Matter waves – Schrodinger's time independent and time dependent wave equation - Physical significance of the wave function – Particle in a one dimensional box – Evolution of microscope - Electron microscope – Comparison of optical and electron microscope - Scanning electron microscope.

UNIT V - CRYSTALLOGRAPHY

9

Crystalline Solids – Amorphous solids – Space Lattice - Unit cell – Bravais lattice – Lattice planes – Miller indices – d spacing in cubic lattice – Calculation of number of atoms per unit cell – Atomic radius – Coordination number and atomic packing factor for SC, BCC, FCC and HCP Structures – Polymorphism and allotropy – Crystal imperfections: point, line and surface defects – burger vector.

Total: 45 Hours

TEXT BOOKS

- 1. B. K. Pandey and S. Chaturvedi, Engineering Physics, Cengage Learning India Pvt. Ltd., Delhi, 2012.
- 2. M. Arumugam, 'Engineering Physics' Anuradha Publications, Kumbakonam, 2006.

REFERENCE BOOKS

- C. Shanthi et al., Engineering Physics, Sonaversity, Sona College of Technology, Salem (Revised edition, 2016).
- R. K. Gaur and S.C. Gupta, Engineering Physics, Dhanpat Rai Publications, New Delhi, 2003.
- 3. V. Rajendran and A. Marikani, Engineering Physics, Tata Mc Graw Hill Publications Ltd, III Edition, New Delhi, 2004.
- M.N. Avadhanulu and PG Kshirsagar, A Text book of Engineering Physics,
 S.Chand and company, Ltd., New Delhi, 2005.

U15CHE104AR - ENGINEERING CHEMISTRY

(Common to BE - Civil, EEE, Mech, Mechatronics & BTech - FT)

L T P C M 3 0 0 3 100

Course Outcomes

At the end of the course, the students will be able to,

- 1. analyze the types of impurities present in water, their removal methods and explain the conditioning methods for domestic and industrial uses.
- 2. outline the principles and applications of electrochemistry to engineering and technology.
- 3. compare the types of corrosion and describe the methods of corrosion control.
- 4. outline the principle and applications of surface chemistry and catalysis in engineering and technology.
- 5. illustrate the basics of nano chemistry, synthesis, properties and applications of nano materials in engineering and technology.

UNIT I - WATER TECHNOLOGY

9

Introduction - Characteristics - hardness - estimation of hardness by EDTA method - alkalinity and its estimation - Boiler feed water - requirements - disadvantages of using hard water in boilers - internal conditioning (colloidal - phosphate - calgon and carbonate conditioning methods) - external conditioning - zeolite process, demineralization process - desalination of brackish water by reverse osmosis - Domestic water treatment - screening, sedimentation - coagulation - aeration - sand filtration and disinfection methods - Chlorination - ozonation and UV treatment.

UNIT II - ELECTROCHEMISTRY

9

Electrode potential - Nernst Equation - derivation and problems based on single electrode potential calculation - reference electrodes - standard hydrogen electrode - calomel electrode - Ion selective electrode - glass electrode - measurement of pH - electrochemical series – significance – electrolytic and electrochemical cells – reversible and irreversible cells – EMF – measurement of emf – potentiometric titrations (redox – Fe^{2+} vs dichromate) – conductometric titrations (acid-base – HCl vs NaOH).

UNIT III - CORROSION AND CORROSION CONTROL

Chemical corrosion - Pilling-Bedworth rule - electrochemical corrosion - mechanism - galvanic corrosion - differential aeration corrosion - factors influencing corrosion - corrosion control - sacrificial anode and impressed cathodic current methods - corrosion inhibitors - protective coatings - preliminary treatment - Paints constituents and their functions - surface conversion coatings - Galvanizing and Tinning.

UNIT IV – SURFACE CHEMISTRY AND CATALYSIS 9

Adsorption – types-physical and chemical adsorption – adsorption of gases on solids-adsorption isotherms – Freundlich and Langmuir isotherms-adsorption of solutes from solution—applications of adsorption-role of adsorption in catalytic reactions—ion exchange adsorption-basic principles in adsorption chromatography – adsorption in pollution abatement (granular activated carbon and powdered activated carbon) – catalysis-types - characteristics of catalysts - autocatalysis - definition and examples.

UNIT V - NANOCHEMISTRY

9

9

Basics - distinction between molecules, nanoparticles and bulk materials – size-dependent properties – nanoparticles: nano cluster, nano rod, nanotube (CNT) and nanowire – Synthesis: precipitation – thermolysis – hydrothermal – solvothermal – electrodeposition - chemical vapour deposition - sol-gel technique – properties and applications of nano materials.

Total: 45 Hours

TEXT BOOKS

- P.C.Jain and Monica Jain, "Engineering Chemistry" Dhanpat Rai Pub, Co., New Delhi, 2010 (15th Edition).
- B. Sivasankar "Engineering Chemistry" Tata McGraw-Hill Pub.Co.Ltd, New Delhi, 2008.

REFERENCE BOOKS

- 1. T. Maruthavanan et al., "Engineering Chemistry", Sonaversity, Sona College of Technology, Salem, Revised Edition 2018.
- 2. Kannan P., Ravikrishnan A., "Engineering Chemistry", Sri Krishna Hi-tech Publishing Company Pvt. Ltd., Chennai, 2009.
- 3. H.K. Chopra, A. Parmer, "Chemistry for Engineers", Narosa Publishing House, New Delhi, 110 002, 2016.
- 4. Ozin G. A. and Arsenault A. C., "Nanochemistry: A Chemical Approach to Nanomaterials", RSC Publishing, 2005.

U15CPR105AR - PROGRAMMING IN C

(Common to BE - CIVIL, CSE, EEE, MECH, Mechatronics, B.Tech - FT, IT)

L T P C M 3 0 0 3 100

Course Outcomes

At the end of the course, the students will be able to,

- 1. formulate problems, apply logics to solve problems by practice and outline the basics of computer technology
- 2. write, compile and find errors in simple c programs
- 3. apply the concepts such as arrays, decision making and looping statements to solve real-time applications
- 4. examine the power of functions and pointers to become expert programmers in c
- 5. solve simple scientific and statistical problems using structures and unions

UNIT I – INTRODUCTION TO PROBLEM SOLVING AND COMPUTERS

8

Problem formulation, Problem Solving methods, Need for logical analysis and thinking – Algorithm – Pseudo code – Flow Chart. Need for computer languages, Generation and Classification of Computers- Basic Organization of a Computer

UNIT II – C PROGRAMMING BASICS

10

Structure of a C program – Compiling and Debugging a C program - C Character set, Identifies and Keywords, Data Types, Declarations, Expressions, Statements and Symbolic constants, Operators – Arithmetic Operators – Unary operators – Relational and Logical Operators – Assignment operators – Conditional operators. Managing Input and Output operations, pre-processor directives and storage classes

UNIT III – CONTROL STATEMENTS, ARRAYS AND STRINGS 9

Unconditional statements, conditional statements, branching and looping statements - Arrays - Initialization - Declaration - One dimensional and Two dimensional arrays. String- String operations - String Arrays. Simple programs- sorting- searching - matrix operations and solving simple scientific and statistical problems

UNIT IV – FUNCTIONS AND POINTERS

9

Function – Library functions and user-defined functions – Function prototypes and function definitions – Call by value –Call by reference – Recursion – Pointers - Definition – Initialization – Pointers arithmetic – Pointers and arrays- Example Problems. Pointers and Functions

UNIT V - STRUCTURES AND UNIONS

9

Introduction – need for structure data type – structure definition – Structure declaration – Structure within a structure – Passing structures to functions – Array of structures – Pointers to structures. Union - Programs using structures and Unions

Total: 45 Hours

TEXT BOOKS

- 1. Yashavant P. Kanetkar, "Let Us C", BPB Publications, 2011.
- 2. Balagurusamy E, "Programming in ANSI C", sixth edition, Tata Mcgraw-Hill, 2012.

REFERENCE BOOKS

- 1. Deitel and Deitel, "C How to Program", Pearson Education, New Delhi, 2011.
- 2. Byron S Gottfried, "Programming with C", Schaums Outlines, Second Edition, Tata McGraw-Hill, 2006.
- 3. Kernighan, B.W and Ritchie, D.M, "The C Programming language", Second Edition, Pearson Education, 2006.
- Anita Goel and Ajay Mittal, "Computer Fundamentals and Programming in C", Dorling Kindersley (India) Pvt. Ltd., Pearson Education in South Asia, 2011.

U15EGR106AR - ENGINEERING GRAPHICS

L T P C M 2 2 0 3 100

Course Outcomes

At the end of the course, the students will be able to,

- predict the construction of various curves in civil elevation plan and machine components.
- 2. draw the projection of three dimensional objects representation of machine structure and explain standards of orthographic views by different methods.
- 3. analyze the principles of projection of various planes by different angle to project points, lines and planes.
- 4. draw the principles of projection of simple solid by the axis is inclined to one reference plane by change of position method. understand the interior components of machinery (or) buildings by sectioning the solid,
- 5. study the development of simple solids for fabrication of sheet metals.

CONCEPTS AND CONVENTIONS (Not for Examination) 12

Importance of graphics in engineering applications, Use of drafting instrument, BIS conventions and specifications - Size, layout and folding of drawing sheets, Lettering and dimensioning.

COMPUTER AIDED DRAFTING (Not for Examination) 12

Importance 2d Drafting, sketching, modifying, transforming and dimensioning.

UNIT I – PLANE CURVES (Free hand sketching)

12

Curves used in engineering practices

Conics – Construction of ellipse – Parabola and hyperbola by eccentricity method – Construction of cycloid – construction of involutes of square and circle – Drawing of tangents and normal to the above curves.

UNIT II – ISOMETRIC TO ORTHOGRAPHIC VIEWS (Free Hand Sketching) 12

Representation of three dimensional objects – General Principles of Orthographic projection – Need for importance of multiple views and their placement – First angle projection – layout of views – Developing visualization skills through free hand sketching

of multiple views from pictorial views of objects.

UNIT III – PROJECTION OF POINTS, LINES AND PLANE SURFACES (Free hand sketching and 2D Software) 12

Projection of points – Projection of straight lines located in the first quadrant – Determination of true lengths and true inclinations – Projection of polygonal surface and circular lamina inclined to one reference planes.

UNIT IV – PROJECTION OF SOLIDS

12

(Free hand sketching and 2D Software)

Projection of simple solids like prisms – pyramids – cylinder and cone when the axis is inclined to one reference plane by change of position method.

UNIT V - SECTION OF SOLIDS AND DEVELOPMENT OF SURFACES (Free hand sketching and 2D Software) 12

Sectioning of simple solids like prisms – pyramids, cylinder and cone in simple vertical position by cutting planes inclined to one reference plane and perpendicular to the other, (Obtaining true shape of section is not required). Development of lateral surfaces of simple and truncated solids – Prisms – pyramids –cylinders and cones.

TEXT BOOKS

- 1. P. Suresh et al., "Engineering Graphics and Drawing", Sonaversity, Sona College of Technology, Salem, Revised edition, 2012.
- 2. K.V. Natarajan Engineering Graphics by, Chennai, 17th edition 2003.

REFERENCE BOOKS

- Dhananjay A. Jolhe, Engineering Drawing with an introduction to AutoCAD, Tata McGraw Hill Publishing Company Limited, 2008.
- 2. Basant Agarwal and Agarwal C.M., Engineering Drawing, Tata McGraw Hill Publishing Company Limited, New Delhi, 2008.
- K. R. Gopalakrishnana, Engineering Drawing (Vol. I & II), Subhas Publications, 1998.
- 4. Bertoline & Wiebe fundamentals of graphics communication III edition McGrawhill 2002.

U15PCL107AR - PHYSICS AND CHEMISTRY LABORATORY I

(Common to CIVIL, EEE, Mech, Mechatronics & FT Branches)

L T P C M 0 0 2 1 100

Course Outcomes

At the end of the course, the students will be able to,

- 1. apply the principles of optics, thermal physics and elasticity to determine the engineering properties of materials.
- 2. analyse the given water sample to determine the amount of hardness and alkalinity.
- 3. determine the thickness of the given copper turn used for house hold applications and evaluate the amount of alkalinity, pH, conductivity and iron content of house hold water sample.

List of Experiments – (PHYSICS PART)

- 1. Determination of the thickness of a thin wire by forming interference fringes using air wedge apparatus.
- 2. Determination of the wavelength and velocity of ultrasonic waves and the compressibility of a given liquid using the ultrasonic interferometer.
- 3. Determination of thermal conductivity of a bad conductor using Lee's disc apparatus.
- 4. Determination of the angle and dispersive power of a given prism using a spectrometer.
- 5. Determination of laser wavelength, particle size (lycopodium powder), acceptance angle and numerical aperture of an optical fibre using a diode laser.
- 6. Determination of the Young's modulus of a given material by non-uniform bending method.

(Any five experiments may be conducted from the above list)

List of Experiments – (CHEMISTRY PART)

- 1. Estimation of hardness of water by EDTA method.
- 2. Estimation of alkalinity of water by indicator method.
- 3. Estimation of hydrochloric acid by pH metry.
- 4. Conductometric titration of strong acid vs strong base (HCl vs NaOH).
- 5. Estimation of ferrous iron by potentiometric titration (Fe²⁺ vs dichromate).
- 6. Estimation of corrosion in iron sheets by weight loss method.

(Any five experiments may be conducted from the above list)

Total: 30 Hours

U15CPL108AR - C PROGRAMMING LABORATORY

(Common to BE - CIVIL, CSE, EEE, Mech, Mechatronics & BTech FT, IT)

L T P C M 0 0 2 1 100

Course Outcomes

At the end of the course, the students will be able to,

- 1. design and develop simple programs using branching, looping statements, functions and arrays
- 2. develop programs using structures, strings, pointers and recursion
- 3. effectively choose programming components that efficiently solve computing problems in real-world

List of Experiments

- 1. Programs using Input, Output and assignment statements
- 2. Programs using Branching statements
- 3. Programs using Looping statements
- 4. Programs using Functions
- 5. Programs using one dimensional and two dimensional arrays
- 6. Programs using Structures
- 7. Programs using Strings
- 8. Programs using Pointers (both data pointers and function pointers)
- 9. Programs using Recursion

Total: 30 Hours

U15EPL109R - ENGINEERING PRACTICES LABORATORY

(Common to all Branches)

L T P C M 0 0 2 1 100

Course Outcomes

At the end of the course, the students will be able to,

- 1. plan the pipe connections using PVC, G.I pipes
- analyze the process of wood separation with proper types of joints using tools and machines
- 3. demonstrate the method of material removal from metal components and assemble the components using sheet metals
- 4. demonstrate the working principles of house wiring and Fluorescent lamp wiring
- 5. analyze the functions of logic gates (AND, OR, NOT, NAND, NOR and Ex-OR)

List of Experiments

GROUP A (CIVIL & MECHANICAL)

1. CIVIL ENGINEERING PRACTICE

PLUMBING WORKS

- a. Basic pipe connections (PVC) involving the fittings like Valves, Taps, and Bends.
- Mixed pipe (PVC and G.I) connections involving the fitting like Valves, Taps, and Bends

CARPENTRY WORKS

- a. Planning
- b. Lap joint
- c. Cross lap joint

II MECHANICAL ENGINEERING PRACTICE

SHEET METAL WORK

- a. Square tray
- b. Funnel

FITTING WORK

- a. L joint
- b. V-joint
- c. Demonstration of Welding classes

GROUP B (ELECTRICAL & ELECTRONICS)

ELECTRICAL ENGINEERING

- 1. Study of Resistor, Inductor and capacitor-ratings-colour coding-series and parallel equivalence.
- 2. House wiring
- 3. Fluorescent lamp wiring.
- 4. Stair-case Wiring and Door bell wiring
- 5. Measurement of circuit parameters for RLC series circuit..
- 6. Measurement of Energy using Energy meter for Single Phase system.
- 7. Study of Fan and Iron Box.

ELECTRONICS ENGINEERING

- 1. Verification of Ohm's Law
- 2. Measurement of Amplitude and frequency of AC wave forms using CRO.
- 3. Verification of logic gates (AND, OR, NOT, NAND, NOR and ExOR).
- 4. Generation of Clock Signal using IC 555 timer.
- 5. Soldering practice Components Devices and Circuits Using general purpose PCB.
- 6. Study of Multimeter

Total: 45 Hours

SONA COLLEGE OF TECHNOLOGY, SALEM – 636 005 (An Autonomous Institution)

Courses of Study for BE / B Tech Semester II under Regulations 2015R (CBCS) Branch: Mechatronics

| S.No. | Course Code | Course Title | L | Т | P | С | Group code | |
|-----------------------------|-------------|---|---|-----|---|----|---------------|--|
| Theory | | | | | | | | |
| 1 | U15ENG201AR | Technical English –II | | 0 | 2 | 3 | HS | |
| 2 | U15MAT202AR | Mathematics – II 3 2 0 | | 0 | 4 | BS | | |
| 3 | U15PHY203FR | Physics For Mechatronics Engineering 3 | | 0 | 0 | 3 | BS | |
| 4 | U15CHE205ER | Chemistry For Mechatronics Engineering 3 0 | | 0 | 0 | 3 | BS | |
| 5 | U15MEA206R | Basic Mechanical and Electrical Engineering | | 0 | 0 | 3 | ES | |
| 6 | U15GE207R | Engineering Mechanics | | 2 | 0 | 3 | ES | |
| Practical | | | | | | | | |
| 7 | U15PCL208AR | Physics and Chemistry Laboratory – II [#] | 0 | 0 | 2 | 1 | BS | |
| 8 | U15MEC209R | Manufacturing Technology Laboratory – I | 0 | 0 | 2 | 1 | ES | |
| 9 | U15CDL210R | Computer Aided Drafting Laboratory | | 0 | 2 | 1 | ES | |
| Total Credits | | | | | | | | |
| Optional Language Elective* | | | | | | | | |
| 10 | U15OLE1201 | French | 0 | 0 0 | | | | |
| 11 | U15OLE1202 | German | | | 2 | 1 | HS | |
| 12 | U15OLE1203 | Japanese | | | | | | |

^{*}Students may opt for foreign languages viz., German/French/Japanese with additional one credit (over and above the CGPA calculation).

Approved by

| HOD-First Year Dr. M. Renuga | Chairperson BOS/ Mechatronics & HOD-Mechatronics Dr. P. Suresh | Member Secretary, Academic Council Dr. R. Shivakumar | Chairperson, Academic Council & Principal Dr. S.R.R. Senthilkumar |
|---------------------------------|---|--|---|
|---------------------------------|---|--|---|

^{*}Laboratory classes on alternate weeks for Physics and Chemistry. The lab examination will be conducted separately for 50 marks each with 2 hours duration.

U15ENG201AR - TECHNICAL ENGLISH II

L T P C M 2 0 2 3 100

Course Outcomes

At the end of the course, the students will be able to,

- 1. use grammatical components effectively in both written and spoken communication
- 2. develop speaking skills for self introduction, delivering speeches and technical presentation.
- 3. speak effectively in real time and business situations
- 4. write emails, formal letters and descriptions of graphics
- 5. develop skills for writing reports and proposals

UNIT I - FOCUS ON LANGUAGE

- Cause and effect expressions
- Concord
- · If conditionals
- Articles
- Pronouns
- Adverbs
- · Grammatical structures

UNIT II - SPEAKING-I

- Self introduction, personal information, name, home background, study details, area of interest, hobbies, strengths and weaknesses, projects and paper presentations, likes and dislikes in food, travel, clothes, special features of home town.
- Welcome address, vote of thanks, special address on specific topics.

UNIT III - SPEAKING - II

 Mini presentation in small groups of two or three regarding, office arrangements, facilities, office functions, sales, purchases, training recruitment, advertising, applying for financial assistance, applying for a job, team work, discussion, presentation • Situational role play between examiner and candidate, teacher and student, customer and sales manager, hotel manager and organiser, team leader and team member, bank manager and candidate, interviewer and applicant, car driver and client, industrialist and candidate, receptionist and appointment seeker, new employee and manager, employee and employee, P.A. and manager, schedule for training, asking for directions, seeking help with office equipment, clarifying an error in the bill, job details, buying a product, selling a product, designing a website, cancelling and fixing appointments, hotel accommodation, training facilities, dress code, conference facilities.

UNIT IV - WRITING - I

- Email, fixing an appointment, Cancelling appointments, conference details, hotel accommodation, order for equipment, training programme details, paper submission for seminars and conferences
- Letter Writing, Business communication, quotations, placing orders, complaints, replies to queries from business customers, inviting dignitaries, accepting and declining invitations
- Resume / CV
- Transcoding: Flow Chart, Pie Chart, Graph, Bar Chart, Tabular Column.

UNIT V - WRITING -II

- Technical report writing, feasibility reports, accident reports, survey reports
- General purpose writing specifications of equipment, description of an object, National and International issues, answering general questions with special emphasis on seeking opinions
- Technical Writing: recommendations, checklists, instructions, note making and memo
- Proposal: establishing a lab, introducing a subject in the curriculum, training programme for students

Total: 45 Hours

Speaking test will be conducted for 20 marks externally and evaluated along with Technical English –II in the End Semester Valuation.

TEXT BOOK

Technical English – I & II, Dr. M. Renuga, et al. Sonaversity, Sona College of Technology, Salem, Revised edition, 2016.

EXTENSIVE READING

- 1. Who Moved my Cheese? Spencer Johnson-G. P. Putnam's Sons
- 2. "Discover the Diamond in You" Arindam Chaudhuri Vikas Publishing House Pvt. Ltd.

REFERENCE BOOKS

- 1. Norman Whitby, Business Benchmark Pre-Intermediate to Intermediate, Students Book, Cambridge University Press, 2006.
- 2. A Course in Communication Skills, P. Kiranmai Dutt, Geetha Rajeevan, C. L. N. Prakash, published by Cambridge University Press India Pvt. Ltd.

U15MAT202AR - MATHEMATICS II

(Common to Civil, Mech, Mechatronics, EEE, IT and FT Branches)

L T P C M 3 2 0 4 100

Course Outcomes

At the end of the course, the students will be able to.

- 1. explain the different types of ordinary differential equations and describe the various methods to solve ordinary differential equations.
- 2. define and explain the vector functions, operators and discuss the methods of solving line, surface and volume integrals.
- 3. state the special features of function of a complex variable, properties and discuss the problems involving conformal mapping.
- 4. describe the power series expansion of a complex function and the procedures of evaluating the complex integral.
- 5. define laplace transform, its inverse, properties and solve an ordinary differential equation using laplace transform.

UNIT I – ORDINARY DIFFERENTIAL EQUATIONS 9+6

Linear higher order ordinary differential equations with constant coefficients – Cauchy's and Legendre's homogeneous linear ordinary differential equations – method of variation of parameters.

UNIT II - VECTOR CALCULUS

9+6

Vector differentiation: Scalar and vector valued functions, gradient, directional derivative, divergence and curl, scalar potential.

Vector integration: Line, surface and volume integrals, statement of Green's, Stoke's and Gauss divergence theorems, simple applications involving squares, rectangles, cubes and rectangular parallelepiped.

UNIT III - ANALYTIC FUNCTIONS

9+6

Function of a complex variable, analytic function, necessary conditions and sufficient conditions (excluding proof), properties of an analytic function, harmonic conjugate, construction of an analytic function by Milne's Thomson method, conformal mapping: w = z + c, cz, 1/z and bilinear transformation.

UNIT IV - COMPLEX INTEGRATION

9+6

Statement of Cauchy's integral theorem and Cauchy's integral formula, simple applications, Taylor's and Laurent's expansions, singular points, residues, statement of Cauchy's residue theorem, evaluation of contour integration over unit circle and semi circle (excluding poles on real axis).

UNIT V - LAPLACE TRANSFORM

9+6

Laplace transform: conditions for existence, transform of elementary functions, basic properties, transform of derivatives and integrals, transform of unit step function and impulse function, transform of periodic functions

Inverse Laplace transform: standard results – statement of convolution theorem and its applications, initial and final value theorems, solution of linear second order ordinary differential equations with constant coefficients using Laplace transformation.

Total: 75 Hours

TEXT BOOKS

- 1. B. S. Grewal, "Higher Engineering Mathematics", Khanna Publishers, New Delhi, 43rd Edition, 2014.
- 2. T. Veerarajan, "Engineering Mathematics" (I Year), Tata McGraw Hill, 4th Edition, 2011.

REFERENCE BOOKS

- 1. P. Kandasamy, K. Thilagavathy and K. Gunavathy, "Engineering Mathematics", (for first Year), S. Chand and Co., Ltd., Revised Edition 2011.
- 2. E. Kreyszig., "Advanced Engineering Mathematics", John Wiley and Sons (Wiley Student Edition), 10th Edition, 2011.
- S.Karthikeyan, R. Rajeswari, P. Senthilvadivu and R.Shivakumar, "Vector Calculus and Complex Analysis", Sonaversity, Revised Edition, 2017.
- 4. N. P. Bali, M. Goyal, "Engineering Mathematics", University Science Press, New Delhi, 9th Edition, 2011.

U15PHY203FR - PHYSICS FOR MECHATRONICS ENGINEERING

L T P C M 3 0 0 3 100

Course Outcomes

At the end of the course, the students will be able to,

- 1. calculate electrical and thermal conductivity of conducting materials.
- 2. classify semiconductors and analyze the variation of Fermi level with temperature and examine the nature of charge carriers.
- 3. compare the types of magnetic materials and explain the applications of superconducting materials.
- 4. compare the different modes of heat transfer and apply the thermodynamic processes and laws to compute the efficiency of heat engines.
- 5. describe the significance of new engineering materials and their applications.

UNIT I - CONDUCTING MATERIALS

9

Conductors-classical free electron theory of metals-Electrical and thermal conductivity-Wiedemann-Franz law-Lorentz number-Drawbacks of classical theory-Quantum theory-band theory of solids(qualitative treatment only) - Fermi distribution function- Effect of temperature on Fermi Function-Density of energy states- Carrier concentration in metals - application of conducting materials in induction furnace.

UNIT II - SEMICONDUCTOR PHYSICS

9

Intrinsic semiconductors – Energy band diagram – direct and indirect band gap semiconductors - Carrier concentration in intrinsic semiconductors - Fermi level – Variation of Fermi level with temperature – Electrical conductivity – Band gap determination – Extrinsic semiconductors – Carrier concentration in N-type and P-type semiconductors (Qualitative Treatment only) – Variation of Fermi level with temperature and impurity concentration – Compound semiconductors – Hall effect –Determination of Hall coefficient – Hall effect applications - application of semiconductors in strain measurements.

UNIT III - MAGNETIC AND SUPERCONDUCTING MATERIALS

9

Origin of magnetic moment – Bohr magneton – Dia, para and ferromagnetic materials – Domain theory – Hysteresis – Soft and hard magnetic materials – Ferrites – applications – Magnetic hard disc.

Superconductivity-Properties-Types of superconductor—BCS theory of superconductivity (Qualitative) - High Tc superconductors - Applications of superconductors: SQUID, cryotron, magnetic levitation in trains.

UNIT IV - HEAT AND THERMODYNAMICS

9

Thermal conductivity - Forbe's and Lee's disc methods- Radial and cylindrical flow of heat -Thermal conductivity of rubber and glass - Thermal insulation of buildings- Thermal insulating materials -Thermal equilibrium - Zeroth law of thermodynamics - Internal Energy - First law of thermodynamics - Indicator diagram - Isothermal process - Work done in an isothermal expansion - Adiabatic process - Work done in an adiabatic expansion - Reversible and irreversible processes - Second law of thermodynamics - Carnot engine - Efficiency of Carnot's cycle - Carnot's cycle as heat engine and refrigerator - Carnot's theorem - Comparative study of Ideal Otto and diesel engines and their efficiency (no derivation) -Entropy - temperature diagram of Carnot's cycle.

UNIT V - NEW ENGINEERING MATERIALS

9

Metallic glasses: Preparation - properties - applications

Shape memory alloys: Characteristics - properties of Ni-Ti alloy – application-advantages and disadvantages of SMA

Advanced Ceramics: Introduction – characteristics – structural ceramics

Nano science and Nanotechnology – significance of the nano scale - different types of nanostructures (Confinement Dimensions 0-D, 1-D, 2-D and 3-D) - Categories of nanomaterials - Fabrication of nanomaterials - Ball milling method and Chemical vapour deposition technique - Carbon nanotubes - Types of carbon nanotubes - CNT structure – properties and applications

Total: 45 Hours

TEXT BOOKS

- 1. B. K. Pandey and S. Chaturvedi, 'Engineering Physics', Cengage Learning India Pvt. Ltd., Delhi, 2012.
- 2. M. Arumugam, 'Materials Science' Anuradha Publications, Kumbakonam, 2006.

REFERENCE BOOKS

- 1. C. Shanthi et al., Physics for Mechatronics Engineering, Sonaversity, Sona College of Technology, Salem (Revised edition, 2017).
- 2. V. Rajendran and A. Marikani, 'Materials science' TMH Publications, New Delhi, 2004.
- 3. N. Subramaniam, Brijlal, 'Heat and Thermodynamics', S. Chand Group, New Delhi, 2007 (Unit II).
- 4. N. Subramaniam, Brijlal, 'Properties of Matter', S. Chand Group, New Delhi, 2007 (Unit I).

U15CHE205ER - CHEMISTRY FOR MECHATRONICS ENGINEERING

L T P C M 3 0 0 3 100

Course Outcomes

At the end of the course, the students will be able to,

- describe the chemistry of engineering materials and their industrial applications.
- discuss the chemistry of fuels and combustion.
- explain the industrial importance of phase rule and alloys.
- outline the principle and processes of metallurgy and powder metallurgy.
- describe the chemistry of organic electronic materials and electrochemical processes.

UNIT I – CHEMISTRY OF ENGINEERING MATERIALS

9

Refractories – classification – acidic, basic and neutral refractories – properties (refractoriness, refractoriness under load, dimensional stability, porosity, thermal spalling).

Abrasives – natural and synthetic abrasives – quartz, corundum, emery, garnet, diamond, silicon carbide and boron carbide.

Lubricants – mechanism of lubrication, liquid lubricants, - properties – (viscosity index, flash and fire points, cloud and pour points, oiliness) – solid lubricants – graphite and molybdenum sulphide.

Modern Composite Materials – Definition, constituents – FRP - types and engineering applications.

Polymers – Introduction and Nomenclature of Polymers – Types of Polymerization-Addition-Condensation and Copolymerization – Conducting polymers.

UNIT II - FUELS AND COMBUSTION

9

Fuels – calorific value – gross and net calorific values – coal – proximate and ultimate analyses – metallurgical coke – manufacture by Otto-Hoffmann method – Petroleum processing and fractions – cracking – types – synthetic petrol – Bergius and Fischer Tropsch processes - knocking – octane number and cetane number – power alcohol – biodiesel – Gaseous fuels – Water gas, producer gas, CNG and LPG, Combustion – flue gas analysis by Orsat's method.

9

Statement and explanation of terms involved – one component system – water system – condensed phase rule – construction of phase diagram by thermal analysis – simple eutectic systems (lead – silver system only).

Alloys: Introduction- Definition- Properties of alloys- Significance of alloying, Functions and effect of alloying elements - ferrous alloys – nichrome and stainless steel – heat treatment of steel, non-ferrous alloys – brass and bronze.

UNIT IV - METALLURGY

9

Metallurgy – extraction of metals from its ores – froth floatation, electromagnetic separation and chemical methods – refining of metals – liquation and electrolytic refining methods – metallurgy of iron and nickel - Powder metallurgy – principle – characteristics of metal powders – methods of producing metal powders (mechanical pulverization, atomization, chemical reduction, electrolytic process, decomposition) – mixing and blending – compacting – sintering – applications, advantages and limitations of powder metallurgy, Applications of Chemistry in mechanical engineering.

UNIT V – CHEMISTRY OF ORGANIC ELECTRONIC MATERIALS AND ELECTROCHEMICAL PROCESSES 9

Organo Electronics - Organic Semiconducting Materials - Working Principle and Advantages over Inorganic Semiconducting Materials - P-Type and N-Type Organic Semiconducting Materials - Pentacene Fullerenes- C-60 - Organic dielectric materials - definition and examples-Organic Light Emitting Diodes (Oleds) - Construction-Working Principle and Applications - Organic Transistors- Construction-Working Principle and Applications in Electronic Industries.

Electrochemical processes - Plating Techniques – Electro plating and electroless plating of nickel – Fabrication of PCBs – Electrochemical etching of copper from PCB.

Total: 45 Hours

TEXT BOOKS

- 1. P.C.Jain and Monica Jain, "Engineering Chemistry" Dhanpat Rai Pub, Co., New Delhi, 2010.
- 2. B. Sivasankar, "Engineering Chemistry", Tata McGraw-Hill Pub. Co. Ltd., New Delhi (2008).

REFERENCE BOOKS

- 1. T. Maruthavanan et al., "Chemistry For Mechatronics Engineering" Sonaver sity, Sona College of Technology, Salem, 2019 Edition.
- 2. Gowariker V.R., Viswanathan N.V. and Jayadev Sreedhar, "Polymer Science", New Age International P (Ltd.,), Chennai, 2006
- 3. B.K. Sharma, "Engineering Chemistry", Krishna Prakasan Media (P) Ltd., Meerut (2001).
- 4. N. Krishnamurthy, K. Jeyasubramanian and P. Vallinayagam, "Applied Chem istry", Tata McGraw-Hill Publishing Company Limited, New Delhi (1999).

U15MEA206R - BASIC MECHANICAL AND ELECTRICAL ENGINEERING

L T P C M 3 0 0 3 100

Course Outcomes

At the end of the course, the students will be able to,

- describe the essential features and working principles of conventional power plants and pumping system.
- 2. state the working principle of petrol and diesel ic engines
- 3. explain the working of refrigerators and air conditioning systems.
- 4. state the fundamental laws of electrical circuits and explain the basic principles related to dc and ac electrical circuits
- 5. explain the constructional features and principles of operation of dc and ac motors

UNIT I – POWER PLANT ENGINEERING

9

Introduction, Classification of Power Plant -Working principle of steam, Gas, Diesel, Hydro -Electric and Nuclear Power plants –Merits and Demerits -Pumps and turbines – working principle of Reciprocating pumps (single acting and double acting) –Centrifugal Pump. Concept of IoT in Power plant.

UNIT II – INTERNAL COMBUSTION ENGINES

9

Internal combustion engines as automobile power plant –Working principle of Petrol and Diesel Engines Four stroke and two stroke cycles Comparison of four stroke and two stroke engines. Concept of IoT in automobile.

UNIT III – REFRIGERATION AND AIR CONDITIONING 9

Terminology of refrigeration and air conditioning; Principle of vapour compression and absorption system-Layout of typical domestic refrigerator -window and split type room air conditioner. Concept of IoT in room air conditioning system.

UNIT III - DC AND AC CIRCUITS

9

DC Circuits: Ohm's law, Kirchhoff's laws, Series and Parallel circuits, Star – Delta transformation – Simple Problems.

AC Circuits: AC waveform standard terminologies, Single phase RL, RC, RLC series circuits – Simple Problems. Introduction to three phase circuits.

UNIT IV - DC AND AC MOTORS

9

DC Generator: construction of DC Machine –working principle of DC Generator – EMF equation – Types of DC Generator –DC Motor: Working principle of DC Motor –Types of DC Motor – Transformer: Working principle of Transformer – EMF equation –Transformation ratio.

Total: 45 Hours

TEXT BOOKS

- 1. Shanmugam G and Palanichamy M S, "Basic Civil and Mechanical Engineering", Tata McGraw Hill Publishing Co., New Delhi, (1996).
- 2. Ramamrutham. S, "Basic Civil Engineering", Dhanpat Rai Publishing Co. (P) Ltd. (1999).
- 3. V.K. Mehta and Rohit Mehta, "Principles of Electrical Engineering and Electronics", S. Chand publishers, 2011.
- 4. S.K. Bhattacharya, "Basic Electrical and Electronics Engineering", Pearson publishers, 2012.

REFERENCE BOOKS

- 1. S.R.J. Shantha Kumar, "Basic Mechanical Engineering", 2nd Edition, Hi-Tech Publications, 2000.
- P.K.Nag, "Power Plant Engineering" 3rd Edition, Tata McGraw-Hill Education, 2002.
- Sudhakar A and Shyam Mohan SP, Circuits and Network Analysis and Synthesis". Tata Mc Graw Hill 2007.
- 4. D.P. Kothari and I.J. Nagrath, 'Electric Machines', Tata McGraw Hill 2002.
- A.K. Sawhney, "A Course in Electrical & Electronic Measurements & Instrumentation", Dhanpat Rai and Co 2004.
- 6. B.L. Theraja, "Fundamentals of Electrical Engineering and Electronics", S. Chand publishers, 2007.

U15GE207R- ENGINEERING MECHANICS

L T P C M 2 2 0 3 100

Course Outcomes

At the end of the course, the students will be able to,

- the student should be able to understand the vectorial and scalar representation
 of forces and moments, static equilibrium of particles and rigid bodies both in two
 dimensions and also in three dimensions.
- 2. further, they should understand the principle of work and energy. he should be able to comprehend the effect of friction on equilibrium.
- 3. they should be able to understand the laws of motion, the kinematics of motion and the interrelationship.
- 4. they should also be able to write the dynamic equilibrium equation. all these should be achieved both conceptually and through solved examples.

UNIT I BASICS & STATICS OF PARTICLES

12

Introduction – Units and Dimensions – Laws of Mechanics – Lame's theorem, Parallelogram and triangular Law of forces – Vectors – Vectorial representation of forces and moments – Coplanar Forces – Resolution and Composition of forces – Equilibrium of a particle

Forces in space – Equilibrium of a particle in space – Equivalent systems of forces – Principle of transmissibility – Single equivalent force.

UNIT II EQUILIBRIUM OF RIGID BODIES IN 2 DIMENSIONS 12

Free body diagram – Types of supports and their reactions – requirements of stable equilibrium – Moments and Couples – Moment of a force about a point – Varignon's theorem – Equilibrium of Rigid bodies in two dimensions

UNIT III FRICTION

12

Frictional force – Laws of Coulomb friction – Angle of friction – cone of friction – Equilibrium of bodies on inclined plane – Ladder friction - Wedge Friction – Belt friction – Screw Jack - Self locking

Determination of Areas and Volumes – First moment of area and the Centroid of sections – Rectangle, circle, triangle from integration – T section, I section, Hollow section by using standard formula

Second and product moments of plane area – Rectangle, triangle, circle from integration – T section, I section by using standard formula – Parallel axis theorem and perpendicular axis theorem – Polar moment of inertia – Principal moments of inertia of plane areas – Principal axes of inertia – Mass moment of inertia of cylinder

UNIT V DYNAMICS OF PARTICLES

12

Displacements, Velocity and acceleration, their relationship – Rectilinear and Curvilinear motion – Newton's law – Work Energy Equation of particles – Impulse and Momentum – Impact of elastic bodies.

Total: 60 Hours

TEXT BOOKS

- 1. Engineering mechanics by sonaversity III edition, by 2013.
- 2. Beer, F.P and Johnson Jr. E.R. "Vector Mechanics for Engineers", Vol. 1 Statics and Vol. Dynamics, McGraw-Hill International Edition, (1997).

REFERENCE BOOKS

- 1. Rajasekaran, S, Sankarasubramanian, G., "Fundamentals of Engineering Mechanics", Vikas Publishing House Pvt. Ltd., (2000).
- 2. Hibbeller, R.C., "Engineering Mechanics", Vol. 1 Statics, Vol. 2 Dynamics, Pearson Education Asia Pvt. Ltd., (2000).
- 3. Palanichamy, M.S., Nagam, S., "Engineering Mechanics Statics & Dynamics", Tata McGraw–Hill, (2001).
- 4. MeriamJ.L,KraigeL.G,"Engineering Mechanics-Statics" 6th Edition, Wiley, 2010.
- Irving H. Shames, "Engineering Mechanics Statics and Dynamics", IV Edition
 Pearson Education Asia Pvt. Ltd., (2003).
- 6. Ashok Gupta, "Interactive Engineering Mechanics Statics A Virtual Tutor (CDROM)", Pearson Education Asia Pvt., Ltd., (2002).

U15PCL208AR - PHYSICS AND CHEMISTRY LABORATORY II

L T P C M 0 0 2 1 100

Course Outcomes

At the end of the course, the students will be able to,

- 1. apply the principles of optics, electricity and elasticity to determine the engineering properties of materials.
- evaluate the amount of iron content in the given sample using spectrophotometry, analyze the amount of chloride in a domestic water sample and analyse the quality of brass by estimating copper.
- 3. determine the resistivity of the given fuse wire used for house hold applications and determine the dissolved oxygen in two different water samples collected from the students residential areas.

LIST OF EXPERIMENTS (PHYSICS PART)

- 1. Determination of rigidity modulus of the material using torsion pendulum.
- 2. Determination of specific resistance of a given wire using Carey-Foster's bridge.
- 3. Determination of Young's modulus of the material by non-uniform bending method.
- 4. Determination of wavelength of the spectral lines in the mercury spectrum using a spectrometer.
- 5. Determination of band gap of a semiconductor diode.
- Determination of coefficient of viscosity of the given liquid using Poiseuille's method

(Any five experiments may be conducted from the above list)

LIST OF EXPERIMENTS (CHEMISTRY PART)

- 1. Determination of molecular weight of Polyvinyl alcohol using Ostwald Viscometer.
- 2. Estimation of copper in brass solution by EDTA method.
- 3. Determination of Calcium Oxide (CaO) in Cement.
- 4. Estimation of chromium in waste water.
- 5. Determination of dissolved oxygen in water by Winkler's method.
- 6. Estimation of Iron content in water by Spectrophotometric method.

(Any five experiments may be conducted from the above list)

Total: 30 Hours

U15MEC209R - MANUFACTURING TECHNOLOGY LABORATORY - I

L T P C M 0 0 2 1 100

Course Outcomes

At the end of the course, the students will be able to,

CO1: to gain experience on working of general purpose in machine tools and on various manufacturing processes.

CO2: to gain knowledge and experience on working in welding machine.

CO3: to gain knowledge on foundry.

LIST OF EXPERIMENTS

Lathe

- 1. Simple facing & turning.
- 2. Step turning model.
- 3. Taper turning model.
- 4. Thread cutting operation.
- 5. Knurling and grooving.
- 6. Drilling, boring and chamfering.
- 7. Exercise on radial drilling machine (Drilling, Tapping, Reaming and Counter Sink).
- 8. Eccentric turning model Demonstration.

Welding

- 9. Butt Joints by using Arc welding
- 10. Lap Joints by using Arc welding
- 11. Tee Joints by using Arc welding
- 12. Gas welding Demonstration

Foundry

 $13.\ Foundry-Demonstration$

List of Equipments

| 1. Centre Lathe with accessories | - | 15 Nos |
|------------------------------------|---|--------|
| 2. Pillar type drilling machine | - | 01 No |
| 3. Table top drilling machine | - | 01 No |
| 4. Radial drilling machine | - | 01 No |
| 5. Moulding table | - | 05 Nos |
| 6. Moulding boxes, tools, patterns | - | 05 Nos |
| 7. Injection Moulding Machine | - | 01 No |
| 8. Arc Welding Unit | - | 02 Nos |
| 9. Gas Welding Unit | - | 01 No |

U15CDL210R - COMPUTER AIDED DRAFTING LABORATORY

L T P C M
0 0 2 1 100

1. General Introduction:

Introduction to CAD Modeling Software – Industrial Applications – Parametric & Feature based modeling. Comparison - CAD models with Proto types. Practice - Sketch – Part Model – Detailing.

Introduction about ANALYSIS.

2. Preparation of Standard Solid Primitives

Create 3D- simple solids- Prism, Pyramid, Cylinder and Cone – Front view-Top view-and side view Create 3D simple models- V-block, Spur Gear, Bolt and Nut etc.).

3. Preparation of Orthographic Drawing and Sectioning:

Ortho graphic view and Cut section of standard Machine Elements.,

4. Material Properties and Rendering

Applying different materials for Machine Components-Steel –Aluminum-Copper-Brass-Silver-Wood

Plastic-Ceramic-. Concrete etc., Preparing Final CAD outputs with rendering features.

5. Geometric Tolerance and Dimension

Detailing with Fits, Limits and Tolerance.

Introduction to GD&T – Industrial Drawing practice- Machining symbols, Welding Symbols etc.,

Note: Laboratory Practicing CAD Modeling Software: Solidworks 2012.

Sona College of Technology, Salem

(An Autonomous Institution)

Courses of Study for B.E/B.Tech. Semester III under Regulations 2015R (CBCS)

Branch: Mechatronics Engineering

| S.No | Course Code | Course Title | Lecture | Tutorial | Practical | Credit |
|------|-------------|--|---------|----------|-------------|--------|
| | | Theory | | | | |
| 1 | U15MAT301DR | Transforms and Boundary Value Problems | 3 | 2 | 0 | 4 |
| 2 | U15MC301R | Fluid Mechanics and Machinery | 3 | 0 | 0 | 3 |
| 3 | U15MC302 | Strength of Materials | 3 | 0 | 0 | 3 |
| 4 | U15MC303R | Manufacturing Technology | 3 | 0 | 0 | 3 |
| 5 | U15MC304R | Electrical Machines and Drives | 3 | 0 | 0 | 3 |
| 6 | U15MC305R | Electron Devices and Circuits | 3 | 0 | 0 | 3 |
| | | Practical | | | | |
| 7 | U15MC306R | Fluid Mechanics and Strength of Materials Laboratory | 0 | 0 | 4 | 2 |
| 8 | U15MC307R | Electron Devices and Circuits Laboratory | 0 | 0 | 2 | 1 |
| 9 | U15MC308R | Electrical Machines and Drives Laboratory | 0 | 0 | 4 | 2 |
| 10 | U15GE301R | Soft Skill and Aptitude – I | 0 | 0 | 2 | 1 |
| | | | • | Tot | tal Credits | 25 |

Approved By

Chairman, Mechatronics Engineernig BoS Dr.P.Suresh Member Secretary, Academic Council Dr.R.Shivakumar

Chairperson, Academic Council & Principal Dr.S.R.R.Senthil Kumar

Copy to:-

HOD/Mechatronics Engineering, Third Semester BE MCT Students and Staff, COE

| U15 | МАТ | 301DR | | TRA | NSFO | _ | AND B | | DARY | = | L | T | Р | С | |
|-------|-----------------|--|---------|--------|---------|---------|---------|---------|-------|----------|--------|-------|-------|--------|------|
| | | | | | | Р | ROBL | | 3 | 2 | 0 | 4 | | | |
| Cour | Course Outcomes | | | | | | | | | | | | | | |
| After | suc | cessful | com | oletio | n of th | nis co | urse, t | the st | udent | s sho | uld be | able | to | | |
| CO | | escribe f Fourie | _ | | | | | • | • | • | | | | | |
| CO | р | Describe the complex (or infinite) Fourier transform pairs, sine and cosine transform pairs and their properties and state convolution theorem and solve the problems elated to Parseval's identity. | | | | | | | | | | | | | |
| CO | d | orm the ifferent near pa | ial equ | ations | of cer | tain ty | ype, so | olve ho | moge | neous | and no | n hoi | moge | eneo | |
| CO | | lassify roblem | | | | | | | • | | | | • | valu | е |
| CO | | olve the | | • | • | | | | • | | • | | and p | oartia | al |
| Pre-ı | requ | isite | | | | | | | | | | | | | |
| | 1. | . Vector Calculus, Differential Equations and Complex Analysis | | | | | | | | | | | | | |
| | | | | | C | O/PO | , PSO | Марр | oing | | | | | | |
| | | (3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak | | | | | | | | | | | | | |
| COs | | Pro | gramr | ne Ou | tcome | s (POs |) and | Progra | mme | Specifi | c Outc | ome (| (PSO | s) | |
| 203 | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | PO10 | PO11 | PO1 | 2 P | SO 1 | PSO2 |
| CO1 | 3 | 3 | 2 | 3 | | | | | | | 3 | 2 | | 3 | 3 |

| COs | Programme Outcomes (POs) and Programme Specific Outcome (PSOs) | | | | | | | | | | | | | |
|---------------------------|--|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|-------|------|
| COS | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | PO10 | PO11 | PO12 | PSO 1 | PSO2 |
| CO1 | 3 | 3 | 2 | 3 | | | | | | | 3 | 2 | 3 | 3 |
| CO2 | 3 | 3 | 2 | 3 | | | | | | | 3 | 2 | 3 | 3 |
| CO3 | 3 | 3 | 2 | 3 | | | | | | | 3 | 2 | 3 | 3 |
| CO4 | 3 | 3 | 2 | 3 | | | | | | | 3 | 2 | 3 | 3 |
| CO5 | 3 | 3 | 2 | 3 | | | | | | | 3 | 2 | 3 | 3 |
| Course Assessment methods | | | | | | | | | | | | | | |

| | Direct | Indirect |
|-----------------------|-------------------------------|-------------------|
| Internal test I (6) | Seminar (5) | Course end survey |
| Internal test II (6) | Moodle (7) | |
| Internal test III (6) | Attendance (5) | |
| Assignment (5) | End semester Examination (60) | |

Unit 01:Fourier Series 09+6 Hours

General Fourier series - Dirichlet's conditions, odd and even functions, half range sine and cosine series, complex form of Fourier series, Parseval's identify, harmonic analysis.

Unit 02:Fourier Transforms 09+6 Hours

Fourier integral theorem (without proof) - Fourier transform pair, sine and cosine transforms, properties, transforms of simple functions, convolution theorem, parseval's identity.

Unit 03:Partial Differential Equations 09+6 Hours

Formation of partial differential equations, Lagrange's linear equation, solutions of standard types of first order partial differential equations, linear partial differential equations of second and higher order with constant coefficients

Unit 04:Boundary value problems

09+6 Hours

Classifications of quasi linear PDE, Solutions of one dimensional wave equation in Cartesian co-ordinates; steady state solution of two dimensional equation of heat conduction in Cartesian co-ordinates (Insulated edges excluded)

Unit 05:Numerical solutions to boundary value problems in 09+6 Hours **Ordinary and Partial Differential Equations**

Second order ordinary differential equation, finite difference solution of one dimensional heat equation by explicit and implicit methods, one dimensional wave equation and two dimensional Laplace and Poisson equations

Tutorial: 30 Hrs Theory: 45Hrs **Total Hours: 75 Hrs**

Text Books

- 1. Transforms and Partial Differential Equations III" by Sonaversity 2011
- 2. Ponnusamy S., "Numerical Methods", 1st Edition, Sona Varsity, 2008

Extensive Reading

REFERENCES

- 1. Bali N.P., and Manish Goyal, "A Textbook of Engineering Mathematics", 7th Edition, Laxmi Publications (P) Ltd., 2007
- 2. Ramana B.V., "Higher Engineering Mathematics", Tata Mc-GrawHill Publishing Company limited, New Delhi 2007
- 3. Glyn James, "Advanced Modern Engineering Mathematics", 3rd Edition, Pearson Education 2007
- 4. Erwin Kreysizig, "Advanced Engineering Mathematics", 8th edition, Wiley India 2007
- 5. Grewal B.S., "Higher Engineering Mathematics", 40th Edition, Khanna Publishers, Delhi 2007.

| 1115M | C301R | FLUID MECHANICS AND MACHINERY | L | Т | Р | С | | | | |
|----------|---|--|--------|------|-------|---|--|--|--|--|
| OISM | CJOIR | | 3 | | | | | | | |
| Course C | Outcomes | | | • | | | | | | |
| After su | ccessful co | ompletion of this course, the students should be able to | | | | | | | | |
| CO1: | Apply ma | thematical knowledge to predict the properties and characteri | stics | of a | fluid | | | | | |
| CO2: | Analyze the fluid flow problems using continuity equation and Bernoulli's equation with their applications. | | | | | | | | | |
| CO3: | _ | sh laminar and turbulent flow through circular pipes and descrice of dimensional analysis by using Buckingham's Π theorem. | ibe th | ne | | | | | | |
| CO4: | Discuss the theory of turbo machines and their classification and analyze the performances of the hydraulic turbines. | | | | | | | | | |
| CO5: | Explain the working principle of centrifugal pumps & reciprocating pumps and analyze their performances. | | | | | | | | | |

Pre-requisite

- 1. Engineering Physics and
- 2. Transforms & Partial differential equations

CO/PO, PSO Mapping

(3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak

| COs | | Programme Outcomes (POs) and Programme Specific Outcome (PSOs) | | | | | | | | | | | | |
|-----|-----|--|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|
| COS | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | PO10 | PO11 | PO12 | PSO1 | PSO2 |
| CO1 | 3 | 3 | 2 | 2 | 1 | 1 | | | | 1 | | | 3 | 2 |
| CO2 | 3 | 3 | 2 | 2 | | 2 | | | | 1 | | | 3 | 2 |
| CO3 | 3 | 3 | 3 | 2 | 1 | 1 | | | | 1 | | | 3 | 2 |
| CO4 | 3 | 3 | 3 | 2 | | 2 | 1 | 1 | | 1 | | 1 | 3 | 2 |
| CO5 | 3 | 3 | 3 | 2 | | 2 | 1 | 1 | | 1 | | 1 | 3 | 2 |

Course Assessment methods

| | Indirect | |
|-----------------------|-------------------------------|-------------------|
| Internal test I (6) | Seminar (5) | Course end survey |
| Internal test II (6) | Moodle (7) | |
| Internal test III (6) | Attendance (5) | |
| Assignment (5) | End semester Examination (60) | |

Unit 01:FLUID PROPERTIES AND FLOW CHARACTERISTICS

09 Hours

Units & Dimensions. Properties of fluids – mass density, specific weight, specific volume, viscosity, capillarity and surface tension, compressibility, vapor pressure and cavitation. Types of fluid flow-application of continuity equation, Euler's equation along streamline, Bernoulli's equation and its applications- Orifice meter, Venturi meter.

Unit 02:FLOW THROUGH PIPES

09 Hours

Laminar flow though circular pipes [Hagen-Poiseuille equation]. Boundary layer concept- Turbulent flow though circular pipes- Darcy Weisbach equation –friction factor- Moody diagram. Flow through pipes: Energy losses, pipes in series and parallel. Power transmission through pipes.

Unit 03: DIMENSIONAL ANALYSIS

09 Hours

Need for dimensional analysis – methods of dimensional analysis – Buckingham's Π theorem, Dimensionless parameters- application of dimensionless parameters. Models and Similitude.

Unit 04:HYDRAULIC TURBINES

09 Hours

Turbines: definition and classification – impulse and reaction. Construction of velocity diagrams. Pelton turbine - Francis turbine - Kaplan turbine - working principles - velocity triangles - work done - specific speed - efficiencies and performance calculations.

Unit 05:HYDRAULIC PUMPS

09 Hours

Pumps: Definition and classifications. Centrifugal pump- working principle, velocity triangles, head and efficiencies, performance calculations. Reciprocating pump – classification, working principle-performance calculations, function of air vessel. Comparison of pumps. Rotary pumps working principles of gear and vane pumps

Theory: 45Hrs Tutorial: - Total Hours: 45 Hrs

Text Books

1. Bansal, R.K., Fluid Mechanics and Hydraulics Machines, (9th edition), Laxmi publications (P) Ltd, New Delhi, 2015

REFERENCES

- 1. Sukumar Pati., "Fluid Mechanics and Hydraulics Machines", Tata McGraw Hill publications (P) Ltd, New Delhi, 2012.
- 2. C.S.P.Ojha, R.Berndtsson, P.N.Chandramouli., Fluid Mechanics and Machinery, Oxford University Press, New Delhi, 2010.
- 3. Modi P.N. and Seth, S.M. "Hydraulics and Fluid Mechanics", Standard Book House, New Delhi 2004
- 4. Streeter, V. L. and Wylie E. B., "Fluid Mechanics", McGraw Hill Publishing Co. 2010
- 5. Kumar K. L., "Engineering Fluid Mechanics", Eurasia Publishing House(p) Ltd., New Delhi 2004
- 6. Ramamritham. S, Fluid Mechanics, Hydraulics and Fluid Machines, Dhanpat Rai & Sons, Delhi, 2011

| U15M | C302R STRENGTH OF MATERIALS | STRENGTH OF MATERIALS | | | | | | | |
|----------|--|-----------------------|--------|---|---|--|--|--|--|
| | | | | | | | | | |
| Course C | Outcomes | | | | | | | | |
| After su | ccessful completion of this course, the students s | hould be a | able t | 0 | | | | | |
| CO1: | Analyse the state of stresses and strains in engineering components as a result of different loading conditions in the machine members and structures. | | | | | | | | |
| CO2: | Investigate the effect of various loading combinations stresses, principal planes and maximum shear stress parts using Mohr's circle. | • | _ | • | • | | | | |
| CO3: | Applythe principles and equations, necessary tools to analyze structural members under axial loads, bending, shear, and torsion. | | | | | | | | |
| CO4: | Evaluate the material behaviour under pure torsion on circular shafts. | | | | | | | | |
| CO5: | Design the structural beams, columns, long mechanical members under compression | | | | | | | | |

Pre-requisite

1. Engineering Mechanics

and different loading condition.

CO/PO, PSO Mapping

(3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak

| COs | | Programme Outcomes (POs) and Programme Specific Outcome (PSOs) | | | | | | | | | | | | |
|-----|-----|--|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|
| COS | PO1 | PO2 | PO3 | PO4 | PO5 | P06 | PO7 | PO8 | P09 | PO10 | PO11 | PO12 | PSO1 | PSO2 |
| CO1 | 3 | 3 | 3 | 2 | 1 | 2 | | | | 1 | | | 3 | 2 |
| CO2 | 3 | 3 | 3 | 2 | 1 | 2 | | | | 1 | | | 3 | 2 |
| CO3 | 3 | 3 | 3 | 2 | 1 | 2 | 1 | 1 | | 1 | | 1 | 3 | 2 |
| CO4 | 3 | 3 | 3 | 2 | 1 | 2 | 1 | | | 1 | | | 3 | 2 |
| CO5 | 3 | 3 | 3 | 2 | 1 | 2 | 1 | 1 | | 1 | | 1 | 3 | 2 |

Course Assessment methods

| | Direct | Indirect |
|-----------------------|-------------------------------|-------------------|
| Internal test I (6) | Seminar (5) | Course end survey |
| Internal test II (6) | Moodle (7) | |
| Internal test III (6) | Attendance (5) | |
| Assignment (5) | End semester Examination (60) | |

Unit 01:Stress, Strain and Deformation of Solids

09 Hours

Simple stress and strain – Stresses and strains due to axial force - Mechanical properties of materials – Stress-strain curve –- Hooke's law - Factor of safety – Stepped shafts – Uniformly varying sections – Stresses in composite sections - Temperature stresses – Poisson's ratio - shear modulus, bulk modulus, relationship between elastic constants.

Unit 02:Analysis of Stresses in Two Dimensions

09 Hours

State of stresses at a point – Normal and tangential stresses on inclined planes - Principal planes and stresses – Plane of maximum shear stress - Mohr's circle for biaxial stresses – Hoop and longitudinal stresses in thin cylinders and shells – under internal pressure – deformation of thin cylinders and shells.

Unit 03: Beams - Loads and Stresses

09 Hours

Beams – types of supports – simple and fixed, types of load – concentrated, uniformly distributed, varying distributed load, combination of above loading – relationship between bending moment and shear force – bending moment, shear force diagram for simply supported, cantilever and over hanging beams – Point of contra flexure. Introduction to Theory of simple bending.

Unit 04:Torsion in Shafts and springs

09 Hours

Analysis of torsion of circular bars – Shear stress distribution – Bars of Solid and hollow circular section – Stepped shaft – Twist and torsion stiffness – Compound shafts – Springs: Classification – Leaf springs, closed coil helical springs – Application of various springs – Maximum shear stress in spring – Deflection of helical coil springs under axial loads.

Unit 05:columnsand Deflection of Beams

09 Hours

Columns: Buckling of long columns due to axial load - Equivalent length of a column - Euler's and Rankine's formulae for columns of different end conditions - Slenderness ratio Deflection of beams - double integration method - Macaulay's method - slope and deflection using moment area method.

| Theory: 45Hrs | Tutorial: - | Total Hours: 45 Hrs |
|---------------|-------------|---------------------|
| | | |

Text Books

- 1. R K Bansal, "A text book of Strength of Materials", Lakshmi Publications (P) Limited, New Delhi, 2007.
- 2. R K Rajput, "Strength of Materials", S Chand & Co., New Delhi, 2006.

REFERENCES

- 3. Nash W.A, "Theory and problems in Strength of Materials", Schaum Outline Series, McGraw-Hill Book Co, New York, 1995.
- 4. Singh D.K "Mechanics of Solids" Pearson Education 2002.
- 5. Ryder G.H, "Strength of Materials", Macmillan India Ltd., Third Edition, 2002.
- 6. Popov E.P, "Engineering Mechanics of Solids", Prentice-Hall of India, New Delhi, 1997.

| U15MC303R | MANUFACTURING TECHNOLOGY | L | Т | Р | С |
|------------------------|--------------------------|----|---|---|---|
| | | 3 | 0 | 0 | 3 |
| Course Outcomes | | | | | |
| After successful co | able 1 | to | | | |

| After suc | ccessful completion of this course, the students should be able to |
|-----------|--|
| CO1: | Elaborate the sand casting, pattern materials and welding, different welding |
| | processes. |
| CO2: | Describe the various bulk deformation processes, different sheet metal operations and shaping of plastics using different moulding methods. |
| CO3: | Identify the cutting tool materials and its specific purpose and explain about lathe details, main dissimilarity of capstan and turret lathes. |
| CO4: | Illustrate the principle of reciprocating machine tools. |
| CO5: | Explain the working principle of milling and grinding processes. |

Pre-requisite

- 1.Engineering Physics I
- 2. Engineering practice laboratory

CO/PO, PSO Mapping

(3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak

| СО | Programme Outcomes (POs) and Programme Specific Outcome (PSOs) | | | | | | | | | | | | | |
|-----|--|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|
| s | PO1 | PO2 | PO3 | PO4 | PO5 | P06 | PO7 | PO8 | P09 | PO10 | PO11 | PO12 | PSO1 | PSO2 |
| CO1 | 3 | 3 | 3 | 1 | 1 | 2 | 1 | 1 | | 1 | | 1 | 3 | 2 |
| CO2 | 3 | 3 | 3 | 1 | 1 | 2 | 1 | 1 | | 1 | | 1 | 3 | 2 |
| CO3 | 3 | 3 | 3 | 2 | 1 | 2 | 1 | 1 | | 1 | | 1 | 3 | 2 |
| CO4 | 3 | 3 | 3 | 2 | 1 | 2 | 1 | 1 | | 1 | | 1 | 3 | 2 |
| CO5 | 3 | 3 | 3 | 2 | 1 | 2 | 1 | 1 | | 1 | | 1 | 3 | 2 |

Course Assessment methods Direct Internal test I (6) Seminar (5) Course end survey

Internal test II (6) Moodle (7) Internal test III (6) Attendance (5) Assignment (5) End semester Examination (60)

Unit 01:METAL CASTING AND METAL JOINING PROCESS

09 Hours

Indirect

Sand Casting- Moulding Tools- Types of Patterns- Pattern Materials- Moulding Sand-Properties- Melting Furnaces: Cupola, Crucible and Electric arc furnace- Special Casting Process: Shell, Investment Casting - Lost Wax Process- Gas welding- Arc welding -TIG welding- MIG welding-Resistant welding.

Unit 02:SHEET METAL AND PLASTIC COMPONENTS

09 Hours

Drawing Process: Wire drawing, Tube drawing, Metal Spinning, Rolling: Type of rolling mills-Extrusion: - Principles of Extrusion - Types - Hot and Cold extrusion, Sheet metal: Rubber pad forming- Explosive forming. Moulding of thermoplastics- injection moulding- blow moulding -Rotational moulding

Unit 03: CENTRE LATHE

09 Hours

Centre lathe: constructional features- various operations, tool and work holding devices- taper turning methods, thread cutting, special attachments. Special Purpose Lathe: Capstan and turret lathes – automats – single spindle- Swiss type- automatic screw type, multi spindle - geneva mechanism, Bar feed mechanism

Unit 04:SPECIAL MACHINE TOOLS

09 Hours

Construction, Types, Operations and mechanisms of Shaper, Planner and Slotter. Hole making: drilling –Reaming, Boring- Tapping- operations. Broaching machines: broach construction – push, pull, surface and continuous broaching machines.

Unit 05:MILLING AND GEAR PROCESS

09 Hours

Milling operations-types of milling cutter. Gear cutting – forming and generation principle and construction of gear milling, hobbing and gear shaping processes –finishing of gears. Grinding: types of grinding process- types of grinding wheel – Abrasives - cylindrical grinding, surface grinding, centreless grinding – honing, lapping and buffing.

| Theory: 45Hrs | Tutorial: - | Total Hours: 45 Hrs |
|---------------|-------------|---------------------|
|---------------|-------------|---------------------|

Text Books

- 1. Hajra Choudhury, "Elements of Workshop Technology, Vol. I and II", Media promoters Pvt Ltd., Mumbai, 2001.
- 2. Mikell P Groover, "Principles of Modern Manufacturing" Wiley India Pvt Ltd. 2014.

REFERENCES

- 1. B.S. Magendranparashar& R.K. Mittal, "Elements of Manufacturing Processes", Prentice Hall of India, 2003.
- 2. P.N. Rao, Manufacturing Technology", Tata McGraw-Hill Publishing Limited, II Edition, 2002
- 3. J.P .Kaushish "Manufacturing Processes" PHI Learning Private limited, second edition 2010.
- 4. P. C. Sharma, "A text book of production technology", S. Chand and company, IV Edition, 2003.
- 5. Begma, 'Manufacturing process", John Wilely& sons, VII Edition, 2005.
- 6. SeropeKalpajian, Steven R.Schmid, Manufacturing Engineering and Technology, Pearson Education, Inc. 2002 (Second Indian Reprint)
- 7. Beddoes. J and Bibby M.J. 'Principles of Metal Manufacturing Processes', Elsevier, 2006.
- 8. Rajput R.K, 'A text book of Manufacturing Technology', Lakshmi Publications, 2007.

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| U15MC | 304R | ELECTRICAL MACHINES AND DRIVES | L | | P | C |
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| Course O | utcomes | | | | | |
| After suc | cessful co | ompletion of this course, the students should be | able | to | | |
| CO1: | Explain t | he Construction, operation, characteristics of DC gene | rator | and | DC | |
| | motors. | | | | | |
| CO2: | Explain t | he Construction, Types, Operation and characteristics | of th | ree p | ohas | е |
| | Induction | n motor. | | | | |
| CO3: | Describe | about Types of electric drives, Heating and cooling cu | rves. | | | |
| CO4: | Discuss a | about Speed control of DC motor. | | | | |
| CO5: | Discuss 9 | Speed control of three phase induction motor. | | | | |
| Pre-requi | site | | | | | |
| 1. | Basic Elec | trical Engineering | | | | |

CO/PO, PSO Mapping

(3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak

| COs | | Programme Outcomes (POs) and Programme Specific Outcome (PSOs) | | | | | | | | | | | | | | |
|-----|-----|--|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|--|--|--|
| COS | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | PO10 | PO12 | PSO1 | PSO2 | | | |
| CO1 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | | 3 | 2 | | | |
| CO2 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | | 3 | 2 | | | |
| CO3 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | | 3 | 2 | | | |
| CO4 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | | | 3 | | | |
| CO5 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | | | 3 | | | |

Course Assessment methods

| | Direct | Indirect |
|-----------------------|-------------------------------|-------------------|
| Internal test I (6) | Seminar (5) | Course end survey |
| Internal test II (6) | Moodle (7) | |
| Internal test III (6) | Attendance (5) | |
| Assignment (5) | End semester Examination (60) | |

Unit 01:DC MACHINES

DC generator: Construction, principle of operation, EMF equation, OCC and external characteristic curves, and efficiency. **DC motors**: Construction, principle of operation, torque-speed characteristics & Starters.

Unit 02:AC MACHINES 09 Hours

AC Motors: three-phase induction motor: Construction, types, principle of operation, torque-slip characteristics, and starting methods, Introduction to synchronous motor.

Unit 03: ELECTRIC DRIVES INTRODUCTION

09 Hours

09 Hours

Basic Elements – Types of Electric Drives – factors influence the choice of electrical drives – Heating and cooling curves – Loading conditions and classes of duty – Selection of power rating for drive motors with regard to thermal overloading and Load variation factors.

Unit 04:Conventional and solid state speed control of d.c. drives 09 Hours

Speed control of DC series and shunt motors – Armature and field control, Ward-Leonard control system - Controlled rectifiers (1Phase Half wave & full wave) and DC choppers (Class A,B C,D & E).

Unit 05:CONVENTIONAL AND SOLID STATE SPEED CONTROL OF 09 Hours A.C. DRIVES

Speed control of three phase induction motor – Voltage control, voltage / frequency control, slip Power recovery scheme – Inverters, Cyclo converter and AC voltage regulators.

| Theory: 45Hrs Tutorial: - | Total Hours: 45 Hrs |
|---------------------------|---------------------|
|---------------------------|---------------------|

Text Books

- 1. D.P. Kothari and I.J. Nagrath, "Electric Machines", Tata McGraw-Hill, 2010.
- 2. G.K. Dubey, "Fundamentals of Electrical Drives", Narosa publications, 2010.

REFERENCES

- 1. Vedam Subramaniam, "Electric Drives (Concepts and Applications)", Tata McGraw-Hill, 2001.
- 2. Nagrath, I.J. and Kothari, D.P., "Electrical Machines", Tata McGraw-Hill, 1998.
- 3. Pillai, S.K., "A First Course on Electric Drives", Wiley Eastern Limited, 1998.
- 4. Singh, M.D. and Khanchandani, K.B., "Power Electronics", Tata McGraw-Hill, 1998.

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| | Evaluate the performance characteristics of multistage amplifiers and different types of oscillators. | | | | | | | | | | | | | | | |
| Pre-requisite | | | | | | | | | | | | | | | | |
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| CO/PO, PSO Mapping (3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak | | | | | | | | | | | | | | | | |
| | | | Programme Outcomes (POs) and Programme Specific Outcome (PSOs) | | | | | | | | | | | | | |
| COs | PO1 | PO2 | PO3 | PO4 | PO5 | P06 | PO7 | PO8 | P09 | - | PO12 | | | | | |
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| CO3 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | | | 3 | 2 | 2 | |
| CO4 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | | | 3 | 2 | 2 | |
| CO5 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | | | 3 | 2 | 2 | |
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| Inter | nal te | st III (| 6) | Atten | dance | (5) | | | | | | | | | | |
| Assig | nmen | t (5) | | End s | emeste | er Exa | minati | on (60 |) | | | | | | | |
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response – MOSFET small signal model – biasing – analysis of CS and source follower – gain and frequency response.

BJT small signal model – biasing – analysis of CE, CB, CC amplifiers – Gain and frequency

 $characteristic,\ CURRENT\ Equation,\ MOSFET\ -\ structure,\ operation\ and\ V-I\ characteristic\ -$

09 Hours

gant and frequency response.

types of MOSFET

Unit 03: AMPLIFIERS

Unit 04:MULTISTAGE AMPLIFIERS AND DIFFERENTIAL 09 Hours AMPLIFIER

BIMOS cascade amplifier, differential amplifier – common mode and difference mode analysis – tuned amplifiers – single tuned amplifiers – gain and frequency response.

Unit 05:FEEDBACK AMPLIFIERS AND OSCILLATORS

09 Hours

Advantages of negative feedback – voltage / current, series, shunt feedback – positive feedback – condition for oscillations, phase shift – Wien bridge, Hartley, colpitts and crystal oscillators

Theory: 45Hrs Tutorial: - Total Hours: 45 Hrs

Text Books

- 1. David A. Bell, Electronic devices and circuits, Prentice Hall of India, 2004.
- 2. Sedra Smith, Micro electronic circuits, Oxford University Press, 2004.

REFERENCES

- 1. Rashid, Micro electronic circuits, Thomson publications, 1999.
- 2. Floyd, Electron devices, pearson Asia 5th Edition, 2001.
- 3. Donald A Neamen, Electronic Circuit Analysis and Design, Tata McGrawHill, 3 rd Edition, 2003
- 4. Rashid, Micro electronic circuits, Thomson publications, 1999.

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| CO1 | 3 | 3 | 3 | 2 | 2 | | | 1 | 3 | 2 | 1 | 2 | 3 | 2 | |
| CO2 | 3 | 3 | 3 | 2 | 2 | | | 1 | 3 | 2 | 1 | 2 | 3 | 2 | |
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Total Hours: 60 Hrs

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| <u> </u> | 6. Verify the characteristics of IGBT.7. Design of Hartley and Colpitts oscillator. | | | | | | | | | | | | | | |
| 8. | | | | | • | | | oscilla | ator. | | | | | | |
| | 8. Design of RC phase shift and Wein bridge oscillator.9. Design of voltage and current series amplifier. | | | | | | | | | | | | | | |
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Total Hours: 30 Hrs

10. Design of negative feedback amplifier.

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| | 1.Ba | sic ele | ctrical | engin | eering | | | | | | | | | | |
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| CO2 | 3 | 3 | 3 | 3 | | | | | | 2 | | 3 | | 2 | |
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| List o | of Exp | erime | ents | | | | | | | | | | | | |
| 1. | Loa | d test o | on DC | Shunt | & DC | Serie | s moto | r. | | | | | | | |
| 2. | O.C | .C & Lc | ad cha | aracte | ristics | of DC | Shunt | and D | C Ser | ies gene | erator. | | | | |
| 3. | Spe | ed con | trol of | DC sh | unt m | otor (| Armatı | ıre, Fie | eld cor | ntrol). | | | | | |
| 4. | Loa | d test o | on sing | gle pha | se tra | nsfor | mer. | | | | | | | | |
| 5. | | | | | | | ransfor | | | | | | | | |
| 6. | | | | | | | & MMI | | | | | | | | |
| 7. | 7. V curves and inverted V curves of synchronous Motor. | | | | | | | | | | | | | | |
| 8. | | | | | | | cage In | | | | | | | | |
| | Speed control of three phase slip ring Induction Motor. Load test on single phase Induction Motor. | | | | | | | | | | | | | | |
| 10 |). Loa | test o | on sing | jle pha | se Ind | luctio | n Moto | r. | | | | | | | |

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Total Hours: 60 Hrs

11. Study of DC & AC Starters

| U15GE301R | | | SOFT SKILLS AND APTITUDE - I | | | | | | | L | Т | Р | С | | |
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| Course Outcomes | | | | | | | | | | | | | | | |
| After successful completion of this course, the students should be able to | | | | | | | | | | | | | | | |
| CO1: | Demonstrate capabilities in specific soft-skill areas using hands-on and/or case-study approaches. | | | | | | | | | case- | | | | | |
| CO2: | Solve problems of greater intricacy than those in BA-I and II in stated areas of quantitative aptitude and logical reasoning. | | | | | | | | | | | | | | |
| CO3: | Demonstrate higher than BA-I and II levels of verbal aptitude skills in English withregard to specific topics. | | | | | | | | | | | nglish | | | |
| | | | CO/PO, PSO Mapping | | | | | | | | | | | | |
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| COs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | PO10 | PO11 | PO12 | PS | 601 | PSO2 |
| CO1 | 1 | 1 | 1 | 1 | 1 | 2 | 2 | 3 | 3 | 3 | 3 | 3 | | 1 | 3 |
| CO2 | 3 | 3 | 3 | 2 | 2 | 2 | 2 | 3 | 1 | 1 | 1 | 3 | | 1 | 3 |
| CO3 | 1 | 2 | 2 | 2 | 3 | 2 | 3 | 3 | 3 | 3 | 2 | 3 | | 2 | 3 |

1. Soft Skills

Demonstrating soft-skill capabilities with reference to the following topics:

- a. Attitude building
- b. Dealing with criticism
- c. Innovation and creativity
- d. Problem solving and decision making
- e. Public speaking
- f. Group discussions

2. Quantitative Aptitude and Logical Reasoning

Solving problems with reference to following topics:

- a) Problems on ages
- b) Ratio and proportion
- c) Mixtures and Solutions
- d) Partnerships
- e) Averages
- f) Data Arrangement- Linear and Circular
- g) Data Interpretation-Bar/Pie
- h) Problems on cubes

3. Verbal Aptitude

Demonstrating English language skills with reference to the following topics:

- a. Verbal analogy
- b. Tenses
- c. Prepositions
- d. Reading comprehension
- e. Choosing correct / incorrect sentences
- f. Describing pictures

Sona College of Technology, Salem

(An Autonomous Institution)

Courses of Study for B.E/B.Tech. Semester IV under Regulations 2015R (CBCS)

Branch: Mechatronics Engineering

| S.No | Course Code | Course Title | Lecture | Tutorial | Practical | Credit | | |
|---------------|-------------|--|---------|----------|-----------|--------|--|--|
| | | Theory | | | | | | |
| 1 | U15MAT401DR | Statistics and Numerical Methods | 3 | 2 | 0 | 4 | | |
| 2 | U15CHE405R | Environmental science and Engineering | 3 | 0 | 0 | 3 | | |
| 3 | U15MC401R | Applied hydraulics and pneumatics | 3 | 0 | 0 | 3 | | |
| 4 | U15MC402R | Theory of machines | 3 | 0 | 0 | 3 | | |
| 5 | U15MC403R | Sensors and Instrumentation | 3 | 0 | 0 | 3 | | |
| 6 | U15MC404R | Microprocessors and microcontrollers | 3 | 0 | 0 | 3 | | |
| | | Practical | | | | | | |
| 7 | U15MC405R | Hydraulics and pneumatics Laboratory | 0 | 0 | 4 | 2 | | |
| 8 | U15MC406R | Sensors and Instrumentation Laboratory | 0 | 0 | 2 | 1 | | |
| 9 | U15MC407R | Microprocessors and Microcontroller Laboratory | 0 | 0 | 4 | 2 | | |
| 10 | U15GE401R | Soft Skills and Aptitude – II | 0 | 0 | 2 | 1 | | |
| Total Credits | | | | | | | | |

Approved By

Chairperson, Mechatronics Engineering, BoS Dr.P.Suresh Member Secretary, Academic Council Dr.R.Shivakumar Chairperson, Academic Council & Principal Dr.S.R.R.Senthil Kumar

Copy to:-

HOD/ Mechatronics Engineering, Fourth Semester BE MCT Students and Staff, COE

| | | | | CTAT | STATISTICS AND NUMEDICAL | | | | | | т | | Р | С |
|--|-------|--|-------|----------------------------------|--------------------------|--------|---------|---------|---------------|---------------|---------|--------|----------|--------|
| U15N | 1AT | 401DF | 2 | STATISTICS AND NUMERICAL METHODS | | | | | | | 2 | | 0 | 4 |
| Cours | e Oı | ıtcome | S | | | | | | | | | | | |
| After | succ | essful | com | pletior | of th | is cou | ırse, t | he stu | ıdent | s shou | ld be | able | to | |
| CO1 | : D | Define the sampling distribution, test and analyse the hypothesis for mean, | | | | | | | | | | | | |
| | | variance, proportions and differences using z and t, chi-square and F – distribution | | | | | | | | | | | | |
| | _ | and also test and analyse the independence of attributes and goodness of fit. | | | | | | | | | | | | |
| CO2 | | Apply one-way and two – way classification techniques and analyse the various standard designs (CRD, RBD, LSD) for the real – life problems. | | | | | | | | | | | us | |
| CO3 | _ | Explain the methods to solve algebraic and transcendental equation, a linear | | | | | | | | | | | | |
| 005 | | system of equations by direct and iterative methods and find eigen value of a | | | | | | | | | | | | |
| | 1 - | matrix by power method. | | | | | | | | | | | | |
| CO4: Describe and apply the interpolation methods for equal and uner | | | | | | | | | | | l uneq | ual ir | ntervals | s, and |
| obtain the derivatives using those interpolation methods to compute. | | | | | | | | | | | | | | |
| CO5: Solve linear and nonlinear ordinary differential equations of first a | | | | | | | | | | and s | econd | order | | |
| _ | | / single | and | multi si | tep me | thods. | • | | | | | | | |
| Pre-re | | | | | | | | | | | | | | |
| | | Transfo | rms 8 | & Partia | ıl differ | ential | equa | itions | | | | | | |
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| COs | РО | PO | РО | РО | PO | PO | PO | PO | P0 | РО | PO | РО | PSO | PSC |
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 1 | 2 |
| CO1 | 2 | 3 | 3 | | 2 | _ | _ | _ | _ | _ | _ | _ | 3 | _ |
| CO2 | 2 | 3 | 3 | _ | _ | 2 | _ | _ | _ | _ | 2 | _ | 3 | _ |
| CO3 | 2 | - | | 2 | _ | 2 | _ | _ | _ | _ | - | _ | _ | 2 |
| CO4 | 2 | _ | | 2 | _ | 2 | _ | _ | _ | _ | _ | _ | _ | 2 |
| CO5 | 2 | _ | _ | 2 | _ | 2 | _ | _ | _ | _ | _ | _ | | 2 |
| | | | | | Cours | | essme | ent me | ethod | s S | | | | |
| | | | | Dire | | | | | | | Inc | dire | ct | |
| Internal test I (6) Seminar (5) Course end surve | | | | | | | | | | | | | | |
| Intern | al te | st II (6) |) | Moodle (7) | | | | | | | | | | |
| | | st III (6 | 5) | Attendance (5) | | | | | | | | | | |
| Assign | | . , | | | emeste | | ninatio | on (60) |) | | | | | |
| Unit 01: TESTING OF HYPOTHESIS | | | | | | | | | | 09+6 Hours | | | | |
| | - | hypothe t for po | | | | - | - | | | | _ | | | |
| square test for population variance, goodness of fit, independence of attributes Unit 02: DESIGN OF EXPERIMENTS | | | | | | | | | 09+6 Hours | | | | | |
| Compl design | - | randoi | mized | d desigr | n, rand | omize | d bloc | k desig | gn, Lat | in squa | are des | sign | | |

Unit 03: SOLUTION OF EQUATIONS AND EIGENVALUE PROBLEMS

09+6 Hours

Newton – Raphson method, Gauss elimination method, pivoting, Gauss – Jordan methods, iterative methods of Gauss-Jacobi and Gauss- Seidel ,matrix inversion by Gauss -Jordan method, eigen values of a matrix by power method

Unit 04: INTERPOLATION, NUMERICAL INTEGRATION

NUMERICAL DIFFERENTIATION

k 09+6 Hours

Lagrange's and Newton's divided difference interpolation, Newton's forward and backward difference interpolation, approximation of derivatives using interpolation polynomials, numerical integrating using Trapezoidal and Simpson's 1/3 rules

Unit 05: INITIAL VALUE PROBLEMS FOR ORDINARY DIFFERENTIAL EQUATIONS

09+6 Hours

Taylor series method, Euler and modified Euler methods, fourth order Runge – Kutta method for solving first and second order equations, Milne's and Adam's predictor and corrector methods.

Theory: 45 Hrs Tutorial: 30 Hrs Total Hours: 75 Hrs

Text Books

- 1. Ponnusamy S., and Santha Kumaran A., "Statistics and Numerical Methods", Sonaversity, 1st Edition, 2009
- 2. Johnson R.A., and Gupta C.B., "Miller and Freund's, "Probability and Statistics for Engineer's", Pearson Education, Asia, 8th Edition, 2011

Extensive Reading

REFERENCES

- 1. Grewal, B.S., and Grewal J.S., "Numerical Methods in Engineering and Science", khanna publishers, New Delhi, 6th Edition, 2014
- 2. Walpole R.E, Myers R.H., and Kye., "Probability and Statistics for Engineers and Scientists", Pearson Education, Asia, 9th Edition, 2012
- 3. Gerald, C.F and Wheatley, P.O., "Applied Numerical Analysis", Pearson Education Asia, New Delhi, 6th Editions, 2006

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| U1! | 5CHE | 405R | | ENV | IRONI | MENT | AL SC | IENCE | ANI | D ENGIN | IEERIN | IG | L | T | Р | С |
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| Cour | se Ou | itcome | es | | | | | | | | | • | | | | |
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| CO1: | | | • | | | | | | | nmental | | | | | | |
| | | - | | | natur | al reso | ources | like fo | rests | s, water, | minera | l, food, | ene | rgy a | ınd | |
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| CUZ | | nserva | | ncepts | oi aii | ecosys | ыен а | na pro | viue | an over | view oi | biodive | Sity | anu | ILS | |
| CO3: | | | | ious kr | nown k | inds o | f envii | ronme | ntal ı | pollution | and dis | cuss the | eir c | ause | S. | |
| | | fects a | | | | | | 0 | i i cai ¡ | 50 | 41.4 4.5 | cass cire | O O | aase | - , | |
| CO4: | Gi | ve an | accou | nt of th | ne soci | al issu | ies wit | h rega | rd to | the env | ironmer | nt. | | | | |
| CO5: | Di | scuss | the im | pact o | f huma | an pop | ulatio | n on th | ne en | vironme | nt. | | | | | |
| Pre-r | equis | site | | | | | | | | | | | | | | |
| | ŀ | Engine | ering (| chemis | try | | | | | | | | | | | |
| | | | | | | | | | | | | | | | | |
| | CO/PO, PSO Mapping (3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak | | | | | | | | | | | | | | | |
| | | | | | | | | | | | | | | | | |
| COs | DO1 | | | | | | | | | me Spec | | | | - | DC | 02 |
| | PO1 | PO2 | PO3 | PO4 | PO5 | P06 | PO7 | PO8 | P09 | PO10 | PO11 | PO12 | P5 | 01 | PS | 02 |
| CO1 | 2 | | 1 | 2 | | 2 | 3 | 2 | | | T | 2 | | 2 | 1 | L |
| CO2 | 2 | | 1 | 2 | | 2 | 3 | 2 | | | 1 | 2 | : | 2 | 2 | 2 |
| CO3 | 2 | | 1 | 2 | | 3 | 3 | 3 | | | 2 | 2 | | 2 | 2 | 2 |
| CO4 | 2 | | 2 | 1 | | 3 | 3 | 3 | 1 | | 2 | 2 | | 2 | 2 | 2 |
| CO5 | 2 | | 1 | 3 | | 3 | 3 | 2 | 1 | | 2 | 2 | | 2 | 1 | L |
| | | | | | | Cour | se As | sessn | ent | method | S | | | | | |
| | | | | Dire | ct | | | | | | | Indirec | t | | | |
| Inter | nal tes | st I (6) | | | nar (5) | | | | | Course | end sur | vey | | | | |
| | | st II (6 | | Moodl | ` ′ | | | | | | | • | | | | |
| Inter | nal tes | st III (| 6) | Attend | dance | (5) | | | | | | | | | | |
| Assig | nmen | nment (5) End semester Examination (60) | | | | | | | | | | | | | | |

Unit 01: Introduction to Environmental Studies and Natural Resources 12 Hours

Definition, Scope and Importance – Need for public awareness – Forest Resources:- Use and over - exploitation, deforestation, Case Studies, Timber Extraction, Dams, Benefits and their effects on forests and tribal people - Water Resources:- Use and Over-Utilization of Surface and ground water , Floods, Drought, Conflicts Over Water – Mineral Resources:- Use–Environmental Effects of Extracting and Using Mineral Resources – Food Resources: World Food Problems, Changes caused by Agriculture and Overgrazing, Effects of Modern Agriculture, Fertilizer- Pesticide Problems, Water Logging, salinity – Energy Resources:- Growing Energy Needs, Renewable and Non Renewable Energy Sources, Use of Alternate Energy Sources – Land Resources:- Land as a Resource, Land Degradation, Man Induced Landslides, Soil Erosion and Desertification – Role of an Individual in Conservation of Natural Resources.

Unit 02: Ecosystems and Biodiversity

9 Hours

Concepts of an Ecosystem – Structure and Function of an Ecosystem – Producers, Consumers and Decomposers – Energy Flow in the Ecosystem – Biogeochemical Processes - Ecological Succession – Food Chains, Food Webs and Ecological Pyramids.

Introduction to Biodiversity – Definition: Genetic, Species and Ecosystem Diversity – Value of Biodiversity: Consumptive Use, Productive Use, Social, Ethical, Aesthetic and Option Values – Biodiversity at Global, National and Local Levels – India as a Mega-Diversity Nation – Hot-Spots of Biodiversity – Threats to Biodiversity: Habitat Loss, Poaching of Wildlife, Man-Wildlife Conflicts – endangered and Endemic Species of India – Conservation of Biodiversity: In-Situ and Ex-Situ conservation of Biodiversity.

Unit 03: Environmental Pollution

10 Hours

Definition – Causes, Effects and Control Measures of:- (A) Air Pollution (B) Water Pollution (C) Soil Pollution (D) Marine Pollution (E) Noise Pollution (F) Thermal Pollution (G) Nuclear Hazards – Solid Waste Management:- Causes, Effects and Control Measures of Urban and Industrial Wastes, hazardous wastes and biomedical wastes – Role of an Individual in Prevention of Pollution – Pollution Case Studies – disaster Management:- Floods, Earthquake, Cyclone and Landslides, Waste water treatment methods, Green chemistry – principles and applications

Unit 04: Social Issues and the Environment

8 Hours

Sustainable Development – Urban Problems Related To energy – Water conservation, Rain Water Harvesting, Watershed Management – Resettlement and Rehabilitation of People, its Problems and Concerns – Environmental Ethics:- Issues and Possible Solutions — Climate Change, Global Warming, Acid Rain, Ozone Layer Depletion, Nuclear Accidents and Holocaust, Case Studies – Wasteland Reclamation – Environment Production Act – Air (Prevention and Control of Pollution) Act – Water (Prevention and Control of Pollution) Act – Wildlife Protection Act – Forest Conservation Act – Issues Involved in enforcement of Environmental Legislation – Public Awareness.

Unit 05: Human Population and the Environment

6 Hours

Population Growth, Variation Among Nations – Population Explosion – Family Welfare Programme – environment and Human Health – Human Rights – Value Education – HIV /AIDS – Women and Child Welfare – Role of Information Technology in Environment and Human Health – Case Studies.

Theory: 45 Hr Tutorial: - Total Hours: 45 Hr

Text Books

- 1. Gilbert M.Masters, Introduction to Environmental Engineering and Science, Pearson Education Pvt., Ltd., Third Edition, 2008.
- 2. Miller T.G. Jr., Environmental Science, Wadsworth Publishing Co., 14th edition 2014

REFERENCES

- 1. S. Radjarejesri et al., "Environmental Science" Sonaversity, Sona College of Technology, Salem, 2018.
- 2. Bharucha Erach, The Biodiversity of India, Mapin Publishing Pvt. Ltd., Ahmedabad, India-2002
- 3. Trivedi R.K., Handbook of Environmental Laws, Rules, Guidelines, Compliances and Standards, Vol. I and II., third edition 2009.
- 4. Masters, G.M., "Introduction to Environmental Engineering and Science", Pearson Education Pvt., Ltd., 2nd Edition, 2004.
- 5. Erach Bharucha, "Textbook of Environmental Studies for Undergraduate Courses", University Grands Commission, Universities Press India Private Limited, Hyderguda, 2005.

| U | 15MC401R APPLIED HY | DRAULICS AND PNEUMATICS | L | Т | P | С |
|---------|--|---------------------------------------|-------|------|-------|------|
| | | | 3 | 0 | 0 | 3 |
| Course | Outcomes | | | | | |
| After s | uccessful completion of this cours | se, the students should be able to |) | | | |
| CO1: | Apply the pump theory and classification | ations and able to use the fluid powe | r in | his/ | her | |
| | professional career. | | | | | |
| CO2: | Demonstrate the principle of hydrau | lic cylinders and fluid motors, Gear, | Vane | e an | ıd Pi | ston |
| | motors. | | | | | |
| CO3: | Compare accumulators and intensifi | ers and justify the usage of accumul | ators | on | rea | |
| | time feedback circuits in their profes | ssional career. | | | | |
| CO4: | Differentiate the different Pneumation | approaches for simple applications | and | able | e to | |
| | synthesis the new approach specific | to their application. | | | | |
| CO5: | Define fluidic devices applications w | ith basic trouble shooting methodolo | gies | and | ltyp | es |

Pre-requisite

Fluid Mechanics and machinery

of Servo systems.

CO/PO, PSO Mapping

(3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak

| | | | | | | | | | | | • | | | |
|--|-----|-------|-----|-----|-----|-----|-----|-----|-----|----|----|----|-----|-----|
| Programme Outcomes (POs) and Programme Specific Outcome (PSOs) | | | | | | | | | | | | | | |
| COs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | PO | PO | PO | PSO | PSO |
| | PO1 | P 0 2 | 103 | 704 | 100 | 700 | 107 | 100 | 109 | 10 | 11 | 12 | 1 | 2 |
| CO1 | 3 | 2 | 3 | 3 | 3 | 1 | | | | | | | 3 | 3 |
| | | | | | | | | | | | | | _ | _ |
| CO2 | 3 | 3 | 3 | | | | | | | | | | 3 | 3 |
| CO3 | 2 | 3 | 1 | 3 | 2 | | | | | | | 3 | 3 | 3 |
| | | | | | | | | | | | | | | |
| CO4 | 3 | 3 | 3 | 3 | | 3 | | | | | | | 3 | 3 |
| CO5 | 3 | 2 | 3 | 3 | 3 | 3 | | 3 | | | | 3 | 3 | 3 |

Course Assessment methods

| | Direct | Indirect |
|-----------------------|-------------------------------|-------------------|
| Internal test I (6) | Seminar (5) | Course end survey |
| Internal test II (6) | Moodle (7) | |
| Internal test III (6) | Attendance (5) | |
| Assignment (5) | End semester Examination (60) | |

Unit 01: FLUID POWER SYSTEMS AND GENERATOR

09 Hours

Introduction to fluid power, Advantages of fluid power, Application of fluid power system. Types of fluid power systems, Fluid power symbols.

Sources of Hydraulic Power: Pumping theory – Pump classification – Gear pump, Vane Pump, piston pump, construction and working of pumps – pump performance – Variable displacement pumps

Unit 02: CONTROL AND ACTUATION ELEMENTS

09 Hours

Construction of Control Components: Direction control valves – 3/2 way valve – 4/2 way valve – 4/3 valve-5/3 valve- Shuttle valve – check valve – pressure control valve – pressure reducing valve, sequence valve, Flow control valve – Fixed and adjustable -electrical control solenoid

valves, Relays.

Fluid Power Actuators: Linear hydraulic actuators – Types of hydraulic cylinders – Single acting, Double acting -special cylinders like-Tandem, Rod-less, Telescopic, Cylinder cushioning mechanism, Construction of double acting cylinder, Rotary actuators – Fluid motors, Gear, Vane and Piston motors.

Unit 03: HYDRAULIC CIRCUITS

09 Hours

Hydraulic circuits-reciprocating-quick return-pressure sequencing circuit- Regeneration circuit Drilling circuit, synchronizing circuit, speed control-meter in, meter out and bleed off circuit, safety circuits

Accumulators and Intensifiers: Types of accumulators – Accumulators circuits, intensifier – Applications of Intensifier – Intensifier circuit.

Unit 04: PNEUMATIC SYSTEMS AND CIRCUITS

09 Hours

Pneumatic Components: Properties of air – Compressors – Filter, Regulator, and Lubricator Unit – Air control valves, Quick exhaust valves, and pneumatic actuators. Fluid Power Circuit Design, Pneumo-hydraulic circuit, Sequential circuit design for simple applications using cascade method.

Unit 05: SPECIAL SYSTEM AND MAINTENANCE

09 Hours

Servo systems – Hydro Mechanical servo systems, Electro hydraulic servo systems and hydro pneumatic circuits -Introduction to logic circuits.

Introduction to fluidic devices, simple circuits, ladder diagrams, PLC applications in fluid power control circuit –fault finding -Failure and troubleshooting. Low cost automation.

Theory: 45 Hr Tutorial: - Total Hours: 45 Hr

Text Books

- 1. Anthony Esposito, "Fluid Power with Applications", Pearson Education, 7th edition, 2013.
- 2. Majumdar S.R., "Oil Hydraulics Systems- Principles and Maintenance", Tata McGraw-Hill, 2011.

REFERENCES

- 1. Dudelyt, A. Pease and John T. Pippenger, "Basic Fluid Power", Prentice Hall, 2007
- 2. Michael J, Prinches and Ashby J. G, "Power Hydraulics", Prentice Hall, 2009.
- 3. Anthony Lal, "Oil hydraulics in the service of industry", Allied publishers, 2002.
 - 4. Shanmuqasundaram.K, "Hydraulic and Pneumatic controls", Chand & Co, 2006.

Course Outcomes

After successful completion of this course, the students should be able to

- **CO1:** Identify and enumerate different link-based mechanisms with a force-motion relationship in components subjected to external forces.
- **CO2:** Design and evaluate the performance of different cams and followers.
- **CO3:** Interpret the force analysis of simple mechanisms.
- **CO4:** Design and evaluate the performance of rotating & reciprocating masses.
- **CO5:** Value the principles in mechanisms used for governing of machines

Pre-requisite

Engineering Mechanics

CO/PO, PSO Mapping

(3/2/1 indicates the strength of correlation) 3-Strong, 2-Medium, 1-Weak

| Programme Outcomes (POs) and Programme Specific Outcome (PSOs) | | | | | | | SOs) | | | | | | | |
|--|-----|-----|-----|-----|-----|-----|------|-----|-------|----|----|----|----|----|
| COs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | РО | РО | РО | PS | PS |
| | 701 | FUZ | 103 | 104 | 103 | 100 | 107 | 100 | F 0 9 | 10 | 11 | 12 | 01 | 02 |
| CO1 | 3 | 3 | 3 | 3 | | | 3 | | | 3 | | 3 | 3 | 3 |
| CO2 | 3 | 3 | 3 | 3 | | | 3 | | | 2 | | | 3 | 3 |
| CO3 | 3 | 3 | 3 | 3 | | | | | | 2 | | 2 | 3 | 3 |
| CO4 | 3 | 3 | 3 | 3 | | | | | | 2 | | | 3 | 3 |
| CO5 | 3 | 3 | 3 | 3 | | | 3 | | | | | | 3 | 3 |

Course Assessment methods Direct Indirect Seminar (5) Course and survey

| Internal test I (6) | Seminar (5) | Course end survey |
|-----------------------|-------------------------------|-------------------|
| Internal test II (6) | Moodle (7) | |
| Internal test III (6) | Attendance (5) | |
| Assignment (5) | End semester Examination (60) | |

Unit 01: INTRODUCTION TO MECHANISMS

09 Hours

Definitions Link or Element, Kinematic Pairs, Kinematic chain, Degrees of Freedom, Grubler's Criterion (without derivation), Kinematic Chain, Mechanism, Structure, Mobility of Mechanism, Mechanical Advantage, Transmission angle. Inversions of Kinematic Chains: Four bar chain, Single slider and Double slider. Common Mechanisms, Straight line Mechanisms (Exact & Approximate Straight line).

Unit 02: KINEMATICS OF CAM

09 Hours

Cams: Types of cams, Types of followers. Displacement, Velocity & Acceleration Time curves for cam Profiles. Disc cam with Reciprocating follower having Knife- Edge, Roller & Flat-face follower, Disc cam with oscillating roller follower. Follower motions including,

SHM, Uniform velocity, Uniform acceleration & retardation and Cycloidal motion.

UNIT 03: FORCE ANALYSIS

09 Hours

Static force analysis:

Introduction: Static equilibrium. Equilibrium of two and three force members. Members with two forces and torque, free body diagrams. Static force analysis of four-bar mechanism and slider-crank mechanism with and without friction.

Dynamics force analysis:

Alembert's principle, Inertia force, inertia torque, Dynamic force analysis of reciprocating engine (Analytical method)

Unit 04: BALANCING OF ROTATING & RECIPROCATING MASSES

09 Hours

Balancing of Rotating Masses:

Static and dynamic balancing, balancing of single rotating mass by balancing masses in same plane and in different planes. Balancing of several rotating masses by balancing masses in same plane and in different planes.

Balancing of Reciprocating Masses:

Balancing of Locomotives, Multi cylinder engine, partial balancing of locomotive engines.

Unit 05: GYROSCOPE & GOVERNORS

09 Hours

Governors:

Types of governors; force analysis of Watt, Porter (Problem alone) and Hartnell governors (Theory). Controlling force, stability, sensitiveness, isochronism, effort and power.

Gyroscope:

Gyroscopic couple, Effect of gyroscopic couple on ship, aeroplane, stability of two-wheelers.

Theory: 45Hrs Tutorial: 0 Total Hours: 45 Hrs

Text Books

- 1. Ratan, S.S., "Theory of Machines", Tata McGraw Hill Publishing company Ltd., 4th Edition, 2014.
- 2. Sadhu Singh., "Theory of Machines", Pearson Education India, 2nd Edition 2013.
- 3. Thomas Bevan, "Theory of Machines", Pearson Education India, 1948, 3rd Edition, 2010.

REFERENCES

- 1. R. S. Khurmi, J. K. Gupta. "Theory of Machines" Eurasia Publishing House, 2008.
- 2. B.L. Balleney, "Theory of Machines", Khanna Pub. Delhi, 2012.
- 3. Shigley J.E and Uicker J.J "Theory of Machines and Mechanisms," McGraw Hill ISE, 2011.
- 4. Rao J.S and Dukkipati R.V, "Mechanism and Machine Theory", New Age Intl., New Delhi, 2nd Edition, 2012.
- 5. Ambekar A. G, "Mechanism and machine theory", PHI Learning Pvt. Ltd, New Delhi, 2007.

| U15MC403R | SENSORS AND INSTRUMENTATION | L | Т | Р | С |
|-----------|-----------------------------|---|---|---|---|
| | | 3 | 0 | 0 | 3 |

Course Outcomes

After successful completion of this course, the students should be able to

- **CO1:** Understand the units and standards, their conversions, characteristics and error analysis of measurement systems.
- **CO2:** Describe the different sensors available in mechanical measurements
- **CO3:** Classify the different types signal conditioning systems.
- **CO4:** Design a signal conditioning circuit and data acquisition system
- **CO5:** Develop the virtual instrumentation systems.

Pre-requisite

Electron devices and circuits

1.

CO/PO, PSO Mapping

(3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak

| Programme Outcomes (POs) and Programme Specific Outcome (PSOs) | | | | | | | | | | | | | | |
|--|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|----|-----|-----|
| COs | PO1 | PO2 | PO3 | PO4 | DOE | PO6 | PO7 | PO8 | P09 | PO10 | DO11 | РО | PSO | PSO |
| | POI | PU2 | PU3 | PU4 | PO5 | P06 | PO7 | PU6 | P09 | | PO11 | 12 | 1 | 2 |
| CO1 | 3 | | 3 | 2 | | | 2 | | | 2 | | | 3 | 2 |
| CO2 | 3 | | 3 | 2 | | | 2 | | | 2 | | | 3 | 2 |
| CO3 | 3 | | 3 | 2 | | | 2 | | | 2 | | | 3 | 2 |
| CO4 | 3 | | 3 | 2 | | | 2 | | | 2 | | | 3 | 2 |
| CO5 | 3 | | 3 | 2 | | | 2 | | | 2 | | | 3 | 2 |

Course Assessment methods

| | Direct | Indirect |
|-----------------------|-------------------------------|-------------------|
| Internal test I (6) | Seminar (5) | Course end survey |
| Internal test II (6) | Moodle (7) | |
| Internal test III (6) | Attendance (5) | |
| Assignment (5) | End semester Examination (60) | |

Unit 01: GENERAL CONCEPTS OF MEASUREMENT

09 Hours

Generalized Measurement System – Performance Characteristics – Static and Dynamic Characteristics – Errors in Measurements – Generalized Performance of Zero Order, First Order and Second Order Systems – Classifications of Transducers

Unit 02: SENSORS 09 Hours

Introduction -Sensor Characteristics - Fundamentals of Time and Frequency- Linear and Rotational Sensors-Acceleration Sensors-Force Measurement-Torque and Power Measurement-Flow Measurement-Temperature Measurements-Distance Measuring and Proximity Sensors-Light sensor.

Unit 03: SIGNALCONDITIONING

09 Hours

Instrumentation amplifier characteristics, OP-Amp- characteristics- OP-Amp circuits used in instrumentation- A/D and D/A conversion, Clipper and clamper, Frequency to voltage, voltage to frequency Conversion concept and methods.

Unit 04: DATA ACQUISITION

09 Hours

Real-time interfacing – Introduction - Elements of data acquisition and control - Overview of I/O process, Data Acquisition Conversion-General configuration-single channel and multichannel data acquisition – Data conversion – Introduction to Digital Transmission system.

Unit 05 VIRTUAL INSTRUMENTATION

09 Hours

Block diagram and architecture of the virtual instrumentation - VIs and sub VIs, loops and charts, arrays, clusters and graphs, case and sequence structures, formula nodes, local and global variables, string and file I/O.

Theory: 45 Hr Tutorial: - Total Hours: 45 Hr

Text Books

- 1. John G. Webster, "Measurement, Instrumentation, and Sensors Handbook", CRC Press. 2014.
- 2. Brian Morriss, "Automated Manufacturing Systems Actuators, Controls, Sensors and Robotics", McGraw Hill International Edition, 1995.

REFERENCES

- 1. Buchanan, W, "Industrial Instrumentation and Control", Butterworth-Heinemann Publishers, 1999.
- 2. Patranabis, D, "Sensors and Transducers", Wheeler Publishing Co, Ltd., New Delhi, 2003.
- 3. Holeman . J, "Experimental Methods for Engineers", Mc Graw Hill, 10th Edition, 2010.
- 4. Deoblin E.O. "Measurement Systems Application and Design", McGraw Hill, 4th Edition, 2005.

| U15I | MC404R | MICROPROCESSORS AND | L | т | P | С |
|---------|-------------|---|------|------|------|-------|
| | | MICROCONTROLLERS | 3 | 0 | 0 | 3 |
| Course | Outcomes | | | | | |
| After s | uccessful c | ompletion of this course, the students should be | able | to | | |
| CO1: | Outline the | architecture, discuss the addressing modes, instruct | tion | set | inte | rrupt |
| | structure a | nd develop skill in simple program writing of Intel 808 | 5 mi | crop | roce | essor |

structure and develop skill in simple program writing of Intel 8085 microprocessor CO2: Discuss various Peripheral Interfacing function and interface with 8085 processor CO3: Outline the architecture, discuss the addressing modes, instruction set interrupt structure and develop skill in simple program writing of Intel 8086 microprocessor

CO4: Explain the architecture, discuss the addressing modes, instruction set interrupt structure and develop skill in simple program writing of Intel 8051 microcontroller

Apply the interfacing techniques in motors and traffic light controller for microcontroller based simple applications

Pre-requisite

Electron devices and circuits

CO/PO, PSO Mapping

(3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak

| | | Prog | gramm | e Outo | comes | (POs) | and P | rogran | nme S | pecifi | c Outo | ome (| PSOs) | |
|-----|-----|------|-------|--------|-------|-------|-------|--------|-------|----------|----------|----------|-------|-------|
| COs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | PO 10 | PO 11 | PO 12 | PSO 1 | PSO 2 |
| CO1 | 3 | 3 | 3 | 2 | 2 | | | | 2 | | | | 3 | 2 |
| CO2 | 3 | 3 | 3 | 2 | 2 | | | | 2 | | | | 3 | 2 |
| CO3 | 3 | 2 | 3 | 2 | 2 | | | | 2 | | | | 3 | 2 |
| CO4 | 3 | 3 | 3 | 2 | 2 | | | | 2 | | | | 3 | 2 |
| CO5 | 3 | 3 | 3 | 2 | 2 | | | | 2 | | | | 3 | 2 |

Course Assessment methods Direct Indirect Internal test I (6) Seminar (5) Course end survey Internal test II (6) Moodle (7)

Internal test III (6) Attendance (5)
Assignment (5) End semester Examination (60)

Unit 01: 8085 MICROPROCESSORS

09 Hours

8085 architecture – Instruction set – Addressing modes– Machine cycles and timing diagrams – interrupts - memory interfacing, typical EPROM and RAM Interfacing.

Unit 02: PERIPHERALS INTERFACING OF 8085

09 Hours

Architecture and programming of ICs: 8255 PPI, 8259 PIC, 8251 USART, 8279 keyboard display controller ,8254 timer/ counter.

Unit 03: 8086 MICROPROCESSORS

09 Hours

8086 architecture – 8086 addressing modes – Memory organization- Instruction set –Stack Structure of 8086- interrupts.

Unit 04: MICROCONTROLLER

09 Hours

8051: Architecture, I/O pins - ports and circuits - Memory organization (internal and

external) – counters and timers – serial data I/O – interrupts. PIC18F: Architecture, I/O pins – ports and circuits

Unit 05: 8051 PROGRAMMING AND APPLICATIONS

09 Hours

8051 addressing modes – instruction set –Interfacing of stepper motor, speed control of DC motor, Introduction to raspberry and Arduino boards.

| Theory: 45 Hr Tutorial: - Total Hours: 45 I | Theory: 45 Hr |
|---|---------------|
|---|---------------|

Text Books

- 1. Krishna Kant, "Microprocessor and Microcontrollers", Eastern Company Edition, Prentice Hall of India, New Delhi, 2007.
- 2. R.S. Gaonkar, 'Microprocessor Architecture Programming and Application', with 8085, Wiley Eastern Ltd., New Delhi, 2013.
- 3. Soumitra Kumar Mandal, Microprocessor & Microcontroller Architecture, Programming & Interfacing using 8085,8086,8051, McGraw Hill Edu,2013.

REFERENCES

- 1. Muhammad Ali Mazidi & Janice Gilli Mazidi, R.D.Kinely 'The 8051 Micro Controller and Embedded Systems', PHI Pearson Education, 5th Indian reprint, 2003.
- 2. N.Senthil Kumar, M.Saravanan, S.Jeevananthan, 'Microprocessors and Microcontrollers', Oxford University Press, 2010.

| U15MC405R | HYDRAULICS AND PNEUMATICS LABORATORY | L | Т | P | С |
|-----------|--------------------------------------|---|---|---|---|
| 015MC405K | HIDRAULICS AND PNEUMATICS LABORATORY | 0 | 0 | 4 | 2 |

Course Outcomes

After successful completion of this course, the students should be able to

- **CO1:** Demonstrate the working principles of Hydraulic, Pneumatic pump and various actuators.
- **CO2:** Construct various hydraulic and, Pneumatic circuits using valves.
- **CO3:** Perform Industrial based circuit operations.

Pre-requisite:

- 1.Fluid Mechanics and fluid machinery
- 2. Fluid Mechanics and fluid machinery laboratory

CO/PO, PSO Mapping

(3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak

| СО | Programme Outcomes (POs) and Programme Specific Outcome (PSOs) | | | | | | | | | | | s) | | |
|-----|--|-----|-----|-----|-----|-----|-----|-----|-----|----------|----------|----------|----------|-------|
| s | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | PO 10 | PO 11 | PO 12 | PSO 1 | PSO 2 |
| CO1 | 3 | 3 | 3 | | 3 | | 2 | | | 3 | | 2 | 2 | 2 |
| CO2 | 3 | 3 | 3 | | 3 | | 2 | | | 2 | | 2 | 2 | 2 |
| CO3 | 3 | 3 | 3 | | 3 | | 3 | | | 2 | | 2 | 3 | 3 |

Course Assessment methods

| Dire | Direct | | | |
|---|----------------------------------|--------|-----|--|
| Mean of 1 st half of Experiment (10) | Quiz on 2 nd half (5) | Course | end | |
| Quiz on 1 st half (5) | Internal test II (10) | survey | | |
| Internal test I (10) | RTPS (10) | | | |
| Mean of 2 nd half of Experiment (10) | End semester Examination (40) | | | |

List of Experiments

- 1. [A] Study of Construction and working of Hydraulic equipments
 [B] Study of Construction and working Pneumatic equipments
- 2. Design and testing of hydraulic circuit for pressure control using pressure relief valve
- 3. Design and testing of hydraulic circuit for flow control using pressure /non-pressure compensated flow control valve.
- 4. Design and testing of hydraulic circuit for direction control using two-way valves
- 5. Design and testing of pneumatic circuit for single acting cylinder.
- 6. Design and testing of pneumatic circuit for double acting cylinder.
- 7. Design and testing of pneumatic circuit for flow control using meter in circuit.
- 8. Design and testing of pneumatic circuit for flow control using meter out circuit
- 9. Design and testing of pneumatic circuit for logic controls
- 10. Design and testing of pneumatic circuit for with multiple cylinder sequences
- 11. Modelling and analysis of hydraulic and pneumatic system using software

Total Hours: 60 Hrs

| U | 1 | 5 | M | C | 4 | 0 | 6 | R |
|---|---|---|---|---|---|---|---|---|
| | | | | | | | | |

SENSORS AND INSTRUMENTATION LABORATORY

| L | Т | P | С |
|---|---|---|---|
| 0 | 0 | 2 | 1 |

Course Outcomes

After successful completion of this course, the students should be able to

- Ability to use the sensors for the measurement of different signals and use of signal processing techniques to convert them to useful signal.
- CO2: Create appropriate design procedure to obtain a required measurement data for displacement
- CO3: Develop an appropriate design procedure, suitable for signal conversion to interface with computer

Pre-requisite

Electron devices and circuits

CO/PO, PSO Mapping

(3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak

| Programme Outcomes (POs) and Programme Specific Outcome (PSC | | | | | | | | | | PSOs) | | | | |
|--|-----|-----|-----|-----|-----|-----|-----|-----|-----|----------|----------|----------|------|------|
| S | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | PO 10 | PO 11 | PO 12 | PSO1 | PSO2 |
| CO1 | 3 | 3 | 3 | 3 | | | | | | 2 | | | 3 | 2 |
| CO2 | 3 | 3 | 3 | 3 | | | | | | 2 | | | 3 | 2 |
| CO3 | 3 | 3 | 3 | 3 | | | | | | 2 | | | 3 | 2 |

Course Assessment methods

| Dir | Direct | | | |
|---|----------------------------------|--------|-----|--|
| Mean of 1 st half of Experiment (10) | Quiz on 2 nd half (5) | Course | end | |
| Quiz on 1 st half (5) | Internal test II (10) | survey | | |
| Internal test I (10) | RTPS (10) | | | |
| Mean of 2 nd half of Experiment (10) | End semester Examination (40) | | | |

List of Experiments

- 1. Measurement of temperature using thermocouple, thermistor and RTD
- 2. Measurement of displacement using POT, LVDT & Capacitive transducer
- 3. Torque measurement using torque measuring devices
- 4. Strain Measurement using strain gauge
- 5. Servomotor position control using photo electric pickup
- 6. Wave Shaping circuit
- 7. Analog to Digital Converters
- 8. Digital Comparator
- 9. Voltage to frequency converter
- 10. Frequency to Voltage Converter
- 11. Position and velocity measurement using encoders
- 12. Study on the application of data acquisition system for industrial purposes

U15MC407R

MICROPROCESSORS AND MICROCONTROLLER LABORATORY

| L | т | P | С |
|---|---|---|---|
| 0 | 0 | 4 | 2 |

Course Outcomes

After successful completion of this course, the students should be able to

- Write an assembly language program to perform basic arithmetic operations using 8085 Microprocessor instructions and also to interface various devices using 8085 instructions.
 Write an assembly language program to perform basic arithmetic operations using 8086 Microprocessor instructions.
- Write an assembly language program to perform basic arithmetic operations using 8051Microcontroller instructions.

Pre-requisite

- 1. Electron devices and circuits
- 2. Electron devices and circuits Laboratory

CO/PO, PSO Mapping

(3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak

| Programme Outcomes (POs) and Programme Specific Outcome (PSG | | | | | | | | | | PSOs) | | | | |
|--|-----|-----|-----|-----|-----|-----|-----|-----|-----|-------|----------|----------|-------|-------|
| s | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | PO10 | PO 11 | PO 12 | PSO 1 | PSO 2 |
| CO1 | 3 | 3 | 3 | 3 | | | | | | 2 | | | 3 | 2 |
| CO2 | 3 | 3 | 3 | 3 | | | | | | 2 | | | 3 | 2 |
| CO3 | 3 | 3 | 3 | 3 | | | | | | 2 | | | 3 | 2 |

Course Assessment methods

| Direc | Indire | ect | |
|---|----------------------------------|--------|-----|
| Mean of 1 st half of Experiment (10) | Quiz on 2 nd half (5) | Course | end |
| Quiz on 1 st half (5) | Internal test II (10) | survey | |
| Internal test I (10) | RTPS (10) | | |
| Mean of 2 nd half of Experiment (10) | End semester Examination (40) | | |

List of Experiments

- 1. Assembly Language Programming of 8-bit binary addition and subtraction using 8085 processor.
- 2. Assembly Language Programming of 8-bit binary multiplication and division using 8085 processor.
- 3. Assembly Language Programming of 16-bit addition and multiplication using 8085 processor.
- 4. Assembly Language Programming of 8-bit Minimum / Maximum number, Ascending / Descending order using 8085 processor.
- 5. Assembly Language Programming of Interface Experiments (A/D and D/A interface) using 8085 processor.
- 6. Interfacing and Programming of Stepper Motor control using 8085 processor.
- 7. Assembly Language Programming of 16-bit binary addition and subtraction using 8086 processor.
- 8. Assembly Language Programming of 16-bit binary multiplication and division using 8086 processor.

- 9. Assembly Language Programming of 8-bit binary addition and subtraction using 8051 microcontrollers.
- 10. Assembly Language Programming of 8-bit binary multiplication and division using 8051 microcontroller.
- 11. Study and Interface of Arduino board.
- 12. Study and Interface of Raspberry PI board.

| Semester – IV | U15 GE 401R: SOFT SKILLS AND APTITUDE - II |
|------------------------|---|
| Course Outcomes | |
| At the end of the cour | rse the student will be able to: |
| 1. Demonstrate capab | ilities in additional soft-skill areas using hands-on and/or case-study approaches |
| 2. Solve problems of | increasing difficulty than those in SSA-I* in given areas of quantitative aptitude ng and score 65-70% marks in company-specific internal tests |
| 3. Demonstrate greate | er than SSA-I level of verbal aptitude skills in English with regard to given topics marks in company-specific internal tests |
| | Demonstrating soft-skill capabilities with reference to the following |
| | topics: |
| | a. SWOT |
| | b. Goal setting |
| 1. Soft Skills | c. Time management |
| | d. Stress management |
| | e. Interpersonal skills and Intrapersonal skills |
| | f. Presentation skills |
| | g. Group discussions |
| | Solving problems with reference to the following topics: |
| | a. Allegation and mixture |
| | b. Time, speed and distance: Unit conversion, Average speed, Relative |
| | speed, two objects crossing each other in the same direction and |
| 2. Quantitative Aptitu | |
| and | c. Clocks |
| Logical Reasoning | d. Calendars |
| | e. Blood relations |
| | f. Cubes and Dices |
| | g. Syllogism (≤3 statements) |
| | h. Ranking and order |
| | i. Company specific aptitude questions |
| | Demonstrating English language skills with reference to the following |
| | topics: a. Critical reasoning |
| | b. Theme detection |
| 2 Verbal Antitude | c. Verbal analogy |
| 3. Verbal Aptitude | d. Prepositions |
| | e. Articles |
| | f. Cloze test |
| | g. Company specific aptitude questions |
| N | 10 Transfer |

Dr.S.Anita

Department of Placement Training Sona College of Technology, Salem-636 005.

Sona College of Technology, Salem (An Autonomous Institution)

Courses of Study for B.E/B.Tech. Semester V under Regulations 2015R (CBCS)

Branch: Mechatronics Engineering

| S. No | Course Code | Cour | rse Title | Lecture | Tutorial | Practical | Credit |
|-------|--|----------------------------|--|---------|----------|----------------------|--------|
| | Course Code Course Title Lecture Tutor | | | | | | |
| 1 | U15MC501R | Computer Aided Design ar | nd Manufacturing | 3 | 0 | 2 | 4 |
| 2 | U15MC502R | Thermodynamics and Hear | t Transfer | 3 | 0 | 0 | 3 |
| 3 | U15CS508R | Object Oriented Programm | ning and Data Structures | 3 | 0 | 0 | 3 |
| 4 | U15MC503R | Embedded Systems and In | nbedded Systems and Internet of Things | | 0 | 0 | 3 |
| 5 | U15MC504R | Industrial Automation | mation | | 0 | 0 | 3 |
| | U15MC901R | | Control Systems | 3 | | | |
| 6 | U15MC902R | | Industrial Drives | | 0 | 0 | 3 |
| | Professional Elective-1 | Additive Manufacturing | | | | | |
| | 1 | | Practical | 1 | | | |
| 7 | U15MC505R | Embedded Systems and In | ternet of Things Laboratory | 0 | 0 | 4 | 2 |
| 8 | U15MC506R | Industrial Automation Lab | oratory | 0 | 0 | 4 | 2 |
| 9 | U15MC507R | Mini Project-I | | 0 | 0 | 2 | 1 |
| 10 | U15GE501R | Soft Skills and Aptitude – | III | 0 | 0 | 2 | 1 |
| | • | • | | • | | Total Credits | 25 |

Approved By

Chairperson, Fashion Technology BoS Dr.P.Suresh Member Secretary, Academic Council Dr.R.Shivakumar

Chairperson, Academic Council & Principal Dr.S.R.R.Senthil Kumar

Copy to:-

HOD/ Mechatronics Engineering, Fifth Semester BE MCT Students and Staff, COE

U15MC501R

COMPUTER AIDED DESIGN AND MANUFACTURING

| L | T | P | C |
|---|---|---|---|
| 3 | 0 | 2 | 4 |

Course Outcomes

After successful completion of this course, the students should be able to

- **CO1:** State fundamental concepts of Computer aided design and Modeling Techniques.
- **CO2:** Explain construction and development of modern CNC machine and give the details of Automatic Tool changers (ATC).
- **CO3:** Write a CNC part program for manufacturing real time component applications.
- **CO4:** Explain and describe the process planning and group technology in CIM environment.
- **CO5:** Explain about the computer aided quality control systems based CMM testing and explain flexible manufacturing systems.

Pre-requisite

- 1. Engineering graphics
- 2. Manufacturing technology

CO/PO, PSO Mapping

(3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak

| COs | | Programme Outcomes (POs) and Programme Specific Outcome (PSOs) | | | | | | | | | | | | |
|-----|-----|--|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|
| COS | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | PO10 | PO11 | PO12 | PSO1 | PSO2 |
| CO1 | 3 | 2 | | | | | | 3 | | | | | 3 | 3 |
| CO2 | 3 | 3 | 3 | 3 | | | 3 | | | | | | 3 | 3 |
| CO3 | 3 | 2 | 3 | 3 | 3 | | 3 | | | | | 3 | 3 | 3 |
| CO4 | 3 | 2 | 3 | | 3 | | 3 | 3 | 3 | 3 | 3 | | 3 | 3 |
| CO5 | 3 | | 3 | | 3 | | 3 | 3 | 3 | 2 | 3 | | 3 | 3 |

Course Assessment methods

| D | Indirect | | | |
|-----------------------|-------------------------------|-------------------|--|--|
| Internal test I (6) | Seminar/ Assignment (5) | | | |
| Internal test II (6) | Moodle test (7) | Course and survey | | |
| Internal test III (6) | Attendance (5) | Course end survey | | |
| Assignment (5) | End semester Examination (60) | | | |

Unit 01 COMPUTER AIDED DESIGN

9+6 Hours

Introduction to CAD, Interactive display devices, Operator input/output devices, Graphic standards, 2D Transformation- Scaling, Translation and Rotation. Geometric Modeling- Wire Frame Modeling, Surface Modeling, Solid Modeling-Constructive solid geometry (CSG), Boundary Representation (B-Rep).

Unit 02: COMPUTER AIDED MANUFACTURING

9+6 Hours

CNC Technology-Classification of CNC systems-Contouring System-Interpolators, open loop and closed loop CNC systems, Hardware features-Direct Numerical Control. Construction features - Structural members-Slide ways-Sides linear bearings-Ball screws-Spindle drives and feed drives - work holding devices and tool holding devices-Automatic Tool changers

Unit 03: CNC - PROGRAMMING

9+6 Hours

Computer Numerical Control codes- Punched tapes, G,M Code, Standards, Types of dimensioning, Manual Part programming for point to point- Linear, Circular interpolation. - Canned cycles and subroutines. CNC programming practices for Turning and Milling Operations.

Unit 04: GROUP TECHNOLOGY AND CAPP

9+6 Hours

Introduction to CIM, Role of Elements, CIM Networking, Group Technology, Part Families, parts Classification & Coding, GT Machine cells, Shop floor phases, Benefits of GT. Computer Aided Process Planning (CAPP), Retrieval type, Generative type Process Planning Systems, Benefits of CAPP.

Unit 05: COMPUTER AIDED QUALITY CONTROL AND FMS

9+6 Hours

Computer Aided Quality Control (CAQC)- Introduction, Contact Inspection methods, Non-Contact Inspection methods, Co-ordinate Measuring Machine. Flexible manufacturing Systems- Introduction, Scope, Types, Elements and Benefits of FMS.

Theory: 45 Hrs Practical: 30 Hr Total Hours: 75 Hrs

Text Books

- 1. Ibrahim Zeid." CAD-CAM Theory and Practice", Tata McGraw-Hill Publishing Co. Ltd. 2nd edition.
- 2. P.Radhakrishan, S.Subramanyan, V. Raju, "CAD/CAM/CIM". New Age International Publishers, 3rd Edition 2012.
- 3. Mikell P. Groover and Emory W. Zimmers, Jr, "CAD/CAM Computer Aided and Manufacturing".
- 4. Eastern Economy Edition, PHI publishers 2007.

REFERENCES

- 1. Mikell.P.Groover "Automation, Production Systems and computer integrated and manufacturing", Pearson Education 2016.
- 2. P.N. Rao, "CAD/CAM Principles and Applications". Tata McGraw Hill Publications, 2010.
- 3. William .M. Neumann and Robert .F. Sproul, "Principle of Interactive Computer Graphics" McGraw Hill Book Co. Singapore, 2001.
- 4. Paul G. Ranky, "Computer Integrated Manufacturing- An Introduction with Case Studies" Prentice Hall International, 2004.

| 1 | МСБ | 02R | | THE | RMOD | YNAN | ICS A | ND | | L | Т | | Р | С |
|---|--------------|----------|---------|---------|----------|--------|---------------|----------|--------|----------|--------|--------------|---------|-------|
| 012 | МСЗ | 0UZK | | | HEAT | TRAN | ISFER | | | 3 | 0 | | 0 | 3 |
| Cour | se Oı | utcom | es | | | | | | | • | | • | • | |
| After | suc | cessfu | l comp | letior | of th | is cou | rse, tl | ne stu | dent | s shoul | d be a | ble to |) | |
| CO | L: Ex | press t | he bas | ic cond | epts a | nd law | s of th | ermod | ynan | nics | | | | |
| CO2 | 2: Pe | rform t | he ana | lysis o | f air st | andar | d cycle | S | | | | | | |
| CO | 3: Ev | aluate | the co | nductio | n heat | trans | fer for | a give | n sys | tem | | | | |
| CO3: Evaluate the conduction heat transfer for a given system CO4: Demonstrate the types of convection and determine heat transfer coefficient | | | | | | | | | | | | | | |
| COS | 5: In | /estiga | te the | radiati | on effe | ct amo | ong dif | ferent | surfa | ices | | | | |
| Pre-r | equi | site | | | | | - | | | | | | | |
| 1. | <u> </u> | neering | Physic | cs | | | | | | | | | | |
| 2. | Fluid | Mecha | nics | | | | | | | | | | | |
| | | | | | C | 0/P0, | PSO | Маррі | ng | | | | | |
| | (3/ | /2/1 ir | ndicat | es str | ength | of cor | relati | on) 3- | Stro | ng, 2-M | lediun | n, 1-W | /eak | |
| СО | | Progra | mme | Outco | mes (| POs) | and P | rograi | nme | Specifi | c Out | come | (PSOs | ;) |
| | РО | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | PO | РО | РО | PSO | PSC |
| S | 1 | PU2 | 103 | PU4 | PO3 | 100 | 107 | 100 | 103 | 10 | 11 | 12 | 1 | 2 |
| CO1 | 3 | 3 | 3 | 2 | 1 | 1 | 2 | 1 | 1 | 2 | 1 | 1 | 3 | 2 |
| 602 | | | _ | 2 | 4 | 4 | _ | 4 | 4 | | 4 | 4 | _ | _ |
| CO2 | 3 | 3 | 3 | | 1 | 1 | 2 | 1 | 1 | 2 | 1 | 1 | 3 | 2 |
| CO3 | 3 | 3 | 3 | 2 | 1 | 1 | 2 | 1 | 1 | 2 | 1 | 1 | 3 | 2 |
| CO4 | 3 | 3 | 3 | 2 | 1 | 1 | 2 | 1 | 1 | 2 | 1 | 1 | 3 | 2 |
| CO5 | 3 | 3 | 3 | 2 | 1 | 1 | 2 | 1 | 1 | 2 | 1 | 1 | 3 | 2 |
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| | | st III (| • | | endan | ` , | | | | C | Course | end si | ırvey | |
| Assigi | | • | -, | | | ` ' | xamina | ation (6 | 50) | | | | | |
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| Syste | ms-c | losed a | nd ope | en syst | ems - | prope | rties, r | rocess | es a | nd cycle | s- equ | ilibriur | n- wor | k and |
| | | | | | | | | | | nd flow | | | | |
| | | / -entr | | | | | | | | | | | | |
| UNIT | II | AIF | R STAI | NDARI | CYCI | LES | | | | | | | 9 Hou | rs |
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| cycle | effici | ency | | | | | | | | | | | | |
| UNIT | III | INTR | ODUC | TION | TO HE | AT TR | RANSF | ER AN | D C | CONDUC | CTION | | 9 Hou | rs |
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| | | | l Stea | dy Sta | ate He | at Co | nduction | on-Tra | nsien | t heat | condu | ction | (eleme | ntar |
| | | only). | | | | | | | | | | - | | |
| | | CONV | | | | | | | | | | | 9 Hou | |
| | • | • | | - | | | | | | Types o | | | | |
| | | | | | | | Flow - | Flow | over | Plates, | Cylind | lers ar | nd Sph | eres |
| | | w (elei | | y trea | tment | only). | | | | | | | | |
| | | ADIAT | | | | | | | | | | | 9 Hou | |
| | | | | | Boltzm | nann L | .aw, K | irchhoi | ff's L | .aw -Bla | ack Bo | dy Ra | diation | and |
| radiat | ion b | etweer | n surfa | ces. | | | | | | | | | | |
| | | | | | | | _ | | | | | | | |

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Total Hours: 45 Hrs

Tutorial: --

Theory: 45 Hrs

Text Books

- 1. P. K. Nag, Engineering Thermodynamics, Tata McGraw-Hill Publishing Company Limited, New Delhi, 2013
- 2. R.C Sachdeva, Fundamentals of Engineering Heat and Mass Transfer, New Age International Publishers, New Delhi, 2017

REFERENCES

- 1. P. K. Nag, Applied Thermodynamics, Tata McGraw-Hill Publishing Company Limited, New Delhi, 2nd edition ISBN: 9780070151314, 0070151318
- 2. Yunus A. Cengel and Michael A. Boles, Thermodynamics An Engineering Approach in SI Units, Tata McGraw Hill Publishing Company, New Delhi, 2010
- 3. Frank P. Incropera and David P. DeWitt, Fundamentals of Heat and Mass Transfer, John Wiley and Sons Pvt. Ltd., Singapore, 2006.
- 4. T. D. Eastop and Mc Conkey, Applied Thermodynamics for Engineering Technologists, Pearson, New Delhi, 2004.
- 5. C. P. Kothandaraman, S. Domkundwar and A. V. Domkundwar, A course in Thermal Engineering, Dhanpatrai and Co. Pvt. Ltd., New Delhi, 2012

C L Т **OBJECT ORIENTED PROGRAMMING** U15CS508R AND 3 0 0 3 **DATA STRUCTURES** Course Outcomes After successful completion of this course, the students should be able to Understand the basic concepts of object-oriented programming. CO2: Design program for real time applications using inheritance and polymorphism. CO3: Apply various linear tree data structures in real time applications. CO4: Implement the operations of tree traversals and hashing techniques **CO5:** Develop and apply algorithms for real time applications using graphs **Pre-requisite** 1. Programming in C **Course Assessment methods** Direct Indirect Internal test I (6) Seminar/ Assignment (5) Internal test II (6) Moodle test (7) Course end survey Internal test III (6) Attendance (5) Assignment (5) End semester Examination (60) UNIT I PRINCIPLES OF OOP 9 Hours Basic Concepts of Object Oriented Programming - Expressions - Control Structures -Classes and Objects - Class Members - Access Control - Pointers -Constructors and Destructors - Parameter Passing Methods - Inline Functions - Static Class Members - This Pointer -Friend Functions - Dynamic Memory Allocation (new and delete). UNIT II **INHERITANCE AND POLYMORPHISM** 9 Hours Inheritance Basics - Types of Inheritance - Base Class Access Control -Compile Time Polymorphism -Runtime Polymorphism using Virtual Functions - Abstract Class -Exception Handling. **UNIT III DATA STRUCTURES** 9 Hours

Basic Data Structures -Abstract Data Type - Linear Data Structures - List ADT - Single -Double and Circular - Stack ADT - Queue ADT.

UNIT IV TREES AND GRAPHS

9 Hours

Basic Terminologies -Tree Traversals - Binary Trees - Binary Search Tree ADT - Graph Traversals -Shortest Path Algorithm - Dijkstra's Algorithm - Minimum Spanning Tree -Prim's Algorithm - Kruskal's Algorithm.

UNIT V SEARCHING TECHNIQUES

9 Hours

Searching Techniques - Linear Search - Binary Search - Sorting Techniques - Insertion -Bubble and Merge Sort.

Tutorial: --Theory: 45 Hrs **Total Hours: 45 Hrs**

TEXT BOOKS

- 1. Mark Allen Weiss, "Data structures and Algorithms Analysis in C++", 4th Edition, Prentice Hall, 2013.
- 2. E. Balagurusamy, "Object-Oriented Programming With C++", 3rd Edition, Tata McGraw Hill, 2006.

REFERENCE BOOKS

- 1. Adam Drozdek, "Data structures and algorithms in C++", 3rd Edition, Cengage Learning, 2013.
- 2. Langsam, Augenstein and Tanenbaum "Data structures using C and C++", 2nd Edition, Prentice Hall of India, 1998.
- 3. Micheal T. Goodrich, Roberto Tamassia, David Mount, "Data Structures and Algorithms in C++", Wiley Student edition, John Wiley and Sons, 2009.

| 111 51 | 4C503R | EMBE | EDDED SYSTEMS AND INTERNET OF | L | Т | P | С | |
|----------|-----------------|------------|---|------------------|-----------|---------|--------|--|
| 0131 | MC3U3K | | THINGS | 3 | 0 | 0 | 3 | |
| Course | e Outcomes | <u> </u> | | | | | | |
| After s | successful o | completi | ion of this course, the students shoul | d be ab | ole to | | | |
| CO1: | | <u>-</u> | embedded systems and their developme | | | | | |
| CO2: | | | cepts involved in Real time operating sys | | euures. | | | |
| CO3: | | | ction, addressing modes and instructions | | DIC mic | ro cont | rollar | |
| CO4: | | | propriate sensors for an application and o | | | .io com | Toner. | |
| CO5: | | | tant aspects of IoT architectures and write | | | Arduin | o and | |
| cos. | Raspberry | • | · | e progra | 31115 101 | Arduni | Janu | |
| Dro-ro | quisite | TT to but | id System | | | | | |
| NIL | quisite | | | | | | | |
| | | | Course Assessment methods | | | | | |
| | | | Direct | | Ind | rect | | |
| Interna | l test I (6) | | Seminar/ Assignment (5) | | | | | |
| | l test II (6) | | Moodle test (7) | Course end surve | | | | |
| Interna | al test III (6) |) | Attendance (5) | | ourse e | na surv | ey | |
| Assigni | ment (5) | | End semester Examination (60) | | | | | |
| | TNTDOD | NUCTION | LTO EMPEDDED CYCTEMS | | | 9 H | lours | |
| JNIT I | INTROD | OCTION | I TO EMBEDDED SYSTEMS | | | | | |
| | | - | ems, embedded system design process, | | _ | | _ | |
| metrics | and optimiz | zing then | n. Hardware - Software codesign embedd | ed prod | luct dev | elopme | nt | |
| UNIT | II Real Tin | ne Oper | ating System | | | 9 H | lours | |
| Real tir | ne operatino | g system: | s Architecture - Tasks and Task states - 1 | asks ar | nd Data | - Sema | phon | |
| | | | je queues, mail boxes and pipes - End | | | | • | |
| | | _ | in an RTOS Environment. Introduction to | - | _ | - | | |
| JNIT II | I PERIPHI | ERALS A | ND NETWORKING | | | 9 H | lours | |
| Archite | cture - Instr | ruction se | et - Addressing modes - Timers - Interrup | t logic - | - CCP m | odules | _ | |
| ADC- N | letworking - | CAN BUS | S - I 2C - GSM - GPRS - Zig bee | | | | | |
| UNIT | V SENSOI | RS AND | CIRCUITS | | | 9 H | lours | |
| Sensor | - Introduct | tion. Teri | minology, Behavior, Selection, Circuits - | Overvi | iew and | Applic | ation | |
| | | - | Management, Wireless Link, Digital and A | | | | | |
| - | to Digital In | | gee.is, Thereas Link, Digital and | | 2.9.0 | | | |
| | | | URE AND PROGRAMMING | | | 9 H | lours | |
| | | | | | | | | |
| T T A | chitectures | - embe | dded System, Gateway and Cloud (Mo | $G()$ Δr | chitectu | re and | othe | |
| | | | tectures Arduino vs Raspberry Pi vs Elec | - | | | | |

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Tutorial: --

Total Hours: 45 Hrs

comparisons Arduino Interfaces – Arduino IDE - Programming

Theory: 45 Hrs

Text Books

- 1. Frank Vahid, Tony Givargis Embedded system design: a unified hardware/ software introduction. Wiley publication. 2002
- 2. "Internet of Things: A Hands-on Approach", by ArshdeepBahga and Vijay Madisetti (Universities Press)

REFERENCES

- 1. "The Internet of Things: Enabling Technologies, Platforms, and Use Cases", by Pethuru Raj and Anupama C. Raman (CRC Press)
- 2. Adrian McEwen and Hakim Cassimally, "Designing the Internet of Things", John Wiley & Sons Ltd., UK, 2014.
- 3. Rajkamal, 'Embedded System Architecture, Programming, Design', Tata Mc Graw Hill, 2011
- 4. John B. Peatman, "Design with PIC Microcontrollers" Prentice Hall, 2003.

| U15MC504R | INDUSTRIAL AUTOMATION | L | Т | Р | С |
|-----------|-----------------------|---|---|---|---|
| | | 3 | 0 | 0 | 3 |

Course Outcomes

After successful completion of this course, the students should be able to

| CO1: | Illustrate the requirements of industrial Automation |
|------|--|
| | · |

CO2: Explain the configuration and components of PLC devices

CO3: Design PLC programming using ladder logic.

CO4: Explain the distributed control systems

| CO5: Develop control for motor device |
|--|
|--|

Pre-requisite

Electronic Devices and circuits

CO/PO, PSO Mapping

(3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak

| | Programme Outcomes (POs) and Programme Specific Outcome (PSOs) | | | | | | | | | | s) | | | |
|-----|--|----|----|-----|----|----|----|-----|------|------|-----|------|------|------|
| COs | РО | РО | РО | PO4 | PO | PO | PO | PO8 | P09 | PO10 | PO1 | PO1 | PSO1 | PSO2 |
| | 1 | 2 | 3 | 104 | 5 | 6 | | 109 | 1010 | 1 2 | | 7301 | F302 | |
| CO1 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | | | 3 | 2 |
| CO2 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | | | 3 | 2 |
| CO3 | 3 | 2 | 3 | 2 | 3 | | 2 | | | 2 | | | 3 | 2 |
| CO4 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | | | 3 | 2 |
| CO5 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | | | 3 | 2 |

Course Assessment methods

| | Indirect | |
|-----------------------|-------------------------------|--------------------|
| Internal test I (6) | Seminar/ Assignment (5) | |
| Internal test II (6) | Moodle test (7) | Course and sum (a) |
| Internal test III (6) | Attendance (5) | Course end survey |
| Assignment (5) | End semester Examination (60) | |

UNIT I INTRODUCTION TO INDUSTRIAL AUTOMATION

9 Hours

Requirements of industrial automation – Industrial electrical equipment requiring control and integration through PLC – Functions of the central distributed control panels in a plant – conventional central relay and interlock panels and the various components used – advantages of PLC based system.

UNIT II PLC HARDWARE

9 Hours

PLC configuration and various components of the PLC – PLC inputs and outputs modules – Power Supplies – Programming format – Construction of PLC Ladder Diagrams – Analog Input and analog output devices – CPU, I/O cards.

UNIT III PLC AND SCADA

9 Hours

Networking of PLCs-Data communication-Fieldbus, PROFI bus, and Mod bus-OSI Model types-OPC function. Supervisory Control and Data Acquisition-Architecture-Remote terminal unit-Master terminal unit-Data Storage

| Controlling a Robot with PLC – PLC control of Stepper Motor – PLC Based AC motor Drive an Motor Drive. Theory: 45 Hrs Tutorial: Text Books Text Books | UNIT | IV DISTRIB | UTED CONTROL SYSTEM | | 9 Hours | | | | |
|---|-------|---|--|------------------|---------------|--|--|--|--|
| Operator displays - Engineering interfaces - Low level and high level engineering interfaces UNIT V PLC BASED ELECTRIC DRIVES 9 Hours Controlling a Robot with PLC - PLC control of Stepper Motor - PLC Based AC motor Drive an Motor Drive. Theory: 45 Hrs Tutorial: Total Hours: 45 Hrs Text Books 1. John W. Webb and Ronald A.Reis "Programmable Logic Controllers", Prentice - Hall of India Publishers, 2007. 2. Frank D Petruzella, "Programmable Logic Controllers", McGraw Hill Publishers, 3 rd Edition, 2010. REFERENCES 1. John R Hackworth, "Programmable Logic Controllers: Programming Methods and Applications", Pearson education, 1st Edition, 2003. 2. Siemens PLC Hand book for total automation 3. Allen - Bradley hand book for total automation | Evolu | ution - Architectur | es - Comparison - Local control unit - | Process interfa | cing issues - | | | | |
| Controlling a Robot with PLC – PLC control of Stepper Motor – PLC Based AC motor Drive and Motor Drive. Theory: 45 Hrs Tutorial: Total Hours: 45 Hr Text Books 1. John W. Webb and Ronald A.Reis "Programmable Logic Controllers", Prentice – Hall of India Publishers, 2007. 2. Frank D Petruzella, "Programmable Logic Controllers", McGraw Hill Publishers, 3 rd Edition, 2010. REFERENCES 1. John R Hackworth, "Programmable Logic Controllers: Programming Methods and Applications", Pearson education, 1st Edition, 2003. 2. Siemens PLC Hand book for total automation 3. Allen – Bradley hand book for total automation | | | · | • | | | | | |
| Controlling a Robot with PLC – PLC control of Stepper Motor – PLC Based AC motor Drive and Motor Drive. Theory: 45 Hrs Tutorial: Total Hours: 45 Hr Text Books 1. John W. Webb and Ronald A.Reis "Programmable Logic Controllers", Prentice – Hall of India Publishers, 2007. 2. Frank D Petruzella, "Programmable Logic Controllers", McGraw Hill Publishers, 3 rd Edition, 2010. REFERENCES 1. John R Hackworth, "Programmable Logic Controllers: Programming Methods and Applications", Pearson education, 1st Edition, 2003. 2. Siemens PLC Hand book for total automation 3. Allen – Bradley hand book for total automation | | | neering interfaces - Low level and high leve | l engineering in | terfaces | | | | |
| Theory: 45 Hrs Tutorial: Total Hours: 45 Hr Text Books 1. John W. Webb and Ronald A.Reis "Programmable Logic Controllers", Prentice – Hall of India Publishers, 2007. 2. Frank D Petruzella, "Programmable Logic Controllers", McGraw Hill Publishers, 3 rd Edition, 2010. REFERENCES 1. John R Hackworth, "Programmable Logic Controllers: Programming Methods and Applications", Pearson education, 1st Edition, 2003. 2. Siemens PLC Hand book for total automation 3. Allen – Bradley hand book for total automation | UNI | T V PLC BAS | ED ELECTRIC DRIVES | | 9 Hours | | | | |
| Theory: 45 Hrs Tutorial: Total Hours: 45 Hr Text Books 1. | Cont | rolling a Robot with | PLC - PLC control of Stepper Motor - PLC I | Based AC motor | Drive and DC | | | | |
| Text Books 1. John W. Webb and Ronald A.Reis "Programmable Logic Controllers", Prentice – Hall of India Publishers, 2007. 2. Frank D Petruzella, "Programmable Logic Controllers", McGraw Hill Publishers, 3 rd Edition, 2010. REFERENCES 1. John R Hackworth, "Programmable Logic Controllers: Programming Methods and Applications", Pearson education, 1st Edition, 2003. 2. Siemens PLC Hand book for total automation 3. Allen – Bradley hand book for total automation | Moto | r Drive. | | | | | | | |
| John W. Webb and Ronald A.Reis "Programmable Logic Controllers", Prentice – Hall of India Publishers, 2007. Frank D Petruzella, "Programmable Logic Controllers", McGraw Hill Publishers, 3 rd Edition, 2010. John R Hackworth, "Programmable Logic Controllers: Programming Methods and Applications", Pearson education, 1st Edition, 2003. Siemens PLC Hand book for total automation Allen – Bradley hand book for total automation | TI | heory: 45 Hrs | Tutorial: | Total Hou | rs: 45 Hrs | | | | |
| India Publishers, 2007. 2. Frank D Petruzella, "Programmable Logic Controllers", McGraw Hill Publishers, 3 rd Edition, 2010. REFERENCES 1. John R Hackworth, "Programmable Logic Controllers: Programming Methods and Applications", Pearson education, 1st Edition, 2003. 2. Siemens PLC Hand book for total automation 3. Allen – Bradley hand book for total automation | Text | Books | | | | | | | |
| REFERENCES 1. John R Hackworth, "Programmable Logic Controllers: Programming Methods and Applications", Pearson education, 1st Edition, 2003. 2. Siemens PLC Hand book for total automation 3. Allen – Bradley hand book for total automation | 1. | John W. Webb and Ronald A.Reis "Programmable Logic Controllers", Prentice – Hall of India Publishers, 2007. | | | | | | | |
| John R Hackworth, "Programmable Logic Controllers: Programming Methods and Applications", Pearson education, 1st Edition, 2003. Siemens PLC Hand book for total automation Allen – Bradley hand book for total automation | 2. | | | | | | | | |
| Applications", Pearson education, 1st Edition, 2003. 2. Siemens PLC Hand book for total automation 3. Allen – Bradley hand book for total automation | REFE | ERENCES | | | | | | | |
| 3. Allen – Bradley hand book for total automation | 1. | | | | | | | | |
| | 2. | Siemens PLC Hand book for total automation | | | | | | | |
| 4. GE – Fanuc hand book for total automation | 3. | Allen – Bradley hand book for total automation | | | | | | | |
| | 4. | GE – Fanuc hand book for total automation | | | | | | | |

U15MC505R

EMBEDDED SYSTEMS AND INTERNET OF THINGS LABORATORY

| L | T | P | С |
|---|---|---|---|
| 0 | 0 | 4 | 2 |

Course Outcomes

| After su | After successful completion of this course, the students should be able to | | | | | | | | | |
|----------|--|--|--|--|--|--|--|--|--|--|
| CO1: | Write embedded programs for any application | | | | | | | | | |
| CO2: | Create communication between peripherals using appropriate interfaces | | | | | | | | | |
| CO3: | Design and develop an IoT application using Arduino sensors and actuators | | | | | | | | | |

Pre-requisite

Sensors and instrumentation

Course Assessment methods

| Dire | Indirect | |
|--|---|-------------------|
| Mean of 1 st half of Experiment (10) Quiz on 1 st half (5) Internal test I (10) Mean of 2 nd half of Experiment (10) | Quiz on 2 nd half (5) Internal test II (10) RTPS (10) End semester Examination (40) | Course end survey |
| List of Experiments | | • |

| List of Experiments |
|--|
| I/O Programming |
| Interrupts and Timer application |
| Interfacing Keypad |
| Interfacing LCD |
| Interfacing ADC/DAC |
| Using Arduino |
| To control LED. |
| To identify objects using IR and PIR sensor. |
| Interfacing Arduino with modules and Shields |

Simple Project

Each student has to select an IoT Application / Product / System Requirement, that the student will develop during this course after thorough literature survey and analysis including feasibility and develop the same.

Total Hours: 60 Hrs

| U15 | U15MC506R INDUSTRIAL AUTOMATION LABORATORY | | | | | | | | L | Т | Р | С | | |
|--------|---|---------|---------|-----------|--------|---------|---------|---------|-----------|-----------|----------|----------|----------|------|
| | | | | | | | | | | | 0 | 0 | 4 | 2 |
| Cours | Course Outcomes | | | | | | | | | | | | | |
| After | suc | essfu | l com | pletion | of thi | s cou | rse, th | ne stud | lents sl | hould b | e able | e to | | |
| CO1: | D | evelop | the PL | C prog | ram fo | r the i | mplem | entatio | n of logi | ic gates | | | | |
| CO2: | D | evelop | the PL | C prog | ram fo | r conti | rolling | the par | ameters | s like Pr | essure | , Level | and Flow | · |
| CO3: | CO3: Design the real time PLC program for various applications like bottle filling, cylinder actuation and elevator control | | | | | | | | | | | | | |
| Pre-r | equi | site | | | | | | | | | | | | |
| 1.Elec | troni | c Devi | ces and | d circuit | s labo | ratory | | | | | | | | |
| 2.Hyd | rauli | cs and | pneun | natics la | borato | ory | | | | | | | | |
| | | | | | | CO | /PO, F | PSO Ma | pping | | | | | |
| | | (3/2 | /1 ind | dicates | stren | gth o | f corre | elation |) 3-Str | ong, 2- | Mediu | ım, 1-\ | Weak | |
| | | Р | rogra | mme O | utcon | nes (P | Os) a | nd Pro | gramm | e Spec | ific O | utcome | e (PSOs) | |
| COs | PO 1 | PO 2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | PO10 | PO1 1 | PO1 2 | PSO1 | PSO2 |
| CO1 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | | | 3 | 2 |
| CO2 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | | | 3 | 2 |
| CO3 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | | | 3 | 2 |
| CO4 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | | | 3 | 2 |
| CO5 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | | | 3 | 2 |

Course Assessment methods

| Dir | Indirect | |
|---|----------------------------------|-------------------|
| Mean of 1 st half of Experiment (10) | Quiz on 2 nd half (5) | Course end survey |
| Quiz on 1 st half (5) | Internal test II (10) | |
| Internal test I (10) | RTPS (10) | |
| Mean of 2 nd half of Experiment (10) | End semester Examination (40) | |

List of experiments/demonstrations:

- 1. Write ladder logic program for AND and OR gate.
 - 2. Write ladder logic program for NAND and NOR gate.
 - 3. Write ladder logic program for NOT and EX-OR gate.
 - 4. Automate the level and flow control using PLC.
 - 5. Conduct the temperature control using PLC
- 6. Conduct the pressure and flow control using PLC.
- 7. Conduct the control of elevator using PLC
- 8. Study the Bottle filling process using PLC
- 9. Conduct the cylinder sequencing using simple pneumatic direct control valve.
- 10. Write ladder logic program for the traffic light controller using PLC
- 11. Conduct the special I/O for speed control of DC motor using PLC.
- 12. Programming in HMI and SCADA.

13.05.2020 Regulations-2015R

Total Hours: 60 Hrs

| U15MC507R | | MINI PROJECT-I | L | Т | P | С | | | | | |
|-----------|--|---|-----------|-------|---|---|--|--|--|--|--|
| | | | 0 | 0 | 2 | 1 | | | | | |
| Course | Course Outcomes | | | | | | | | | | |
| After s | uccessful c | ompletion of this course, the students shou | ıld be ab | le to | | | | | | | |
| CO1: | Frame a real world problem, identify the requirement and develop the design solutions. Express the technical ideas, strategies and methodologies. | | | | | | | | | | |
| CO2: | Apply the new tools, algorithms, techniques that contribute to obtain the solution of the | | | | | | | | | | |
| CO3: | Prepare re | port and present the oral demonstrations. | | | | | | | | | |
| | CO/PO, PSO Mapping | | | | | | | | | | |
| | (3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak | | | | | | | | | | |

| | | Programme Outcomes (POs) and Programme Specific Outcome (PSOs) | | | | | | | | | | | | |
|-----|----|--|-----|-----|-----|-----|-----|-------|-----|------|-----|-----|------|------|
| COs | РО | РО | DO3 | PO4 | PO5 | DO6 | PO7 | PO8 | P09 | PO10 | PO1 | PO1 | PSO1 | PSO2 |
| | 1 | 2 | PO3 | PU4 | PU3 | PO6 | PU/ | F 0 6 | F09 | 1010 | 1 | 2 | F301 | F302 |
| CO1 | 3 | 3 | 3 | 2 | 1 | 2 | 2 | 2 | 2 | 2 | 1 | 1 | 3 | 2 |
| CO2 | 3 | 3 | 3 | 3 | 3 | 2 | 2 | 2 | 2 | 2 | 3 | 3 | 3 | 2 |
| CO3 | 3 | 2 | 2 | 2 | 2 | 2 | 3 | 3 | 3 | 3 | 1 | 1 | 3 | 2 |

Course Assessment methods

| Direct | Indirect | |
|---------------------------|--------------------------|-------------------|
| Review- I (10 marks) | End semester Examination | Course end survey |
| Review- II (10 marks) | (50 marks) | |
| Review- III (10 marks) | | |
| Project report (20 marks) | | |

- 1. The students formed into a team of convenient groups of not more than 4 members on a project are not allowed to change their team members.
- 2. Every project team should report to their faculty guide for discussion from the day of beginning of 5th semester.
- 3. The group has to analyze the selected problem addressed in their project work to draw solution.
- 4. A project report has to be submitted by each student group at the end of the 5^{th} semester.
- **5.** Three reviews have to be conducted by a team of faculty (minimum of 1 and maximum of 2) along with their faculty guide as a member of faculty team (for monitoring the progress of project planning and implementation).

| U15MC901R | Professional Elective 1 CONTROL SYSTEMS | L | Т | Р | С | | | | | |
|--|---|---|---|---|---|--|--|--|--|--|
| | CONTROL STSTEMS | 3 | 0 | 0 | 3 | | | | | |
| Course Outcomes | | | | | | | | | | |
| After an acceptul completion of this course the students should be able to | | | | | | | | | | |

After successful completion of this course, the students should be able to CO1: Derive the transfer function of a given system using mathematical models CO2: Determine the time response of systems and analyse the steady state error CO3: Calculate the frequency domain specifications using frequency response plots. CO4: Determine and analyse the stability of given system.

betermine and unaryse the stability of given system

CO5: Solve the state equations using state space model.

Pre-requisite

- 1. Electrical machines and drives
- 2. Engineering mathematics

CO/PO, PSO Mapping

(3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak

| | | Programme Outcomes (POs) and Programme Specific Outcome (PSOs) | | | | | | | | | | | | |
|-----|-----|--|-----|-----|-----|-----|-----|-----|-------|----|----|----|-----|-----|
| COs | DO1 | PO2 | PO3 | DO4 | PO5 | PO6 | PO7 | PO8 | P09 | РО | РО | РО | PSO | PSO |
| | PO1 | PUZ | 103 | PO4 | PU3 | 100 | 107 | F08 | F 0 9 | 10 | 11 | 12 | 1 | 2 |
| CO1 | 3 | 3 | 3 | 2 | 1 | 1 | 2 | 1 | | 2 | | | 3 | 2 |
| CO2 | 3 | 3 | 3 | 2 | 1 | 1 | 2 | 1 | | 2 | | | 3 | 2 |
| CO3 | 3 | 3 | 3 | 2 | 1 | 1 | 2 | 1 | | 2 | | | 3 | 2 |
| CO4 | 3 | 3 | 3 | 2 | 1 | 1 | 2 | 1 | | 2 | | | 3 | 2 |
| CO5 | 3 | 3 | 3 | 2 | 1 | 1 | 2 | 1 | | 2 | | | 3 | 2 |

Course Assessment methods

| | Direct | Indirect |
|-----------------------|-------------------------------|-------------------|
| Internal test I (6) | Seminar/ Assignment (5) | Course end survey |
| Internal test II (6) | Moodle test (7) | |
| Internal test III (6) | Attendance (5) | |
| Assignment (5) | End semester Examination (60) | |

UNIT I FUNDAMENTAL LAWS OF ELECTRICAL ENGINEERING AND CIRCUIT ELEMENTS 9 Hours

Introduction – types of control systems-linear – non-linear – continuous discrete – open loop and closed loop systems – mathematical model of control systems – transfer functions – mechanical translational system –mechanical rotational systems – electrical analogous of mechanical systems – transfer function of field controlled DC motor – block diagram algebra – signal flow graph – Mason's gain formula – transfer function of armature controlled DC motor.

UNIT II TIME RESPONSE ANALYSIS

9 Hours

Time response – standard test signals – type and order of control system – time response of first order system for unit step, unit ramp and impulse input – time response of second order system for unit step input – time domain specifications – steady state error and static error constants – generalized error coefficients –correlation between static and dynamic error coefficients – controllers: P, PI and PID – Tuning methods.

UNIT III FREQUENCY RESPONSE ANALYSIS

9 Hours

Frequency response – frequency domain specifications – correlation between time and frequency response –frequency response plots – polar plot – bode plot.

UNIT IV STABILITY ANALYSIS

9 Hours

The concepts of stability – necessary conditions for stability –relative stability – Routh Hurwitz stability criterion – root locus – effect of addition of poles – effect of addition of zeros.

UNIT V COMPENSATORS AND STATE SPACE ANALYSIS

9 Hours

Compensators: introduction – types – lag, lead and lag-lead (qualitative treatment only). State space analysis: concepts of state, state variables and state model for linear continuous time systems –

state space representation using physical variable and phase variable method – solution of state equation using Laplace transform method.

Text Books

- 1. I.J.Nagrath and M.Gopal, "Control Systems Engineering", 5th Edition, New Age International (P) Ltd, Publishers, 2006.
- 2. Samarajit Gosh, "Control Systems Theory and Applications", Second edition, Pearson publications, 2012.

REFERENCES

- 1. M.Gopal, "Control Systems, Principles and Design", Fourth Edition, Tata McGraw Hill, New Delhi, 2012.
- 2. A.Nagoorkani, "Control Systems Engineering", First edition, RBA Publications, 2010.
- 3. S.Palani, "Control Systems Engineering", Second Edition, Tata McGraw Hill, 2010.
- 4. B. C. Kuo, "Automatic Control Systems", John wiley and sons, 8th edition, 2003.

| U15MC902R | | Professional Elective 1 | L | Т | Р | С | | |
|-----------|--|---|---------|---------|---|---|--|--|
| | | INDUSTRIAL DRIVES | 3 | 0 | 0 | 3 | | |
| Course | Course Outcomes | | | | | | | |
| After s | uccessful | completion of this course, the students sho | ould be | able to | | | | |
| CO1: | Analyze the behaviour of power converter for dc drives. | | | | | | | |
| CO2: | Explain the principles of operation of induction motor drives. | | | | | | | |

CO3: Analyze the working principles of Synchronous motor drives.

CO4: Analyze and operating principle of Permanent magnet motor drives.

CO5: Explain the principles of operations of Switched reluctance motor drives.

Pre-requisite

Electrical machines and drives

CO/PO, PSO Mapping

(3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak

| | | Progr | amme | Outc | omes (| POs) | and P | rogra | mme S | pecifi | c Out | come | (PSOs |) |
|-----|-----|----------|------|------|--------|------|-------|-------|----------|--------|-------|------|-------|------|
| COs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | РО | РО | РО | PSO1 | PSO2 |
| | POI | 71 PO2 | PU3 | 104 | PU3 | 100 | 107 | 100 | 76 709 | 10 | 11 | 12 | P301 | P302 |
| CO1 | 3 | 3 | 3 | 2 | 1 | 1 | 2 | 1 | 1 | 2 | 1 | 1 | 3 | 2 |
| CO2 | 3 | 3 | 3 | 2 | 1 | 1 | 2 | 1 | 1 | 2 | 1 | 1 | 3 | 2 |
| CO3 | 3 | 3 | 3 | 2 | 1 | 1 | 2 | 1 | 1 | 2 | 1 | 1 | 3 | 2 |
| CO4 | 3 | 3 | 3 | 2 | 1 | 1 | 2 | 1 | 1 | 2 | 1 | 1 | 3 | 2 |
| CO5 | 3 | 3 | 3 | 2 | 1 | 1 | 2 | 1 | 1 | 2 | 1 | 1 | 3 | 2 |

Course Assessment methods

| | Direct | Indirect |
|-----------------------|-------------------------------|-------------------|
| Internal test I (6) | Seminar/ Assignment (5) | Course end survey |
| Internal test II (6) | Moodle test (7) | |
| Internal test III (6) | Attendance (5) | |
| Assignment (5) | End semester Examination (60) | |

UNIT I POWER CONVERTERS FOR DC DRIVES

9 Hours

single phase converter fed D.C motor drive. -Class A, B, C, D and E chopper-controlled DC motor. - Drive employing dual converter fed DC motor drive. Drive circuits for stepper motor.

UNIT II INDUCTION MOTOR DRIVES

9 Hours

Solid state controllers for Stator voltage control, Rotor side speed control of wound rotor induction motors. Voltage source and Current source inverter fed induction motor drives -voltage fed inverter control-v/f control.

UNIT III SYNCHRONOUS MOTOR DRIVES

9 Hours

Modelling of synchronous machines, open loop v/f control, vector control, direct torque control, CSI fed synchronous motor drives.

UNIT IV PERMANENT MAGNET MOTOR DRIVES

9 Hours

Introduction to various PM motors, BLDC and PMSM drive configuration, comparison, block diagrams, Speed and torque control in BLDC and PMSM.

9 Hours

Evolution of switched reluctance motors, various topologies for SRM drives, comparison, Closed loop speed and torque control of SRM.

| The | eory: 45 Hrs | Tutorial: | Practical: Hr | Total Hours: 45 Hrs | | | | | | |
|------|--|-------------------------|-----------------------------|-----------------------------|--|--|--|--|--|--|
| Text | Books | | | | | | | | | |
| 1. | B. K. Bose, "Modern Power Electronics and AC Drives", Pearson Education, Asia, 2003. | | | | | | | | | |
| 2. | V Subramanyam , " Thyristor control of Electric Drives ", Tata Mcgraw hill, 2012 | | | | | | | | | |
| | • | | | | | | | | | |
| REFE | RENCES | | | | | | | | | |
| 1. | P. C. Krause, | O. Wasynczuk and S. D | O. Sudhoff, "Analysis of El | ectric Machinery and Drive | | | | | | |
| | Systems", Johr | Wiley & Sons, 2013. | | | | | | | | |
| 2. | R. Krishnan, "F | Permanent Magnet Sync | hronous and Brushless DC | motor Drives", CRC press, | | | | | | |
| | 2006. | | | | | | | | | |
| 3. | H. A. Taliyat ar | nd S. G. Campbell, "DSP | based Electromechanical I | Motion Control", CRC press, | | | | | | |
| | 2003. | | | | | | | | | |
| 4. | R. Krishnan, " | Switched Reluctance Mo | otor Drives: Modeling, Sir | mulation, Analysis, Design | | | | | | |
| | and Application | ıs", CRC press, 2006. | | | | | | | | |

| U15MC903R | Professional Elective 1 | L | Т | P | С |
|-----------|-------------------------|---|---|---|---|
| 015MC903K | ADDITIVE MANUFACTURING | 3 | 0 | 0 | 3 |

Course Outcomes

| Course C | Course Outcomes | | | | | | | |
|--|---|--|--|--|--|--|--|--|
| After successful completion of this course, the students should be able to | | | | | | | | |
| CO1: | Explain steps involved in Rapid tooling and Addictive manufacturing. | | | | | | | |
| CO2: | Discuss various fabrication & modelling techniques. | | | | | | | |
| CO3: | Analyse the working principle of various precision instruments based on laser, Electron beam machine. | | | | | | | |
| CO4: | Describe the concept of 3D printing, Direct and Indirect tooling techniques. | | | | | | | |
| CO5: | Identify the suitable AM process to fabricate metallic components through reverse engineering. | | | | | | | |

Pre-requisite

- 1. Engineering Physics
- 2. Manufacturing Technology

CO/PO, PSO Mapping

(3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak

| | | | | | | | | , | <u>J.</u> | | • | | | |
|-----|--|-----|-----|-----|-----|-----|-----|-----|-----------|------|------|------|------|------|
| COs | Programme Outcomes (POs) and Programme Specific Outcome (PSOs) | | | | | | | | | | | | | |
| COS | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | PO10 | PO11 | PO12 | PSO1 | PSO2 |
| CO1 | 3 | 3 | 3 | | 3 | | | | | | | | 3 | 3 |
| CO2 | 3 | 3 | 3 | | 3 | | | | | | | | 3 | 3 |
| CO3 | 3 | 3 | 3 | | 3 | | | | | | | | 3 | 3 |
| CO4 | 3 | 3 | 3 | | 3 | | | | | | | | 3 | 3 |
| CO5 | 3 | 3 | 3 | | 3 | | | | | | | | 3 | 3 |

Course Assessment methods

| | Direct | | | | | |
|-----------------------------|-------------------------------------|-------------------|--|--|--|--|
| Internal test I (6 marks) | Seminar/ Assignment (5 marks) | | | | | |
| Internal test II (6 marks) | Moodle test (7 marks) | Course and survey | | | | |
| Internal test III (6 marks) | Attendance (5 marks) | Course end survey | | | | |
| Assignment (5 marks) | End semester Examination (60 marks) | | | | | |
| | • | | | | | |

UNIT I INTRODUCTION

9 Hours

Needs - Impact of AM and Rapid Tooling on Product Development - Distinction between AM and CNC Machining- The Generalized AM Process chain - CAD Model - Input file formats - Generation and Conversion of STL file - File Verification and Repair - Build File Creation - Part Construction - Part Cleaning and finishing - RP Benefits - Classification of RP systems

UNIT II LIQUID POLYMER AND SOLID BASED SYSTEMS

9 Hours

Stereo lithography Apparatus (SLA), Digital Light Projection (DLP), Photo polymerization process, Solid Ground Curing (SGC), Fused Deposition Modeling (FDM) and Laminated Object Manufacturing (LOM) - Working Principle, Construction, Materials and Applications.

UNIT III POWDER BASED SYSTEMS

9 Hours

Selective Laser Sintering (SLS), Three-dimensional Printing (3DP), Direct Metal Deposition (DMD), Ballistic Particle Manufacturing (BPM), Electron Beam Melting (EBM) and Laser Engineered Net Shaping (LENS)- Working Principle, Construction, Process Variables, Materials and Applications

UNIT IV OPEN SOURCE PRINTER AND RAPID TOOLING

9 Hours

Concept of open source 3D printer - Structural details, Control mechanism - Materials and Applications. Introduction to rapid tooling (RT) - Direct and Indirect tooling - Silicone rubber moulding, Epoxy tooling, Spray Metal Coating, 3D printing direct, 3D Metal printing, Electro Optical Sintering (EOS) - Working Principle, Materials and Applications

UNIT V REVERSE ENGINEERING AND APPLICATIONS OF ADDITIVE MANUFACTURING

9 Hours

Reverse Engineering - Application of CMM, Laser scanner, CT and MRI scan in acquiring point data - Software for STL file processing. Application of Rapid prototyping in Medical field, Manufacturing, Automotive industries, Aerospace and Electronics and Retail industries. Leading manufacturer of RP systems

| Т | heory: 45 Hrs | Tutorial: | Practical: Hr | | Total Hours: 45 Hrs | | | |
|----|---|-----------|--|------------|---------------------|--|--|--|
| | Text Books | | | | | | | |
| 1. | 1. C. K. Chua, K. F. Leong and C. S. Lim, Rapid prototyping: Principles and applications, Cambridge University Press, 2010. | | | | | | | |
| 2. | D. T.Pham and S. S.Dimov, Rapid manufacturing, Springer-Verlag, London, 2001. | | | | | | | |
| | REFERENCES | | | | | | | |
| 1. | I. Gibson, D. W. Ros Prototyping to Direct | • | er, Additive Manufacto curing, Springer, 2010 | - | nodologies: Rapid | | | |
| 2. | L.W. Liou, F.W. Liou, prototype developme | | | plications | : A toolbox for | | | |
| 3. | 3. A. K. Kamrani, E. A. Nasr, Rapid Prototyping: Theory and practice, Springer, 2006 | | | | | | | |

| Semester -V | U15 GE 50 | DIR:SOFT SKILLS AND APTITUDE - III | L T P C Marks 0 0 2 1 100 | | | | | |
|-----------------------------------|----------------|---|---------------------------|--|--|--|--|--|
| Course Outcomes At the end of the | | tudent will be able to: | | | | | | |
| | | supplementary areas of soft-skills and job-rel- study approaches | lated selection processes | | | | | |
| 2. Solve problem | s of advance | d levels than those in SSA-II in specified areas core 70-75% marks in company-specific interna | s of quantitative aptitud | | | | | |
| 3. Demonstrate g | greater than S | SSA-II level of verbal aptitude skills in Engli arks in company-specific internal tests | | | | | | |
| | | Demonstrating soft-skill capabilities with | reference to the | | | | | |
| | | following topics: | | | | | | |
| | | | | | | | | |
| | | a. Career planning | | | | | | |
| 1.Soft Skills | | b. Resume writing | | | | | | |
| 1.501t Skills | | c. Group discussion | | | | | | |
| | | d. Teamwork | | | | | | |
| | | e. Leadership skills f. Interview skills | | | | | | |
| | | g. Mock interview | | | | | | |
| | | h. Mock GDs | | | | | | |
| | | Solving problems with reference to the fol | llowing topics : | | | | | |
| | | N 1 P 11 | | | | | | |
| | | a. Numbers: Remainder concept | C.: | | | | | |
| | | b. Time and work: Fraction technique, Eff and cisterns and Chain rule | iciency technique, Pipe | | | | | |
| 2.Quantitative Ap | otitude | c. Simple interest | | | | | | |
| | | d. Compound interest | | | | | | |
| and | | e. Set theory: Venn diagram | | | | | | |
| Logical Reasoning | a Topics | f. Puzzles | | | | | | |
| Logical Reasoning | g ropics | g. Mathematical operators | | | | | | |
| | | h. Syllogism (≥4 Statements) | | | | | | |
| | | i. Data sufficiencyj. Statement and assumptions | | | | | | |
| | | j. Statement and assumptions k. Statement and conclusions | | | | | | |
| | | Company specific aptitude questions | | | | | | |
| | | Demonstrating English language skills with | th reference to the | | | | | |
| | | following topics: | | | | | | |
| | | a. Subject verb agreement | | | | | | |
| | | b. Selecting the best alternative for the state | ed parts of given | | | | | |
| 3. Verbal Aptitud | e | sentences | - Farm or Briver | | | | | |
| | | c. Reading comprehension | | | | | | |
| | | d. Contextual synonyms | | | | | | |
| | | e. Sentence fillers | | | | | | |
| | | f. Writing a story for a given picture | | | | | | |
| | | g. Company specific aptitude questions | | | | | | |

Department of Placement Training

Sona College of Technology, Salem

(An Autonomous Institution)

Courses of Study for B.E/B.Tech. Semester VI under Regulations 2015R (CBCS)

Branch: Mechatronics Engineering

| S. No | Course Code | Course Title | | | Tutorial | Practical | Credit |
|-------|--------------------|-------------------------------|---|---|----------|-----------|--------|
| | l | L | Theory | | | | |
| 1 | U15MC601R | Python programming | | 3 | 0 | 0 | 3 |
| 2 | U15MC602R | Power Electronics | | 3 | 0 | 2 | 4 |
| 3 | U15MC603R | Automotive Electronics | | 3 | 0 | 0 | 3 |
| 4 | U15MC604R | Artificial Intelligence | | 3 | 0 | 0 | 3 |
| 5 | noc21-me55 | Professional Elective: | Principles of Mechanical Measurement | 3 | 0 | 0 | 3 |
| | noc21-ee05 (NPTEL) | | Control Engineering | 3 | <u> </u> | U | 3 |
| | U15CE1004R | | Municipal Solid Waste Management | | | | |
| | U15EE1001R | | Electric Mobility | | 0 | 0 | |
| | U15EE1006R | | Renewable Energy Systems | | | | |
| | U15FT1001R | | Fundamentals of Fashion Design | | | | |
| 6 | U15IT1003R | Open Elective | Problem solving Techniques Using Java Programming | 3 | | | 3 |
| | U15IT1005R | | Introduction to Database Technology | 1 | | | |
| | U15ME1002R | | Renewable Energy Sources | 1 | | | |
| | U15ME1004R | | Industrial Safety | 1 | | | |

| | | Practical | | | | |
|----|------------|---------------------------------|---|---|---------------|----|
| 7 | U15MC605R | Python Programming Laboratory | 0 | 0 | 4 | 2 |
| 8 | U15ENG601R | Communication Skills Laboratory | 0 | 0 | 2 | 1 |
| 9 | U15MC606R | Mini Project-II | 0 | 0 | 2 | 1 |
| 10 | U15GE601BR | Soft Skill and Aptitude – IV | 0 | 0 | 2 | 1 |
| | | | | | Total Credits | 24 |

Approved By

Chairperson, Mechatronics Engineering BoS Dr.P.Suresh

Member Secretary, Academic Council Dr.R.Shivakumar

Chairperson, Academic Council & Principal Dr.S.R.R.Senthil Kumar

Copy to:-

HOD/ Mechatronics Engineering, Sixth Semester BE MCT Students and Staff, COE

| 111 | 5MC60 |)1 P | | | D | ντμο | N PRO |)GRAI | MMTN | G | | L | Т | P | С |
|---------------------|----------|-----------|---------|---------|------------|---------|---------|---------|----------|-------------|---------|----------|----------|-------|-------|
| 01 | Jiicot | , IK | | | • | | II FIX | JUINAI | .11.1714 | J | | 3 | 0 | 0 | 3 |
| Course | Outcom | es | 1 | | | | | | | | | | <u> </u> | | |
| After su | ccessfu | l comple | etion o | f this | course | , the s | studen | ts sho | uld be | able to | | | | | |
| CO1: | Wri | te the lo | gic in | the fo | rm of | algorit | :hm an | ıd pseı | ndo co | de. | | | | | |
| CO2: | Illu | strate th | ne basi | c cond | epts o | f pyth | on pro | gramr | ning. | | | | | | |
| CO3: | Des | ign and | devel | op the | vario | us data | a struc | tures | using | python. | | | | | |
| CO4: | | ly excep | | | | | | | | | using p | ython. | | | |
| CO5: | | ve the p | roblen | ns usir | ng adv | anced | conce | pts in | pytho | า. | | | | | |
| Pre-requ | | | | | | | | | | | | | | | |
| | Prog | rammin | g in C | | | | | | | | | | | | |
| | | | | | | | | | | | | | | | |
| | | (2/2/4 | | | | |), PSO | | _ | - 2 M- | J: 4 | \A/ I - | | | |
| | | • | | | | | | | | g, 2-Med | | | 200) | | |
| COs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | | PO8 | P09 | PO10 | PO11 | ome (PS | | D | SO2 |
| CO1 | 3 | 3 | 3 | 3 | 1 | 1 | 1 | 2 | 2 | 2 | 1 | 3 | 3 | Ρ. | 3 |
| CO2 | 3 | 3 | 2 | 3 | 3 | 1 | 1 | 1 | 3 | 1 | 1 | 3 | 3 | | 3 |
| CO3 | 3 | 3 | 3 | 3 | 3 | 1 | 1 | 3 | 3 | 2 | 1 | 3 | 3 | | 3 |
| CO4 | 3 | 3 | 3 | 3 | 3 | 1 | 1 | 3 | 3 | 2 | 1 | 3 | 3 | | 3 |
| CO5 | 3 | 3 | 3 | 3 | 3 | 1 | 1 | 3 | 3 | 2 | 1 | 3 | 3 | | 3 |
| | | | | | | _ | _ | | | | _ | | | | |
| | | | | | Cou | rse As | sessm | ent m | ethods | | | | | | |
| | | | | | Direct | - | | | | | | | Indire | ct | |
| Internal | test I (| 6 marks | s) | | Semir | ar/ As | ssignm | ent (5 | mark | s) | | | | | |
| Internal | | - | - | | | | (7 ma | - | | | | Cours | se end | surv | ev |
| Internal | | • | ks) | | | | (5 mai | • | | | | Cours | oc ciia | Jul V | C y |
| Assignm | | | | | End | semes | ster Ex | amina | tion (| 60 mark | | | | | |
| Unit 01: | | | | | | | | | | | | Hours | | | |
| Introduc | | _ | - | | _ | | • | | | - | | | | | |
| Decision Program | | | | | | | _ | | | | | - | | | |
| Implicit/ | _ | | | - | 4111111111 | g lair | guage | : V | ariabi | es and | Data | types | Ор | Cracc | 113 |
| Unit 02: | | | | | vthon | | | | | | 9 1 | Hours | | | |
| Control | | | | | · | | res - | Iterati | on Co | ntrol S | | | it Test | ing: | Path |
| Coverag | | | | | | | | | | | | • | | _ | |
| Argume | | | | | | | | | | | | | | | |
| Unit 03: | Data S | tructure | s in P | thon | | | | | | | 9 H | Hours | | | |
| Collection | ns: Lis | t, Array | , Tuple | , Strir | ng, Set | , Dicti | onary, | Types | of ar | gument | s, Vari | ables ar | nd its s | cope | |
| Unit 04: | | | | | | | | | | | | Hours | | - | |
| Exception | n Hand | lling - M | odules | and I | Packag | es - L | ibrarie | s and | Functi | ons, File | e Hand | ling | | | |
| Unit 05: | | | | | | | | | | • | 1 | Hours | | | |
| | | sions, (| | rrency | , Lam | bda fı | unction | ns, Hig | her C | Order fu | ınction | s, Scier | ntific C | omp | uting |
| | | | | | py Arr | | | | | | | | | | |

Practical: --

Total Hours: 45 Hrs

Tutorial: --

Theory: 45 Hrs

| | Text Books |
|----|--|
| 1. | Ashok Namdev Kamthane (Author), Amit Ashok Kamthane "Programming and Problem |
| | Solving with Python" McGraw-Hill Education, 2018 |
| 2. | Swaroop C N, " A Byte of Python ", ebshelf Inc., 1 st Edition, 2013 |
| | REFERENCES |
| 1. | Wesley J. Chun, "Core Python Programming", Pearson, 2nd Edition, 2006 |
| 2. | Allen B.Downey, "Think Python: How to Think Like a Computer Scientist", O'Reilly Media, 2 nd |
| | Edition, 2015 |

| U1 | .5MC | 502R | | | POWE | R ELE | CTRON | ICS | | | L | Т | Р | С |
|--------|---|--|----------|-----------|----------|----------|----------|----------|--|----------|---------|-----------|--------|---------|
| | | | | | | | | | | | 3 | 0 | 2 | 4 |
| | | comes | | | | | | | | | | | | |
| After | After successful completion of this course, the students should be able to CO1: Explain different types of power semiconductor devices and their VI and switching | | | | | | | | | | | | | |
| CO1: | | plain d aracteri | | | • | | emicor | ductor | device | es and | their | VI ar | nd swi | tching |
| CO2: | | ustrate | | | | | cs and | perfor | mance | param | eters o | of single | e phas | e and |
| CO3: | | three phase controlled converters. Classify different types of chopper and to analyse the operation of choppers with relevant | | | | | | | | | | | | |
| | m | mode waveforms. List various types of inverter and Explain the operation of single phase and three phase | | | | | | | | | | | | |
| CO4: | | | | | | | | | | | | | three | phase |
| CO5: | | | | | | | | | | | | | | |
| Duo u | control techniques and Summarise the operation of cycloconverters | | | | | | | | | | | | | |
| | Pre-requisite Electron Devices and Circuits | | | | | | | | | | | | | |
| EI | ectror | Device | s and C | ircuits | | | | | | | | | | |
| | | | | | | CO/PO | , PSO N | 1apping | 1 | | | | | |
| | | (3, | /2/1 inc | dicates | strengt | h of cor | relatio | 1) 3-St | rong, 2 | -Mediu | m, 1-W | eak | | |
| COs | Programme Outcomes (POs) and Programme Specific Outcome (PSOs) | | | | | | | | | | | | | |
| | PO1 | PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PSO1 PSO2 | | | | | | | | | | | PSO2 | |
| CO1 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | | | 3 | 2 |
| CO2 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | | | 3 | 2 |
| CO3 | 3 | 2 | 3 | 2 | | | 2 | | | 2 | | | 3 | 2 |
| CO4 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | | | 3 | 2 |
| CO5 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | | | 3 | 2 |
| | | | | | Cou | irse Ass | sessme | nt meth | nods | | | | | |
| | | | | D | irect | | | | | | | Indire | ct | |
| Inter | nal tes | st I (6 m | arks) | Ser | ninar/ / | Assignm | nent (5 | marks) |) | | Cour | se end | survey | |
| | | st II (6 r | - | | | t (7 ma | - | | | | | | | |
| | | st III (6 | - | | | e (5 ma | - | n (60) | ,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,, | | | | | |
| Unit (| | t (5 mar | er Semi | | | ter Exa | IIIIIIau | טט) ווכ | marks) | | 9+6 | Hours | | |
| | | and Sw | | | | | var dia | dec SC | D RIT | MOSE | | | | |
| Firing | and (| Gating c OSFET. | | | | | | | | | | | | |
| Unit (| | | e-Contr | olled C | onverte | rs | | | | | 9+6 | Hours | | |
| | | se half v | | | | | r - hal | f contro | olled br | ridge co | | | | trolled |
| bridg | e con | verter wower fac | ith R,R | | | | | | | | | | | |
| | Three phase full bridge converter – Half controlled and fully controlled converter with R, RL Load – Estimation of average & RMS values of load voltage, load current for R load. | | | | | | | | | | | | | |
| Unit (| 03: | DC to | DC Co | nverte | r | | | | | | 9+6 | Hours | | |
| Contr | ol str | pers : Prategies d load c | - Class | sificatio | n & op | | | | | | | | | |
| Unit (| 04: | Inve | rters | | | | | | | | 9+6 | Hours | | |

Types of inverters – operation of Single phase and three phase (120° , 180°) voltage source inverter modes analysis with star connected R load – operation of single phase current source inverter – series inverters – parallel inverter – Voltage control of Single phase inverters – harmonic reduction techniques and filters

Unit 05: AC to AC Converters 9+6 Hours

AC Voltage Controllers: Single phase voltage regulators – half wave and full wave with R, RL loads – sequence control of AC regulators – two stage sequence regulator with R, RL load – Multistage sequential control of AC regulators – Introduction to Three phase regulators (no analysis).

Cycloconverters: Single phase to single phase cycloconverter – three phase to single phase and three phase to three phase cycloconverters.

| Tł | neory: 45 Hrs | Tutorial: | Practical: 30 Hrs | Total Hours: 75 Hrs | | | | | | |
|---|-------------------------------------|--|---|------------------------------|--|--|--|--|--|--|
| Text B | Text Books | | | | | | | | | |
| 1. | M.H. Rashid, 'Pow edition, 2018. | er Electronics: Circ | uits, Devices and Applications', | Pearson India, fourth | | | | | | |
| 2. | P.S.Bimbra "Powe | er Electronics" Khan | na Publishers, third Edition 200 | 03. | | | | | | |
| REFER | ENCES | | | | | | | | | |
| 1. | Singh.M.D.&Khan New Delhi 2016. | chandani.K.B. Powe | er Electronics Mcgraw Educati | on (India) Private limited, | | | | | | |
| 2. | | . M.Undeland, Willia Wiley and sons, th | m.P.Robbins, 'Power Electronic ird edition, 2003. | cs: Converters, applications | | | | | | |
| 3. Philip T. Krien, "Power Electronics' Oxford University Press, 2012. | | | | | | | | | | |
| 4. Daniel.W.Hart, "Power Electronics", Indian Edition, McGraw Hill, 3 rd Print, 2013. | | | | | | | | | | |

| U1 | 5MC | 503R | | | AUTO | моті | VE ELI | ECTRO | NICS | | L | | Т | P | С |
|--------|--------------|--|---------------------------|----------|---------|---------|----------|----------|----------|----------|----------|---------|--------|------|---------|
| | | | | | | | | | 3 | ; (| 0 | 0 | 3 | | |
| Cours | rse Outcomes | | | | | | | | | | | • | | | |
| After | succe | ccessful completion of this course, the students should be able to | | | | | | | | | | | | | |
| CO1: | De | elibera | te the | various | types | of ser | nsors a | nd mic | roproce | ssor app | olicatio | n in au | itomob | iles | |
| CO2: | De | emons | rate t | he engi | ne con | trol sy | stems | | | | | | | | |
| CO3: | Ar | Analyze the electronic management systems used in auto motives. | | | | | | | | | | | | | |
| CO4: | In | vestiga | ate the | e hydra | aulic a | ctuatio | on sys | tem, V | ehicles | lighting | Circu | its and | electi | ic | windows |
| | sy | stems | ı | - | | | | | | | | | | | |
| CO5: | Ex | amine | the v | arious a | pplica | tions e | electro | nic cont | rol syst | tems us | ed in a | iuto mo | tives. | | |
| Pre-re | equisi | te | | | | | | | | | | | | | |
| Ва | sic E | lectrica | l and | Mechan | ical Er | nginee | ring | | | | | | | | |
| | | | | | | CC | D/PO, I | PSO Ma | pping | | | | | | |
| | | (| 3/2/1 | indicate | es stre | ngth c | of corre | elation) | 3-Stro | ng, 2-Me | edium, | 1-Wea | ık | | |
| COs | | Programme Outcomes (POs) and Programme Specific Outcome (PSOs) | | | | | | | | | | | | | |
| | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | PO10 | PO11 | PO12 | PSO: | - | PSO2 |
| CO1 | 3 | 3 | 3 3 2 1 2 2 2 1 1 1 2 3 2 | | | | | | | | | | | | |
| CO2 | 3 | 3 | 3 | 2 | 1 | 2 | 2 | 2 | 1 | 1 | 1 | 2 | 3 | | 2 |

Course Assessment methods

| | Direct | Indirect |
|-----------------------------|-------------------------------|-------------------|
| Internal test I (6 marks) | Seminar/ Assignment (5 marks) | Course end survey |
| Internal test II (6 marks) | Moodle test (7 marks) | |
| Internal test III (6 marks) | Attendance (5 marks) | |
| Assignment (5 marks) | End semester Examination (60 | |
| | marks) | |

Unit 01: Fundamentals of Automotive Electronics

9 Hours

Basic sensor arrangement – Types of sensors. Oxygen Sensor – Cranking Sensor – Position Sensors – Engine cooling water temperature Sensor – Engine oil pressure Sensor – Fuel metering – Vehicle speed sensor and detonation sensor – Stepper motors – Relays, solenoids - Microprocessor and Micro Computer applications in automobiles.

Unit 02: Engine Management Systems

CO3

CO4

CO5

9 Hours

Introduction - components for engine management system - Open loop and closed loop control system - Engine cranking and warm up control - Acceleration, deceleration and idle speed control-Integrated engine system - Feedback carburetor system - Throttle body injection and multi point fuel injection system- Advantage of electronic ignition systems - Types of solid state ignition systems and their principles of operation - Electronic spark timing control.

Unit 03: Electronic Management Systems

9 Hours

Introduction-Electronic management of chassis systems, Vehicle motion control, anti - lock braking system, Tyre pressure monitoring system, Collision avoidance system, Traction control system, Active suspension system, Key less entry system and Electronic power steering system.

Unit 04: Electronics Actuators

9 Hours

Wiper system, flasher, electric fuel pump, hydraulic actuation system, Brake Actuation Warning

System. Traficators, Flash System, Windshield Wiper, Starting Systems – Charging Systems – climate control and electronic displays, Vehicles lighting Circuits Signaling Circuit, electric windows systems, seat belt tensioners.

Unit 05: Electronics Control Systems

9 Hours

Introduction of Control Systems - Automatic Cabin climate control, Automatic Cruise Control, Air Bag Control, ABS Control, Automatic Transmission Control, Electronic steering Control, Automatic gear control, Electric Power Steering, Electronic Distributor-less ignition control, Electronic Fuel Control Exhaust emission control, Electronic Clutch Control, Automotive central locking and anti-theft system control.

| COLLEG | 11 | | | | | | | | | | |
|--------|---|---------------------|-------------------------------|--------------------------------|--|--|--|--|--|--|--|
| Th | neory: 45 Hrs | Tutorial: | Practical: Hr | Total Hours: 45 Hrs | | | | | | | |
| Text B | Text Books | | | | | | | | | | |
| 1. | William Ribbens, | Understanding Aut | tomotive Electronics, Newne | s Publishers, India, 2013. | | | | | | | |
| 2. | 2. U.Kiencke, and L. Nielson, "Automotive Control Systems", Springer Verlag Berlin, 2000 | | | | | | | | | | |
| 3. | Jiri Marek, Hans Edition (Wiley -VO | • | ers Applications, Sensers f | or Automotive Technology', 1st | | | | | | | |
| 4. | Bechfold, Underst | anding Automotiv | e electronics, SAE, 1998. | | | | | | | | |
| REFER | ENCES | | | | | | | | | | |
| 1. | Robert Bosch, "Au | utomotive Handbo | ok" SAE, 2003. | | | | | | | | |
| 2. | W.F. Walter, Elect | tronic Measuremer | nts", Macmillan Press Ltd., L | ondon. | | | | | | | |
| 3. | E.Dushin, Basic M | letrology and Elect | trical Measurements", MIR P | Publishers, Moscow, 1989. | | | | | | | |
| 4. | 4. Sonde.B.S. "Transducers and Display System", Tata McGraw Hill Publishing Co. Ltd.New Delhi | | | | | | | | | | |
| 5. | 5. Judge.A.W, "Modern Electric Equipments for Automobiles", Chapman and Hall, London. | | | | | | | | | | |

| U15I | MC604R | ARTIFICIAL INTELLIGENCE | L | Т | P | С | | | |
|----------|---|---|----------|----------|-----------|-------|--|--|--|
| | | | 3 | 0 | 0 | 3 | | | |
| Course | Outcomes | | | | | | | | |
| After su | iccessful con | npletion of this course, the students should be able to |) | | | | | | |
| CO1: | Identify an | d design suitable agent program for the given proble | m | | | | | | |
| CO2: | Solve real | time problems using heuristic based algorithms | | | | | | | |
| CO3: | Design logi | cal agent to construct knowledge base and deduce p | roofs th | rough in | ference | rules | | | |
| CO4: | Design decision making agent to explore uncertainties in the problem domain using probabilistic reasoning methods | | | | | | | | |
| CO5: | Solve the p | problems using suitable machine learning algorithm a | nd desig | gn expe | rt syster | ns | | | |
| Pre-req | Pre-requisite | | | | | | | | |

Object Oriented Programming and Data Structures

CO/PO, PSO Mapping

(3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak

| COs | Programme Outcomes (POs) and Programme Specific Outcome (PSOs) | | | | | | | | | | | | | |
|-----|--|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|
| | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | PO10 | PO11 | PO12 | PSO1 | PSO2 |
| CO1 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | 1 | | 3 | 2 |
| CO2 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | 1 | | 3 | 2 |
| CO3 | 3 | 2 | 3 | 2 | | | 2 | | | 2 | 1 | | 3 | 2 |
| CO4 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | 1 | | 3 | 2 |
| CO5 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | 1 | | 3 | 2 |

Course Assessment methods

| | Direct | Indirect |
|-----------------------------|-------------------------------------|-------------------|
| Internal test I (6 marks) | Seminar/ Assignment (5 marks) | |
| Internal test II (6 marks) | Moodletest (7 marks) | Course and curvey |
| Internal test III (6 marks) | Attendance (5 marks) | Course end survey |
| Assignment (5 marks) | End semester Examination (60 marks) | |
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Unit 01: Introduction 9 Hours

The foundations of AI - The History of AI- Intelligent agents- Applications-Problem solving - Problem spaces-Searching techniques-Blind search strategies: Breadth first search-Depth first search-Iterative deepening-Bi-directional search-Comparing search strategies

Unit 02: Problem Solving

9 Hours

Informed/ Heuristic search - A* search - Hill-climbing search- Genetic Algorithm- Markovian Decision Process (MDP) - Maximum value policies, Adversarial games- value/policy iteration - Minimax - Alpha-beta pruning - Temporal difference (TD) - Constraint satisfaction problem - factor graphs - Backtracking search.

Unit 03: Knowledge Representation and Reasoning

9 Hours

Knowledge representation - Logics - First order logic- Inference in first order logic - Higher order logic - Markov logic- Forward and backward chaining- Unification and resolution- Ontological engineering

| Unit 04: | Uncertain knowled | dge and Decision r | making | | | 9 Hours | | | | | | |
|--|--|------------------------|--------------------------|------------|---------------------|--------------|--|--|--|--|--|--|
| Uncerta | Uncertainty-Probabilistic reasoning - Semantics of Bayesian network - Inference in Bayesian network- | | | | | | | | | | | |
| Direct | Direct sampling method - Probabilistic reasoning over time - Hidden Markov Models- Basics of utility | | | | | | | | | | | |
| theory, | theory, sequential decision problems - decision network- policy -Decision process in infinite horizon: | | | | | | | | | | | |
| Optimal policy, Value iteration - policy iteration- Partially observable decision process | | | | | | | | | | | | |
| Unit 05: Learning 9 Hours | | | | | | | | | | | | |
| Learning from observation – Types of learning – Supervised Learning - Unsupervised and | | | | | | | | | | | | |
| | _ | • • | ning- Expert system | | - | | | | | | | |
| Kelliloi | | Thomledge in lean | illig- Expert system. | - Interiac | Le -Language and | toois | | | | | | |
| | | | | | | | | | | | | |
| Theory | ': 45 HrS | Tutorial: | Practical: | | Total Hours: 45 I | HrS | | | | | | |
| Text Bo | ooks | 1 | | ı | | | | | | | | |
| 1 | Stuart Russel | I and Peter Norv | rig, "Artificial Intelli | gence: A | Modern Approac | ch", Pearson | | | | | | |
| 1. | Education, 20 | 14. | | | | | | | | | | |
| 2. | SIA publishers | s, "Artificial Intelli | gence", SIA Publishei | rs and Dis | stributors (P) Ltd, | 2019. | | | | | | |
| 3. | | , "Introduction to | Expert Systems", 3rd | d edition, | AWL, 1999 | | | | | | | |
| REFERE | ENCES | | | | | | | | | | | |
| 1. | David Pool a | nd Alan Mackwor | th, "Artificial Intelli | gence: F | oundations of Co | omputational | | | | | | |
| 1. | agents", Caml | bridge University, | 2011. | | | | | | | | | |
| 2. | Christopher M | .Bishop, "Pattern | Recognition and Mac | hine Lear | ning", Springer, 2 | 013. | | | | | | |
| Nils J. Nilsson, "The Quest for Artificial Intelligence: A History of Ideas and achievements", | | | | | | | | | | | | |
| | Cambridge University Press, 2010. | | | | | | | | | | | |
| 4. | · | | man, "Probabilistic | Graphica | al Models - Pri | nciples and | | | | | | |
| | Techniques", I | MII, 2009 | | | | | | | | | | |

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Principles of Mechanical Measurement

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Course Outline:

Measurement is always of fundamental significance to the practicing engineers. For the development of any mechanical design procedure, experiments are of paramount interest. Accordingly measurement and correct interpretation of the concerned observation are necessary part of any standard engineering task and also R&D. Present course will introduce the students to the fundamentals of measurement, discussing about various relevant concepts & terminologies. The mathematical background required to categorize & analyze various measurement devices will be prepared and a very pertinent discussion on digitalization will be presented. Subsequently several classical and modern procedures for measuring parameters of scientific interest, such as displacement, motion, stress, force, flow, pressure, temperature etc., will be discussed in detail. Measurement is a topic of fundamental interest in engineering and hence any engineering firm & concerned industry should find this course interesting & valuable.

Intended audience

Undergraduate students of Mechanical Engg. and similar branches; Faculty member associated with Mechanical Engg.; Practicing engineers associated with production/manufacturing industries.

Prerequisites:

No specific pre-requisite. Fundamental knowledge of Mechanics and basics of Mathematics should be sufficient.

Course layout:

Week 1: Introduction to Measurement

Week 2: Response of Measurement Systems Week 3: Digital Techniques in Measurement

Week 4: Data Processing

Week 5 : Displacement Measurement Week 6 : Stress and Strain Measurement Week 7 : Force and Torque Measurement

Week 8 : Pressure Measurement
Week 9 : Flow Measurement

Week 10: Temperature Measurement

Week 11: Motion Measurement

Week 12: Special Topics

| Theory | : 45 HrS | Tutorial: | Practical: | Total Hours: 45 HrS | | | | | | | |
|---------------------------|--|-----------|-------------------------------|-----------------------------|--|--|--|--|--|--|--|
| Text and references Books | | | | | | | | | | | |
| 1. | T.G. Beckwith, J.H. Lienhard V & R.D. Marangoni, Mechanical Measurements, Pearson, New Delhi, 2013. | | | | | | | | | | |
| 2. | E.O. Doeblin & D.N. Manik, Measurement Systems, 6th edition, McGraw Hill India Pvt. Ltd., New Delhi, 2013. | | | | | | | | | | |
| 3. | J.P. Holman, Exp Co. Ltd., New Del | | s for Engineers, 7th edition, | Tata McGraw Hill Publishing | | | | | | | |

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|---------|--|--|--|--|------------------------------|----------------------|----------|----------|--|--|--|
| 11002 | 21_6603 | | Contro | l Engineering | 3 | 0 | 0 | 3 | | | |
| Intende | Course Outline: This course shall introduce the fundamentals of modeling and control of linear time invariant systems; primarily from the classical viewpoint of Laplace transforms and a brief emphasis on the state space formulation as well. The course will be useful for students from major streams of engineering to build foundations of time/frequency analysis of systems as well as the feedback control of such systems. The 11th module of the course will cover a detailed application of filter design in the field of navigation and human movement (gait). Students will be able to design their very own basic navigational system using inertial sensors and microcontrollers. Any industry into Industrial Automation Intended audience: Undergraduate students taking course on Control Engineering Prerequisites: Network and Circuits, Basic Engineering Mathematics. | | | | | | | | | | |
| | layout: Week 1: Week 2: Week 3: Week 4: Week 5: Week 6: Week 6: Week 7: Week 8: Week 9: Week 10: Week 11: Week 12: | Matl Lapl Bloc Intro Rood Freq marg Basi Desi Desi Effect State | hematical Modelli ace Transforms, k diagram reduct oduction to stabil t locus plots, stab uency response a gins in frequency cs of control desi ign using Root Lo ign using Bode pl | ng of Systems transfer functions, block diagration, Time response characteris ity, Routh Hurwitz stability critionallysis: Nyquist stability crite domain. ign, the proportional, derivative cus ots num and non-minimum phase s | etics. erion. erion, B | ode ploi tegral a | ts and s | tability | | | |
| | : 45 HrS | Desig | Tutorial: | Practical: | Total F | lours: 4 | 5 HrS | | | | |
| Text Bo | | | | | | | | | | | |
| | Control Syst | | | man S. Nise, Wiley, 6th edition Ihiko Ogata, Pearson Education | | | | | | | |
| | nces Books | | | | | | | | | | |
| 1. | | | | C. Dorf, Robert H. Bishop, 12th | | | | | | | |
| 2. | 2. Automatic Control Systems, Farid Golnaraghi and Benjamin C Kuo, 9th Edition, John Wiley and Sons | | | | | | | | | | |
| 3. | | • | | n for Scientists and Engineers, | | Astrom | and Ric | hard | | | |
| 4. | M.Murray.(h complete_2 | | | .edu/~murray/books/AM05/pd | t/am08 | | | | | | |
| 5. | MATLAB Tut | torials | | | - | | | | | | |

| U15MC605R PYTHON PROGRAMMING LABORATORY | | | | | | | | | L | Т | Р | С | | | | |
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| | | | | | | | | | | | | | 0 | 0 | 4 | 2 |
| Cours | Course Outcomes After successful completion of this course, the students should be able to | | | | | | | | | | | | | | | |
| After | success | sful cor | npletic | n of tl | าis cou | ırse, t | he stu | dents : | should | l be abl | e to | | | | | |
| CO1: | De | velop F | ython | progr | ams to | impl | ement | basic | conce | pts | | | | | | |
| CO2: | | | | | | | | | | oncepts | | | | | | |
| CO3: | | velop F | ython | progr | ams fo | or dat | abase | handlir | ng | | | | | | | |
| | Pre-requisite Pre-requisite | | | | | | | | | | | | | | | |
| P | rogran | ıming i | n C | | | | | | | | | | | | | |
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| COs | DO1 | _ | | | | | | | | | | ome (P | | | | |
| 601 | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | | | P09 | PO10 | PO11 | PO12 | | 01 | | 502 |
| CO1 | 3 | 3 | 3 | 3 | 3 | 1 | 1 | 3 | 3 | 2 | 1 | 3 | | 3 3 | | 3 3 |
| CO2 | 3 | 3 | 3 | 3 | 3 | | | 3 | 3 | 2 | 1 | 3 | | 3 3 | | <u>3</u> |
| CO3 | 3 | 3 | 3 | 3 | 3 | 1 | 1 | 5 | 3 | | 1 | 3 | , | 3 | | 3 |
| | | | | | | ourco | Assess | mont | motho | dc | | | | | | |
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| Mean | of 1 st h | alf of F | - - - - - - - | nant (| | | Quiz on | 2 nd ha | If (5) | | | Course | | | | , |
| | on 1 st h | | -xperii | nenc (| 10) | | nterna | | | | | Course | e en | u su | ıvey | |
| | al test | | | | | | RTPS (1 | | 1 (10) | | | | | | | |
| | of 2 nd I | | Experi | ment (| 10) | | • | , | Exam | ination | (40) | | | | | |
| | Exper | | | | / | | | | | | (. •) | | | | | |
| 1. | | | | aram | to prin | t the | calend | ar of a | aiver | month | and ve | ar. | | | | |
| 2. | | | | | | | | | | en list d | | | | | | |
| 3. | | | | | | | | | | | | m a list | of ı | numl | oers | |
| 4. | | he list | • | | | | <u>'</u> | | <u>′</u> | | | | | | | |
| 5. | | | | | • • | a sin | gle stri | ng fror | n two | given s | trings, | separat | ed b | y a s | spac | e |
| | and s | wap th | e first | two ch | naracte | ers of | each s | tring. | | | | | | | | |
| | Samp | le Strir | ng: 'Py | thon'` | Java', | Outp | ut: Str | ing: <code>`Jy</code> | /thon' | `Pava′ | 1 | | | | | |
| 6. | | | | | | | | _ | | _ | | . (Note: | Par | ngrai | ms a | ire |
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| | | kample | | | | | • | | | | | | | | | |
| 7. | | • | | - | | | | | | exists w | | | | | | |
| 8. | | • | • | _ | _ | | | | | _ | • | last ele | | | | |
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| 10. | | a Pytn wercas | | | ınat ac | cepts | a Strir | iy and | caicul | ate the | numbe | r of upp | erca | ise i | ettel | S |
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| 12. | | | on pro | gram | to com | bine | each li | ne fror | n first | file wit | h the co | rrespor | ndin | g line | e in | |
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| 13. | Write a Python class to find validity of a string of parentheses, '(', ')', '{', '}', '[' and ']. These |
|-----|---|
| | brackets must be close in the correct order, for example "()" and "()[]{}" are valid but "[)", |
| | "({[)]" and "{{{" are invalid. |
| 14. | Write a Python program to execute SQL queries like create, insert, delete, update and select |
| | in any of the database like MySQL, SQLite etc. |
| | Total Hours: 60 Hrs |

| U15MC606R | | MINI PROJECT-II | L | Т | Р | С | | | | |
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| 013 | Picoook | Pilitz PROSECT II | 0 | 0 | 2 | 1 | | | | |
| Course | Outcomes | | | | | | | | | |
| After su | iccessful con | pletion of this course, the students should be able to | | | | | | | | |
| CO1: | CO1: Frame a real world problem, identify the requirement and develop the design solutions. Express the technical ideas, strategies and methodologies. | | | | | | | | | |
| CO2: | Apply the new tools, algorithms, techniques that contribute to obtain the solution of the project. Examine and validate through conformance of the developed prototype and analysis the cost effectiveness. | | | | | | | | | |
| CO3: | CO3: Prepare report and present the oral demonstrations. | | | | | | | | | |
| | CO/PO, PSO Mapping | | | | | | | | | |

(3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak

| COs | Programme Outcomes (POs) and Programme Specific Outcome (PSOs) | | | | | | | | | | | | | |
|-----|--|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|
| | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | PO10 | PO11 | PO12 | PSO1 | PSO2 |
| CO1 | 3 | 3 | 3 | 2 | 1 | 2 | 2 | 2 | 2 | 2 | 1 | 1 | 3 | 2 |
| CO2 | 3 | 3 | 3 | 3 | 3 | 2 | 2 | 2 | 2 | 2 | 3 | 3 | 3 | 2 |
| CO3 | 3 | 2 | 2 | 2 | 2 | 2 | 3 | 3 | 3 | 3 | 1 | 1 | 3 | 2 |

Course Assessment methods

| | Indirect | |
|---------------------------|-------------------------------------|-------------------|
| Review- I (10 marks) | End semester Examination (50 marks) | Course end survey |
| Review- II (10 marks) | | |
| Review- III (10 marks) | | |
| Project report (20 marks) | | |

- 1. The students formed into a team of convenient groups of not more than 3 members on a project are not allowed to change their team members.
- 2. Every project team should report to their faculty guide for discussion from the day of beginning of 6th semester.
- 3. The group has to analyze the selected problem addressed in their project work to draw solution.
- 4. A project report has to be submitted by each student group at the end of the 6^{th} semester.
- 5. Three reviews have to be conducted by a team of faculty (minimum of 1 and maximum of 2) along with their faculty guide as a member of faculty team (for monitoring the progress of project planning and implementation).

Total Hours: 30 Hrs

| Semester -VI | E 601B R: SOFT SKILLS AND APTITUDE – IV L T P C Marks | | | | | | | | | | |
|---|---|--|--|--|--|--|--|--|--|--|--|
| | (For all Department except Civil) 0 0 2 1 100 | | | | | | | | | | |
| Course Outcomes At the end of the c | ourse the student will be able to: | | | | | | | | | | |
| Demonstrate cap | pabilities in job-oriented company selection processes using the hands-on approach | | | | | | | | | | |
| | of any given level of complexity in all areas of quantitative aptitude and logic core 70-75% marks in company-specific internal tests | | | | | | | | | | |
| | vanced-level verbal aptitude skills in English and score 70-75% marks in company | | | | | | | | | | |
| | Demonstrating Soft -Skills capabilities with reference to the followin | | | | | | | | | | |
| | topics: | | | | | | | | | | |
| 1. Soft Skills | a. Mock group discussionsb. Mock interviewsc. Mock stress interviews | | | | | | | | | | |
| | Solving problems with reference to the following topics: | | | | | | | | | | |
| 2. Quantitative Apand Logical Reasonir | d. Clocks & Calendars e. Functions & polynomials f. Logarithm g. Geometry h. Puzzles i. Data interpretation j. Data Sufficiency k. Company specific aptitude questions (AMCAT & Co cubes) | | | | | | | | | | |
| a. 3. Verbal Apti | tude Demonstrating English language skills with reference to the followin topics: a. Writing captions for given pictures b. Reading comprehension c. Critical reasoning d. Theme detection e. Jumbled sentences f. Writing a story on given pictures g. Company specific aptitude questions | | | | | | | | | | |

Department of Placement Training Sona College of Technology, Salem-635 065.

<u>MCT</u>

| U15MC1001R | | | | 1R AUTOMATION IN INDUSTRIES | | | | | | | L | т | Р | С |
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| 0151 | MCI | UUIK | | AU | IOMA | IION | TIA TIA | וופטעו | KIES | | 3 | 0 | 0 | 3 |
| Cours | Course Outcomes | | | | | | | | | | | | | |
| After s | succe | essful | comp | letion | of this | course | e, the | studen | ts shou | ıld be a | ble to | | | |
| CO1: | CO1: Know the requirements of industrial Automation | | | | | | | | | | | | | |
| CO2: | | | | | | | | | PLC de | ovices | | | | |
| | | | | | | | • | | PLC U | evices | | | | |
| CO3: | Se | lect th | ne I/O |) devid | es inte | rfacin | g with | PLC | | | | | | |
| CO4: | An | alyse | the n | etwor | king re | quiren | nents | and vis | ualizat | ion of t | he ind | ustries | | |
| CO5: | Au | tomat | e the | real t | ime inc | dustrie | S | | | | | | | |
| Pre-re | equi | site | | | | | | | | | | | | |
| Ele | ectro | nic D | evice | es and | l circu | its | | | | | | | | |
| | | | | | | _ | - | | apping | | | | | |
| | (: | 3/2/: | L indi | cates | stren | gth o | corr | elatior | ı) 3-St | rong, | 2-Med | lium, 1 | L-Weak | |
| | | | | me O | | | | nd Pro | gramr | ne Spe | | | ne (PSC |)s) |
| COs | PO 1 | PO 2 | PO 3 | PO4 | PO 5 | PO 6 | PO 7 | PO8 | P09 | PO10 | PO1 1 | PO1 2 | PSO1 | PSO2 |
| CO1 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | | | 3 | 2 |
| CO2 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | | | 3 | 2 |
| CO3 | 3 | 2 | 3 | 2 | 3 | | 2 | | | 2 | | | 3 | 2 |
| CO4 CO5 | 3 | 3 | 3 | 2 | | | 2 | | | 2 | | | 3 | 2 |
| <u>CO3</u> | 3 | 3 | <u> </u> | <u> </u> | Co | ourse | | ssmen | t meth | _ | | | _ 3 | <u> </u> |
| | | | | | Direct | | | | | | | Ind | irect | |
| Totovo | -l +- | oh T (6 | ` | ' | | - μ/ Λο | aian m | ont (E) | | | | | | |
| Intern | | • | - | | | | _ | ent (5) | | | | | | |
| Intern | | • | , | | Moodle | | | | | | Co | urse e | nd surve | У |
| Intern | | | (6) | | Attend | | | | (60) | | | | | |
| Assign | ımen | t (5) | | | Ena se | emeste | er Exai | minatio | n (60) | | | | | |
| JNIT I | INI | ROD | UCTI | ON TO | INDU | JSTRI | AL AL | JTOMA | TION | | | | 9 H | ours |
| Need | of au | ıtoma | tion i | n indu | stries | - Evo | lution | of PLC | - Con | struction | on and | l worki | ng of M | echanical |
| | | | | | | | | | | | | | _ | |
| relay – Relay logic – simple relay ladder diagram for real time examples – relay interlocking - Advantages over relay logic. | | | | | | | | | | | | | | |
| Advan | itaue | s over | I Cla v | louic | | | | | | | | | | |

PLC configuration and various components of the PLC - PLC inputs and outputs modules - Power Supplies - Programming format - Construction of PLC Ladder Diagrams - CPU, I/O cards -Processor less PLCs.

UNIT III **PLC I/O Devices**

9 Hours

Input devices: Manually operated switches - Mechanically operated switches - Temperature and proximity switches - Analog I/P devices. Output devices: Stepper and servomotors - hydraulic and pneumatic actuators - Analog valves.

PLC NETWORKING and SCADA UNIT IV

9 Hours

Networking of PLCs-Data Communication-Fieldbus, PROFI bus, and Mod bus-OSI Model types-OPC function. Human Machine Interface - Supervisory Control and Data Acquisition-Architecture-Remote terminal unit-Master terminal unit-Data storage.

APPLICATION IN REAL TIME INDUSTRIES UNIT V

9 Hours

Automatic Bottle Filling Systems- Traffic Light Control - Hydraulic press control system - car washing system - Automation in power plants.

| Th | Theory: 45 Hrs Tutorial: Total Hours: 45 Hr | | | | | | | | | | |
|------|---|---|----------------------------------|--|--|--|--|--|--|--|--|
| Text | Books | | | | | | | | | | |
| 1. | Frank D Petruzella, "Programmable Logic Controllers", McGraw Hill Publishers, 3 rd Edition, 2010. | | | | | | | | | | |
| 2. | John W. Webb a India Publishers, | and Ronald A. Reis "Programmable Logic 2007. | Controllers", Prentice – Hall of | | | | | | | | |
| REFE | RENCES | | | | | | | | | | |
| 1. | John R Hackwort | h, "Programmable Logic Controllers: Pr | ogramming Methods and | | | | | | | | |
| | Applications", Pearson education, 1st Edition, 2003. | | | | | | | | | | |
| 2. | Siemens PLC Hand book for total automation | | | | | | | | | | |
| 3. | Allen – Bradley h | nand book for total automation | | | | | | | | | |
| 4. | GE – Fanuc hand | book for total automation | | | | | | | | | |

| U15M | C1002R | 3D PRINTING TECHNOLOGY | L | Т | P | С |
|-----------|----------------------|---|----------|-----------|---------|--------|
| 015110 | JIJOZIK | 35 1 KINTING 126111102001 | 3 | 0 | 0 | 3 |
| Course C | utcomes | | | | | |
| After suc | cessful cor | npletion of this course, the students should l | oe able | to | | |
| CO1: | Explain ste | os involved in Rapid tooling and Addictive manufa | cturing. | | | |
| CO2: | Discuss var | ious fabrication & modelling techniques. | | | | |
| CO3: | Analyse the machine. | working principle of various precision instrument | ts based | on laser, | Electro | n beam |

Pre-requisite

CO4:

CO5:

- 1. Engineering Physics
- 2. Manufacturing Technology

CO/PO, PSO Mapping

Describe the concept of 3D printing, Direct and Indirect tooling techniques.

Identify the suitable AM process to fabricate physical components.

(3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak

| | | P | rogram | me Ou | tcomes | (POs) | and Pro | gramn | ne Spec | cific Out | tcome (| (PSOs) | | |
|-----|-----|-----|--------|-------|--------|-------|---------|-------|---------|-----------|---------|--------|------|------|
| COs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | PO10 | | | PSO1 | PSO2 |
| CO1 | 3 | 3 | 3 | | 3 | | | | | | | | 3 | 3 |
| CO2 | 3 | 3 | 3 | | 3 | | | | | | | | 3 | 3 |
| CO3 | 3 | 3 | 3 | | 3 | | | | | | | | 3 | 3 |
| CO4 | 3 | 3 | 3 | | 3 | | | | | | | | 3 | 3 |
| CO5 | 3 | 3 | 3 | | 3 | | | | | | | | 3 | 3 |

Internal test I (6 marks) Internal test II (6 marks) Internal test III (6 marks) Assignment (5 marks) Assignment (5 marks) End semester Examination (60 marks) Course end survey Course end survey

Unit 01: Introduction 9 Hours

Needs - Impact of AM and Rapid Tooling on Product Development - Distinction between AM and CNC Machining- The Generalized AM Process chain - CAD Model - Input file formats - Generation and Conversion of STL file - File Verification and Repair - Build File Creation - Part Construction - Part Cleaning and finishing - RP Benefits - Classification of RP systems

Unit 02: Liquid Polymer and Solid Based Systems

9 Hours

Stereolithography Apparatus (SLA), Digital Light Projection (DLP), Photo polymerization process, Solid Ground Curing (SGC), Fused Deposition Modeling (FDM) and Laminated Object Manufacturing (LOM) -

| | Work | ing Principle, Cor | nstruction, Materia | als and Ap | plications. | | | | | | |
|--|---|--------------------|---------------------|-------------|---------------------|---------------|--|--|--|--|--|
| Unit 0 | 3: POWDER BASE | D SYSTEMS | | | | 9 Hours | | | | | |
| Selective Laser Sintering (SLS), Three-dimensional Printing (3DP), Direct Metal Deposition (DMD), Ballistic Particle Manufacturing (BPM), Electron Beam Melting (EBM) and Laser Engineered Net Shaping (LENS)- Working Principle, Construction, Process Variables, Materials and Applications | | | | | | | | | | | |
| Unit 04: OPEN SOURCE PRINTER AND RAPID TOOLING 9 Hours | | | | | | | | | | | |
| Concept of open source 3D printer - Structural details, Control mechanism - Materials and Applications. Introduction to rapid tooling (RT) - Direct and Indirect tooling - Silicone rubber moulding, Epoxy tooling, Spray Metal Coating, Electro Optical Sintering (EOS) - Working Principle, Materials and Applications | | | | | | | | | | | |
| Unit 0 | 5: APPLICATION | S OF ADDITIV | /E MANUFACTUR | RING | | 9 Hours | | | | | |
| | cation of Rapid prototy onics and Retail indus | | | | notive industries, | Aerospace and | | | | | |
| Т | heory: 45 Hrs | Tutorial: | Practical: Hr | | Total Hou | rs: 45 Hrs | | | | | |
| | Text Books | | | | | | | | | | |
| 1. | C. K. Chua, K. F. Leo Cambridge University | | , Rapid prototypir | ng: Princip | les and application | ons, | | | | | |
| 2. | D. T.Pham and S. S.I | Dimov, Rapid ma | nufacturing, Sprir | iger-Verla | g, London, 2001 | | | | | | |
| | REFERENCES | | | | | | | | | | |
| I. Gibson, D. W. Rosen, and B. Stucker, Additive Manufacturing Methodologies: Rapid Prototyping to Direct Digital Manufacturing, Springer, 2010 | | | | | | | | | | | |
| 2. L.W. Liou, F.W. Liou, Rapid Prototyping and Engineering applications: A toolbox for prototype development, CRC Press, 2013. | | | | | | | | | | | |
| 2 | A. K. Kamrani, E. A. | | | | | | | | | | |

Sona College of Technology, Salem

(An Autonomous Institution)

Courses of Study for B.E/B.Tech. Semester VII 2015R (CBCS)

Branch: Mechatronics Engineering

| S. No | Course Code | | Course Title | Lecture | Tutorial | Practical | Credit | Total Contact Hours |
|-------|----------------------|-------------|--|---------|----------|-----------|--------|------------------------|
| | | | Theory | | | | | |
| 1 | U15GE701R | Professiona | al Ethics and Human Values | 3 | 0 | 0 | 3 | 45 |
| 2 | U15MC701R | Robotics | | 3 | 0 | 0 | 3 | 45 |
| 3 | U15MC702R | Micro Elec | tro Mechanical Systems | 3 | 0 | 0 | 3 | 45 |
| 4 | U15MC904R | Elective | Image Processing and Computer vision | 3 | 0 | 0 | 3 | 45 |
| 5 | U15MC905R | Flootivo | Industrial Engineering | | 0 | 0 | 3 | |
| 3 | 5 U15MC906R Elective | | Total quality management | 3 | U | U | 3 | 45 |
| | U15CS1004R | | Mobile Application Development | | | | | |
| | U15EC1008R | | Mobile Technology and its Applications | | | | | |
| | U15EE1004R | | Energy Conservation and Management | | | | | |
| | U15EE1006R | | Renewable Energy Systems | | | | | |
| | U15EE1007R | Open | Innovation, IPR and Entrepreneurship | | | | | |
| 6 | O13EE1007K | Elective | Development | 3 | 0 | 0 | 3 | 45 |
| | U15IT1003R | Elective | Problem Solving Techniques Using Java | | | | | |
| | 013111003K | | Programming | | | | | |
| | U15ME1004R | | Industrial Safety | | | | | |
| | U15ME1005R | | Maintenance Engineering | | | | | |
| | U15ME1010R | | 3D Printing | | | | | |

Page 1 of 2

| | | Practical | | | | | |
|---|-----------|-----------------------------|---|----|-------------|-----|----|
| 7 | U15MC703R | Robotics Laboratory | 0 | 0 | 4 | 2 | 60 |
| 8 | U15MC704R | Image Processing Laboratory | 0 | 0 | 3 | 1.5 | 45 |
| 9 | U15MC705R | Technical Seminar | 0 | 0 | 3 | 1.5 | 45 |
| | | | | To | tal Credits | 23 | |

Approved By

Chairperson, Mechatronics Engineering BoSDr.P.Suresh

Member Secretary, Academic Council Dr.R.Shivakumar Chairperson, Academic Council & Principal Dr.S.R.R.Senthil Kumar

Copy to:-

HOD/ Mechatronics Engineering, Seventh Semester BE MCT Students and Staff, COE

Page 2 of 2

| T 11 E / | GE701R | | PROF | ESSIC |)NAL 1 | ETHIC | S ANI | HUM | IAN | L | T | P | С |
|--|---|----------|------------|-------------|--------------|----------|----------|-----------|-----------|----------|---------|----------|--------|
| 013 | GE/UIK | | | | \mathbf{V} | ALUES | S | | | 3 | 0 | 0 | 3 |
| Course | Outcom | ies | | | | | | | | | | | |
| After s | uccessfu | l comp | letion | n of thi | s cour | se, the | studer | ts sho | uld be a | ble to | | | |
| CO1: Develop the core values that shape the ethical behavior of an engineer | | | | | | | | | | | | | |
| CO2: | Apply | Kohlbe | erg Gil | lligan's | theory | y in res | solving | moral | Dilemm | as. | | | |
| CO3: | Analyz | e role (| of eng | ineer a | s an et | hical e | xperim | enter i | n solvinş | g societ | al prob | lems. | |
| CO4: | Create | ways t | o redı | ıce var | ious ris | sks in v | workin | g envir | onment | • | | | |
| CO5: Apply ethical principles in global technology development | | | | | | | | | | | | | |
| Pre-req | uisite: | | | | | | | | | | | | |
| | | | | | | | | | | | | | |
| | | | | | CO/ | PO, PS | SO Ma | pping | | | | | |
| (3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak | | | | | | | | | | | | | |
| COs | Os Programme Outcomes (POs) and Programme Specific Outcome (PS | | | | | | | | | | | | |
| | PO1 PO2 | PO3 | PO4 | | | | | | | PSO1 | PSO2 | | |
| CO1 | | | | 3 2 2 2 3 2 | | | | | | 1 | 2 | | |
| CO2 | | | | | 3 | 2 | 3 | 1 | 2 | | 2 | 1 | 2 |
| CO3 | | | | | 3 | 2 | 2 | 1 | 2 | | 2 | 1 | 2 |
| CO4 | | | | | 3 | 3 | 2 | 2 | 2 | | 2 | 1 | 2 |
| CO5 | | | | | 3 | 2 | 2 | 1 | 2 | | 2 | 1 | 2 |
| | | | | | | | | .1 | 1 | | | | |
| | | | | | | Asses | sment | metho | ds | | T . | 1' ' | |
| T . | 1 | | <u>, I</u> | Dir | | | . /= | 1 \ | | | Inc | lirect | |
| | l test I (6 | | | | | O | ent (5 m | narks) | | | | | |
| | l test II (| | , | | letest (| | , | | | C | ourse e | end surv | vey |
| | l test III | ` | , | | dance (| | , | , (60 m | anlea) | | | | |
| | ment (5 1 HUMA | | | EHU Se | emeste | L EXAII | ination | 1 (60 11) | arks) | | | 9 H | ours |
| | Values | | | Integr | ity – W | ork Ft | hic – S | ervice | [earning | r – Civi | c Virtu | | |
| | – Livin | | | _ | - | | | | - | | | | - |
| | | _ | _ | | _ | | _ | - | | _ | | 5 mic | |
| | operation – Commitment – Empathy – Self-Confidence – Character – Spirituality. Unit 02: ENGINEERING ETHICS 9 Hours | | | | | | | | | | | | |
| Senses | of 'Engi | neering | g Ethi | cs' – V | ariety | of mor | al issu | es – Tv | pes of i | nquiry | - Mor | al Diler | nmas – |
| Moral Autonomy – Kohlberg's theory – Gilligan's theory – Consensus and Controversy – | | | | | | | | | | | | | |
| | ions and | - | | _ | - | | • | - | | | | | - |
| Unit 03: | ENGIN | EERIN | IG AS | SOC | AL EX | PERIN | AENT A | ATION | | | | 9 H | ours |

Unit 04: ENGINEER'S RESPONSIBILITY FOR SAFETY

Safety and Risk – Assessment of Safety and Risk – Risk analysis-Reducing Risk – The

Engineering as Experimentation – Engineers as Responsible Experimenters – Research Ethics - Codes of Ethics – Industrial Standards - A Balanced Outlook on Law – The Challenger Case Study

Government Regulator's Approach to Risk - Case Studies - Chernobyl and Bhopal.

Responsibilities and Rights- Collegiality and Loyalty – Respect for Authority – Collective Bargaining – Confidentiality – Conflicts of Interest – Occupational Crime – Professional Rights – Employee Rights – Intellectual Property Rights (IPR) – Discrimination.

Unit 05: GLOBAL ISSUES

9 Hours

Multinational Corporations – Business Ethics - Environmental Ethics – Computer Ethics - Role in Technological Development – Weapons Development – Engineers as Managers – Consulting Engineers – Engineers as Expert Witnesses and Advisors – Honesty – Moral Leadership – Sample Code of Conduct.

| Theor | y: 45 Hrs | Tutorial: | Practical: | Total Hours: 45 Hrs | | | | | | |
|-------|--|-------------------|-----------------------|--------------------------------------|--|--|--|--|--|--|
| TEXT | BOOKS | | | | | | | | | |
| 1. | Mike Martin and | d Roland Schinz | zinger, "Ethics in En | gineering", 4th edition McGraw Hill, | | | | | | |
| 1. | New York, 2014. | | | | | | | | | |
| 2 | Charles E Harr | is, Michael S l | Pritchard and Micha | ael J Rabins, "Engineering Ethics – | | | | | | |
| ۷. | 2. Concepts and Cases", Thompson Learning, 2000. | | | | | | | | | |
| REFEI | RENCES | | | | | | | | | |
| 1. | Charles D Fledd | lermann, "Engii | neering Ethics", Pren | tice Hall, New Mexico,2014. | | | | | | |
| 2. | John R Boatrigh | t, "Ethics and th | ne Conduct of Busine | ss", Pearson Education, 2014. | | | | | | |
| 3. | Edmund G See | bauer and Rob | ert L Barry, "Funda | mentals of Ethics for Scientists and | | | | | | |
| 3. | Engineers", Oxf | ord University | Press, 2001. | | | | | | | |
| 1 | Prof. (Col) P S | Bajaj and Dr. I | Raj Agrawal, "Busine | ess Ethics – An Indian Perspective", | | | | | | |
| 4. | Biztantra, New | Delhi, 2004. | | | | | | | | |

| U15N | MC701R | ROBOTICS | L | T | P | С | | | |
|---------|---|---|-----------|---------|---------|--------|--|--|--|
| | , 10, 011 | 210202120 | 3 | 0 | 0 | 3 | | | |
| Course | Outcomes | | | | | | | | |
| After s | uccessful co | ompletion of this course, the students should be a | ble to | | | | | | |
| CO1: | Express th | Express the basic concepts, laws, components and parameters of robots | | | | | | | |
| CO2: | Explain th | e types of grippers and its functions. | | | | | | | |
| CO3: | Evaluate t | he kinematic calculations and apply Lagrangian an | nd New | ton-Eul | er meth | ods to | | | |
| CO3: | analyze dy | namic characteristics of robots | | | | | | | |
| CO4: | Describing | the various programming techniques used in ind | ustrial r | obots | | | | | |
| CO5: | Basis of machine vision and apply the concept of image processing | | | | | | | | |
| Pre-req | requisite | | | | | | | | |

--

CO/PO, PSO Mapping

(3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak

| COs | | Programme Outcomes (POs) and Programme Specific Outcome (PSOs) | | | | | | | | | | | | |
|-----|-----|--|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|
| | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | PO10 | PO11 | PO12 | PSO1 | PSO2 |
| CO1 | 3 | 2 | 2 | | 3 | | | 2 | | | 3 | | 3 | 2 |
| CO2 | 2 | 3 | 3 | | 3 | | 3 | | 3 | | | 2 | 3 | 2 |
| CO3 | 3 | 3 | 3 | | 3 | | 2 | | | | 2 | | 3 | 2 |
| CO4 | 3 | 2 | 2 | | 2 | | | | | 3 | | | 3 | 2 |
| CO5 | 2 | 3 | 3 | | 2 | | | 2 | | | | 2 | 3 | 2 |

Course Assessment methods

| | Direct | Indirect |
|---|-------------------------------------|---------------------|
| Internal test I (6 marks) | Seminar/ Assignment (5 marks) | |
| Internal test II (6 marks) Moodletest (7 marks) | | Course and augustas |
| Internal test III (6 marks) | Attendance (5 marks) | Course end survey |
| Assignment (5 marks) | End semester Examination (60 marks) | |

Unit 01: FUNDAMENTALS OF ROBOTICS

9 Hours

Introduction- Basic components of robot-Laws of robotics- classification of robot-work space-accuracyresolution –repeatability of robot. Power transmission system: Rotary to rotary motion, Rotary to linear motion, Harmonics drives – gear system - belt drives.

Unit 02: ROBOT END EFFECTORS

9 Hours

Robot End effectors: Introduction- types of End effectors- Mechanical gripper- types of gripper mechanism- gripper force analysis- other types of gripper- special purpose grippers.

Unit 03: ROBOT MECHANICS

9 Hours

Robot kinematics: Introduction- Matrix representation- rigid motion & homogeneous transformationforward & inverse kinematics- trajectory planning. Robot Dynamics: Introduction - Manipulator dynamics – Lagrange - Euler formulation- Newton - Euler formulation

Unit 04: ROBOT PROGRAMMING

9 Hours

Robot programming: Robot Languages- Classification of robot language-Computer control and robot software-Val system and Languages- application of robots.

Unit 05: MACHINE VISION FUNDAMENTALS

9 Hours

Machine vision: image acquisition, digital images-sampling and quantization-levels of computation Feature extraction-windowing technique- segmentation- Thresholding- edge detection- binary morphology - grey morphology.

Communication between robots-Case studies.

| Theor | y: 45 Hrs | Tutorial: | Practical: | T | Total Hours: 45 Hrs |
|-------|--------------------|--------------------|---------------------|-------------|----------------------------|
| TEXT | BOOKS | | | | |
| | M.P.Groover, M | I.Weiss ,R.N. N | agal, N.G.Odrey, | "Industrial | Robotics - Technology, |
| 1. | programming ar | nd Applications" | Tata , McGraw-Hil | l Education | n Pvt Limited 2ndEdition, |
| | 2012. | | | | |
| REFER | RENCES | | | | |
| 1 | John.J.Craig, " In | troduction to Ro | botics: Mechanics & | control"Pe | earson Publication, Fourth |
| 1. | edition, 2018. | | | | |
| 2. | Jazar, "Theory | of Applied Rob | otics: Kinematics, | Dynamics | and Control", Springer, |
| ۷. | 2ndEdition, 2010 |). | | | |
| 3. | K.S.Fu, R.C.Gonz | zalez, C.S.G.Lee, | "Robotics: Sensing, | Vision & In | ntelligence", Tata McGraw- |
| 3. | Hill Publication, | First Edition, 198 | 87. | | |
| 4 | Sathya Ranjan D | Deb, "Robotics Te | echnology & flexibl | e Automat | tion" Second edition, Tata |
| 4. | McGraw-Hill Pu | blication, 2009. | | | |

| U15MC702R | MICRO ELECTRO MECHANICAL SYSTEMS | L | T | P | C |
|-----------|-----------------------------------|---|---|---|---|
| 015WC702K | WICKO ELECTRO WECHANICAL 3131EWIS | 3 | 0 | 0 | 3 |

Course Outcomes

| After successful completion of this course, the students should be able to | | | | | | | | | |
|--|--|--|--|--|--|--|--|--|--|
| CO1: | Retrieve the scaling laws used in conceptual design of microsystems. | | | | | | | | |
| CO2: | Select a suitable micro manufacturing technique for the fabrication of a specific MEMS | | | | | | | | |
| | device. | | | | | | | | |
| CO3: | Summarize the materials and working principles of micro sensors. | | | | | | | | |
| CO4: | Design and working of Micro actuators. | | | | | | | | |

Intrepret concepts of quantum mechanics and nano systems.

Pre-requisite

CO5:

- 1. Engineering Physics
- 2. Sensors and Instrumentation

CO/PO, PSO Mapping

(3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak

| COs | | Programme Outcomes (POs) and Programme Specific Outcome (PSOs) | | | | | | | | | | | | |
|-----|-----|--|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|
| 200 | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | PO10 | PO11 | PO12 | PSO1 | PSO2 |
| CO1 | 3 | 3 | 2 | | 3 | | | 2 | | | 3 | | 3 | 3 |
| CO2 | 2 | 3 | 3 | | 3 | | 3 | | 3 | | | 2 | 2 | 3 |
| CO3 | 3 | 3 | 3 | | 3 | | 2 | | | | 2 | | 3 | 3 |
| CO4 | 3 | 2 | 3 | | 2 | | | | | 3 | | | 3 | 2 |
| CO5 | 3 | 3 | 3 | | 2 | | | 2 | | | | 2 | 3 | 3 |

Course Assessment methods

| | Indirect | |
|-----------------------------|-------------------------------------|-------------------|
| Internal test I (6 marks) | Seminar/ Assignment (5 marks) | |
| Internal test II (6 marks) | Moodle test (7 marks) | Course and curvey |
| Internal test III (6 marks) | Attendance (5 marks) | Course end survey |
| Assignment (5 marks) | End semester Examination (60 marks) | |

Unit 01: MICROSYSTEMS AND MINIATURIZATION

9 Hours

Introduction to Microsystems and microelectronics - Applications of micro system in automotive, bio medical, aerospace - telecommunication industries. Trimmer's scaling vector and scaling laws - scaling in geometry- scaling in rigid body dynamics- scaling in electrostatic forces-scaling in electricity.

Unit 02: MEMS FABRICATION TECHNOLOGIES

9 Hours

Microsystem fabrication processes: Photolithography, Ion Implantation, Diffusion, Oxidation. Thin film depositions: LPCVD, Sputtering, Evaporation, Electroplating; Etching techniques: Dry and wet etching, electrochemical etching; Micromachining: Bulk Micromachining, Surface Micromachining, High Aspect-Ratio (LIGA and LIGA-like) Technology.

Unit 03: MICRO SENSORS

9 Hours

MEMS Sensors: Design of Acoustic wave sensors, resonant sensor, Vibratory gyroscope, Capacitive and Piezo Resistive Pressure sensors- engineering mechanics behind these Microsensors.

Unit 04: MICRO ACTUATORS

Theory: 45 Hrs

Press, 2002.

9 Hours

Design of Actuators: Actuation using thermal forces, Actuation using shape memory Alloys, Actuation using piezoelectric crystals, Actuation using Electrostatic forces (Parallel plate, Torsion bar, Comb drive actuators), Micromechanical Motors and pumps.

Unit 05: MICROSYSTEMS PACKAGING AND APPLICATIONS

Tutorial: --

9 Hours

Total Hours: 45 Hrs

Packaging: Microsystems packaging, Essential packaging technologies, Selection of packaging materials. Other Applications: Optical MEMS: Micro mirrors, optical switches, RF-MEMS: RF resonators for filters, frequency sources, Power MEMS: micro power sources, batteries and solar cells vs. MEMS based devices, energy harvesting, NEMS -sensors.

Practical: --

| TEXT | TEXT BOOKS | | | | | | | | | |
|------|---|--|--|--|--|--|--|--|--|--|
| 1. | Marc Madou, "Fundamentals of Micro fabrication", CRC press 1997. | | | | | | | | | |
| 2. | Tai Ran Hsu, MEMS and Microsystems Design and Manufacture, Tata McGraw-Hill | | | | | | | | | |
| | Publishing Company Ltd, New Delhi, 2017. | | | | | | | | | |
| REFE | REFERENCES | | | | | | | | | |
| 1. | Chang Liu, Foundations of MEMS, Pearson Education, New Delhi, 2011. | | | | | | | | | |
| 2. | James J.Allen, "Micro Electro Mechanical System Design", CRC Press Publisher, 2010. | | | | | | | | | |

3. Sergey Edward Lyshevski, "MEMS and NEMS: Systems, Devices, and Structures" CRC

| | Elective: | L | T | P | C | | | | |
|-----------------|-------------------------------|---|---|---|---|--|--|--|--|
| U15MC904R | IMAGE PROCESSING AND COMPUTER | 3 | 0 | 0 | 3 | | | | |
| | VISION | 3 | O | O | | | | | |
| Course Outcomes | | | | | | | | | |

| After successful completi | ion of this course. | the students s | hould be able to |
|---------------------------|---------------------|----------------|------------------|
|---------------------------|---------------------|----------------|------------------|

- CO1: Implement image enhancement algorithms.
- CO2: Apply image transforms for different image applications.
- CO3: Perform different segmentation and restoration.
- Implement different compression techniques. **CO4**:
- **CO5**: Develop algorithms for computer vision problems.

Pre-requisite

CO/PO, PSO Mapping

(3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak

| COs | Programme Outcomes (POs) and Programme Specific Outcome (PSOs) | | | | | | | | | | | | | |
|-----|--|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|
| | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | PO10 | PO11 | PO12 | PSO1 | PSO2 |
| CO1 | 2 | 3 | 2 | | 3 | | | 2 | | | 3 | | 3 | 2 |
| CO2 | 2 | 3 | 3 | | 2 | | 3 | | 3 | | | 2 | 3 | 2 |
| CO3 | 3 | 3 | 2 | | 3 | | 2 | | | | 2 | | 3 | 2 |
| CO4 | 2 | 2 | 3 | | 2 | | | | | 3 | | | 3 | 2 |
| CO5 | 3 | 3 | 2 | | 2 | | | 2 | | | | 2 | 3 | 2 |

Course Assessment methods

| | Indirect | | | | | | |
|-----------------------------|--|---------------------|--|--|--|--|--|
| Internal test I (6 marks) | Seminar/ Assignment (5 marks) | | | | | | |
| Internal test II (6 marks) | Moodletest (7 marks) | Course on decomposi | | | | | |
| Internal test III (6 marks) | Attendance (5 marks) | Course end survey | | | | | |
| Assignment (5 marks) | Assignment (5 marks) End semester Examination (60 marks) | | | | | | |

Unit 01: IMAGE ENHANCEMENT

9 Hours

Digital Image fundamentals - Types of Images - Relationship between pixels-Image sampling -Quantization - Spatial domain filtering - Image negative - Contrast stretching, Gray level slicing -Histogram equalization - Smoothing filters, Sharpening filters, Maximum filter, Minimum filter, Median filter.

Unit 02: IMAGE TRANSFORM

9 Hours

2D transforms - DFT - DCT - Walsh - Hadamard - Slant - Haar - KLT - SVD - Wavelet transform.

Unit 03: IMAGE RESTORATION AND SEGMENTATION

9 Hours

Image restoration - degradation model - Unconstrained and Constrained restoration - Inverse filtering - Wiener filtering - Image segmentation - Thresholding - Edge detection - Region based segmentation.

Unit 04: IMAGE COMPRESSION

9 Hours

Need for data compression - Huffman - Arithmetic coding - LZW technique – Compression. standards JPEG – MPEG.

Unit 05: COMPUTER VISION

9 Hours

Image classification - Feature extension - Markov Random Field Matrix - Gray Level Co - occurrence Matrix - Gray Level Weight Matrix , Multi Resolution Combined Statistical and Spatial Frequency method, character recognition- zoning approaches, Medical Image Analysis - Diabetic Retinopathy - Glaucoma.

| Theor | y: 45 Hrs | Tutorial: | Practical: | Total Hours: 45 Hrs | | | | | | | |
|--------------------------------|--|-------------------|----------------------|--|--|--|--|--|--|--|--|
| TEXT | BOOKS | | | | | | | | | | |
| 1 | Rafael C.Gonzalex, Richard E.Woods, "Digital Image Processing, Pearson Education. | | | | | | | | | | |
| 1. Inc"., Forth Edition, 2018. | | | | | | | | | | | |
| 2. | Anil K.Jain, "Fundamentals of Digital Image Processing", Prentice Hall of India, 2004. | | | | | | | | | | |
| REFERENCES | | | | | | | | | | | |
| 1. | Richard Szeliski, "Computer Vision Algorithms and Applications", Springer Verlag | | | | | | | | | | |
| 1. | London Limited, 2011. | | | | | | | | | | |
| 2. | Sabeenian R.S., " | Digital Image Pr | cocessing", Sonavers | ity publication, Second Edition, 2010. | | | | | | | |
| 3. | Annadurai S., | R. Shanmugalal | kshmi, "Fundamen | tals of Digital Image Processing", | | | | | | | |
| 3. | Pearson Education | on India, 2007. | | | | | | | | | |
| 4. | Sridhar.S, "Digit | al Image Process | sing", Oxford Univer | rsity Press, First Edition, 2011. | | | | | | | |
| 5. | Kenneth R. Castl | leman, "Digital I | mage Processing", P | earson, 2009 | | | | | | | |

| U15MC905R | Elective: | L | T | P | C |
|-----------------|------------------------|---|---|---|---|
| | INDUSTRIAL ENGINEERING | 3 | 0 | 0 | 3 |
| Course Outcomes | | | | | |

After successful completion of this course, the students should be able to

- **CO1**: Select proper plant layout for the required production system.
- CO2: Plan the resources required for the production and to perform the control methods.
- Apply work study method, prepare charts to outline the process and develop ergonomic CO3: condition suitable for the processes.
- **CO4**: Analyze the inventory required based on production needs and material handling.
- **CO5**: Explain the system and different types of maintenance process for smooth operations.

Pre-requisite

CO/PO, PSO Mapping

(3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak

| COs | | Programme Outcomes (POs) and Programme Specific Outcome (PSOs) | | | | | | | | | | | | |
|-----|-----|--|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|
| | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | PO10 | PO11 | PO12 | PSO1 | PSO2 |
| CO1 | 2 | 3 | 1 | 1 | | | | | | | | | 3 | 2 |
| CO2 | 2 | 2 | 1 | 2 | | | | | | | | | 3 | 2 |
| CO3 | 1 | 2 | 3 | 2 | | | | | | | | | 3 | 2 |
| CO4 | 2 | 3 | 1 | 2 | | | | | | | | | 3 | 2 |
| CO5 | 2 | 3 | 1 | 2 | | | | | | | | | 3 | 2 |

Course Assessment methods

| | Indirect | |
|-----------------------------|-------------------------------------|-------------------|
| Internal test I (6 marks) | Seminar/ Assignment (5 marks) | |
| Internal test II (6 marks) | Course on decourses | |
| Internal test III (6 marks) | Attendance (5 marks) | Course end survey |
| Assignment (5 marks) | End semester Examination (60 marks) | |

Unit 01: INDUSTRIAL ENGINEERING AND PRODUCTION SYSTEM

9 Hours

Industrial engineering - Concept, History and Development, Applications, Roles of Industrial engineer. Production management, Industrial engineering versus Production management, Operations management. Production system Analysis, Input-output model, Productivity, Factors affecting productivity. Plant layout, Criteria for a good layout, Types of layout - Process layout, Product layout, Combination layout, and Fixed position layout. Material flow pattern, Workstation design.

Unit 02: PROCESS PLANNING AND PRODUCTION CONTROL

9 Hours

Introduction to Process planning- Definition, Procedure, Process selection, Machine capacity, Process sheet, Process analysis. Group technology - Definition, Classification and coding system, Formation of component family. Production planning - Introduction, Functions, Loading, Scheduling. Production control - Dispatching, Routing. Progress control - Bar, Curve, Gantt chart, Route and Schedule chart.

Unit 03: WORK STUDY AND ERGONOMICS

9 Hours

Work study - Definition, Need, Advantages, Objectives of method study and work measurement, Method study procedure. Process chart - symbols, outline process chart, flow process chart. The flow diagram, String diagram, Multiple activity chart, Principles of motion economy, Therbligs, SIMO chart, Stopwatch procedure. Ergonomics- applications of ergonomic principles in the shop floor- work benches- seating arrangement.

Unit 04: INVENTORY MANAGEMENTAND MATERIAL HANDLING

9 Hours

Inventory - Definition, Objectives, Classification, Functions, Economic order quantity, Economic batch quantity, Inventory models, ABC analysis. Material Requirement Planning(MRPI), Manufacturing Resource Planning (MRPII), Operating cycle, Just in Time manufacturing system, KANBAN technique, Material handling - Definition, Functions, Principles, Equipment selection, and Equipment types.

Unit 05: SYSTEM ANALYSIS AND MAINTENANCE

9 Hours

System concept, System analysis, System engineering, Techniques, Applications. Value analysis/ Engineering - Definition, Types of values, Aim, Technique, Procedure, Advantages, Applications, Value engineering versus Value control. Plant maintenance department - Objectives, Importance, Duties, Functions, and Responsibilities. Types of maintenance - Breakdown, Scheduled, Preventive and Predictive. Plant maintenance schedule - Introduction, Procedure.

| Theor | y: 45 Hrs | Tutorial: | Practical: | Total Hours: 45 Hrs | | | | | | | | |
|--------|---|-------------------|----------------------|--|--|--|--|--|--|--|--|--|
| Text E | Books | • | • | | | | | | | | | |
| 1. | Khanna O.P., Ind | dustrial Engine | ering and manageme | nt, Dhanpat Rai Publications, 2010. | | | | | | | | |
| 2. | 2. Panneerselvam R., Production and operations management, Heritage Publishers, 2006. | | | | | | | | | | | |
| REFE | EFERENCES | | | | | | | | | | | |
| 1. | Martand T. Tel | lsang, Industri | al Engineering and | Production Management, S Chand | | | | | | | | |
| 1. | Publishers,2006. | | | | | | | | | | | |
| 2. | Ravi Shankar, I | ndustrial Engin | eering and Managen | nent, Golgotia Publications Pvt. Ltd., | | | | | | | | |
| ۷. | New Delhi, 2009 |). | | | | | | | | | | |
| 3. | Jan Dul, Bernar | d Weerdmeeste | er, Ergonomics for B | eginners: A Quick Reference Guide, | | | | | | | | |
| J. | CRC Press, Taylo | or and Francis g | group, 2008. | | | | | | | | | |
| 4. | Lee J. Krajewski | i, Larry P. Ritan | nan, Operations Mana | agement, Addison Wesley, 2007. | | | | | | | | |

| LI1EMC006D | Elective: | L | T | P | C |
|------------|--------------------------|---|---|---|---|
| U15MC906R | TOTAL QUALITY MANAGEMENT | 3 | 0 | 0 | 3 |

Course Outcomes

After successful completion of this course, the students should be able to

- **CO1:** Justify their philosophies/ contributions in Quality Management.
- **CO2:** Manage quality improvement teams.
- **CO3:** Justify the tools of quality and four levels of benchmarking.
- **CO4:** Explain the concept of Six Sigma and its DMAIC process.
- **CO5:** Understand the need for ISO and its implementation methods.

Pre-requisite

CO/PO, PSO Mapping

(3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak

| COs | | Pr | ogram | me Ou | tcomes | s (POs) | and P | rogram | me Sp | ecific C | Outcom | e (PSC |) s) | |
|-----|-----|-----|-------|-------|--------|---------|-------|--------|-------|----------|--------|--------|-------------|------|
| | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | PO10 | PO11 | PO12 | PSO1 | PSO2 |
| CO1 | 3 | 3 | | 3 | | | | 3 | 3 | | | 3 | 3 | 3 |
| CO2 | | 3 | 3 | 3 | | | 3 | 8 | | | | | 3 | 3 |
| CO3 | | | 3 | 3 | | 3 | | 3 | 3 | | | 3 | 3 | 3 |
| CO4 | 3 | 3 | 3 | | 3 | | | | | | | | 3 | 3 |
| CO5 | 3 | 3 | 3 | | 3 | | | | | | | | 3 | 3 |

Course Assessment methods

| | Direct | Indirect | | | | | | |
|-----------------------------|-------------------------------|-------------------|--|--|--|--|--|--|
| Internal test I (6 marks) | Seminar/ Assignment (5 marks) | | | | | | | |
| Internal test II (6 marks) | Moodle test (7 marks) | Course and curvey | | | | | | |
| Internal test III (6 marks) | Attendance (5 marks) | Course end survey | | | | | | |
| Assignment (5 marks) | | | | | | | | |

Unit 01: INTRODUCTION

9 Hours

Introduction – Need for quality – Evolution of quality – Definitions of quality – Dimensions of product and service quality – Basic concepts of TQM – TQM Framework – Contributions of Deming, Juran and Crosby – Barriers to TQM – Quality statements – Customer focus – Customer orientation, Customer satisfaction, Customer complaints, and Customer retention – Costs of quality.

Unit 02: TQM PRINCIPLES

9 Hours

Leadership – Strategic quality planning, Quality Councils – Employee involvement – Motivation, Empowerment, Team and Teamwork, Quality circles Recognition and Reward, Performance appraisal – Continuous process improvement – PDCA cycle, 5S, Kaizen – Supplier partnership – Partnering, Supplier selection, Supplier Rating.

Unit 03: TQM PRACTICES

9 Hours

The seven traditional tools of quality – New management tools – Six sigma: Concepts, Methodology, applications to manufacturing, service sector including IT – Bench marking – Reason to bench mark, Bench marking process – FMEA – Stages, Types.

Unit 04: TQM TOOLS AND TECHNIQUES 9 Hours Control Charts - Process Capability - Concepts of Six Sigma - Quality Function Development (QFD) - Taguchi quality loss function-Lean manufacturing - TPM - Concepts, improvement needs - Performance measures. **Unit 05: QUALITY SYSTEMS** 9 Hours Need for ISO 9000 – ISO 9001-2008 Quality System – Elements, Documentation, Quality Auditing - QS 9000 - ISO 14000 - Concepts, Requirements and Benefits - TQM Implementation in manufacturing and service sectors. Theory: 45 Hrs Tutorial: --Practical: --**Total Hours: 45 Hrs TEXT BOOKS** 1. Dale H. Besterfiled, et at., "Total quality Management", Pearson Education Asia, Third Edition, Indian Reprint 2006. **REFERENCES** 1. James R. Evans and William M. Lindsay, "The Management and Control of Quality", 8th

2. Suganthi.L and Anand Samuel, "Total Quality Management", Prentice Hall (India) Pvt.

3. Janakiraman. B and Gopal .R.K., "Total Quality Management – Text and Cases", Prentice

Edition, First Indian Edition, Cengage Learning, 2012.

Ltd., 2006.

Hall (India) Pvt. Ltd., 2006.

| | U15MC703R ROBOTICS LABORATORY L T P C | | | | | | | | | | | | | | | |
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| CO2: | | se robo | | | | | | | strate. | • | | | | | | |
| CO3: | | rite pro | ogram | ming | for sir | nple c | perati | ions. | | | | | | | | |
| Pre-re | Pre-requisite | | | | | | | | | | | | | | | |
| | | | | | | | | | | | | | | | | |
| | CO/PO, PSO Mapping | | | | | | | | | | | | | | | |
| | CO/PO, PSO Mapping (3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak | | | | | | | | | | | | | | | |
| | (3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak | | | | | | | | | | | | | | | |
| COs | Programme Outcomes (POs) and Programme Specific Outcome (PSOs) PO1 PO2 PO3 PO4 PO5 PO6 PO7 PO8 PO9 PO10 PO11 PO12 PSO1 PSO2 | | | | | | | | | | | | | | | |
| CO1 | 3 | 3 | 2 | 2 | PO5 | PO6 | 2 | PO8 | P09 | 2 | POII | POI2 | | 3 | ŀ | 2 |
| CO2 | 3 | 2 | 3 | 2 | | | 2 | | | 2 | | | 1 | 3 | | 2 |
| CO3 | 3 | 3 | 2 | 2 | | | 2 | | | 2 | | | | 3 | | 2 |
| | | | | | | | | | | | | | | | | |
| | | | | | Co | urse A | Assess | ment | meth | ods | | | | | | |
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| Mean | of 1st | half of | Exper | iment | (10) | Ç | uiz or | n 2 nd ha | alf (5) | | | Cours | se ei | nd s | urv | ey |
| Quiz | on 1st | half (5) | | | | | | l test I | I (10) | | | | | | | |
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| | | half of | | rimen | t (10) | E | nd ser | nester | Exan | ninatio | n (40) | | | | | |
| | | erimen | | | | | | | | | | | | | | |
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| | | d coord | | | | | | | | | | | | | | |
| 3. | - | nation | | | | | - | | | | | | | | | |
| 4. | | | | | | | | | | | | | | | | |
| 5. Robot programming and simulation for Colour identification | | | | | | | | | | | | | | | | |
| 6. | | | | | | | | | | | | | | | | |
| 7. | Robo | t prog | | | | | | | | | | | | | | |

16.06.2021 Regulations-2015R

Robot programming and simulation for any industrial process (Packaging, Assembly)

Total Hours: 60 Hrs

Robot programming and simulation for writing practice

Robot programming and simulation for multi process.

8.

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| U1 | U15MC704R IMAGE PROCESSING LABORATORY | | | | | | | | | | | | | | | |
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| | CO/PO, PSO Mapping | | | | | | | | | | | | | | | |
| | (3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak | | | | | | | | | | | | | | | |
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| COs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | PO10 | PO11 | PO12 | | 601 | F | PSO2 |
| CO1 | 3 | 3 | 2 | 2 | | | 2 | | | 2 | | | , | 3 | | 2 |
| CO2 | 3 | 2 | 3 | 2 | | | 2 | | | 2 | | | , | 3 | | 2 |
| CO3 | | | | | | | | | | | | | | | | |
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| Course Assessment methods | | | | | | | | | | | | | | | | |
| Direct Indirect | | | | | | | | | | | | | | | | |
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| Mean | of 1st h | alf of | Exper | iment | | | uiz or | n 2 nd ha | alf (5) | | | Cours | | | | ey |
| Quiz | on 1st h | alf (5) | Exper | iment | | Q Ir | nterna | l test I | ` ' | | | Cours | | | | ey |
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| Quiz Interr Mean | on 1 st h nal test of 2 nd l | alf (5) I (10) half of | Expe | | (10) | C Ir R | nterna TPS (1 | l test I l0) | I (10) | ninatio | n (40) | Cours | | | | ey |
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16.06.2021 Regulations-2015R

Total Hours: 45 Hrs

| U15M | 4C705R | TECHNICAL SEMINAR | L | T | P | C | | |
|--------------------|----------------|--|------|-----|---|-----|--|--|
| | | | 0 | 0 | 3 | 1.5 | | |
| Course | ourse Outcomes | | | | | | | |
| After su | ccessful co | mpletion of this course, the students should be able to | | | | | | |
| CO1: | Select a to | pic relevant to analysis, design and management of a Mecha | tron | ics | | | | |
| | engineerir | ng system. | | | | | | |
| CO2: | Carry out | a critical review of the literature on the chosen topic. | | | | | | |
| CO3: | Prepare ar | nd present a technical report. | | | | | | |
| Pre-requ | | | | | | | | |
| CO/PO, PSO Mapping | | | | | | | | |

(3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak

| COs | | Programme Outcomes (POs) and Programme Specific Outcome (PSOs) | | | | | | | | | | | | |
|-----|-----|--|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|
| 203 | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | PO10 | PO11 | PO12 | PSO1 | PSO2 |
| CO1 | 2 | 1 | 1 | 1 | | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 3 | 2 |
| CO2 | 2 | 1 | 1 | 1 | | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 3 | 2 |
| CO3 | | | 1 | 1 | | 2 | 3 | 3 | 3 | 3 | 2 | 2 | 3 | 2 |

Course Assessment methods

| Direct | l . | Indirect |
|---------------------------------------|-------------------------------|-------------------|
| Relevance of the topic and literature | End semester Examination (40) | Course end survey |
| survey (15) | | |
| Presentation and discussion(30) | | |
| Regularity in the class and Active | | |
| Participation in the seminar(15) | | |

To kindle as well as measure the ability of the student to study a topic in Mechatronics Engineering, of current relevance, from technical literature and present a seminar on that topic. Arousing their field of interest in Mechatronics engineering, individual students are guided to choose a topic. Give a seminar on that topic for about fifteen minutes. It enables the students to gain knowledge in any of the technically relevant current topics and imparts confidence in the students in presenting the topic. The student will undertake a detailed study on the chosen topic under the supervision of a faculty member, by referring to papers published in reputed journals and conference proceedings. The seminar coordinator for the respective class is appointed by the Head of the Department. Respective seminar coordinator of the section will monitor the attendance for the technical seminar hours. With the approval of the Head of the Department, the respective seminar coordinator will arrange for reviewing the seminar. Each student has to submit a seminar report, based on the papers he/she has studied; the report should not be a reproduction of any original paper. Instead the student should evolve and construct his/her own ideas and enrich the seminar presentation and report. The candidate is expected to submit the seminar report on or before the last working day of the semester. The report will be duly acknowledged by Head of the Department. Final evaluation will be conducted in the form of project viva voce and also seminar will be evaluated on an internal assessment basis.

16.06.2021 Regulations-2015R

Total Hours: 45 Hrs

| Course (| Outcon | nes | | 30 | PKINI | ING IE | | U15MC1002R 3D PRINTING TECHNOLOGY | | | | | | | | |
|---|--|--|---------------|-------------|--------------------|--------------------|---------------------|-----------------------------------|--------------|---------|----------|---------|---------|------|--|--|
| | ccessf | | 3 0 | | | | | | | | |) | 0 | 3 | | |
| After su | 1 | After successful completion of this course, the students should be able to | | | | | | | | | | | | | | |
| After successful completion of this course, the students should be able to CO6: Explain steps involved in Rapid tooling and Addictive manufacturing. | | | | | | | | | | | | | | | | |
| CO6: | CO7: Discuss various fabrication & modelling techniques. | | | | | | | | | | | | | | | |
| CO7: | Discu | ıss vaı | rious fa | bricati | on & m | odelling | g techn | iques. | | | | | | | | |
| CO8: | Analy mach | | e worki | ng prir | nciple o | f variou | ıs prec | ision in: | strumer | nts bas | ed on la | aser, E | lectron | beam | | |
| CO9: | Descr | ribe th | ne conc | ept of | 3D prin | ting, D | irect ar | nd Indir | ect tool | ing tec | hnique | s. | | | | |
| CO10: | Ident | ify the | e suital | ole AM | proces | s to fab | ricate _l | ohysica | l compo | nents. | | | | | | |
| Pre-requ | | | | | | | | | | | | | | | | |
| 3. | 3. Engineering Physics | | | | | | | | | | | | | | | |
| 4. | 4. Manufacturing Technology | | | | | | | | | | | | | | | |
| | CO/PO, PSO Mapping | | | | | | | | | | | | | | | |
| (3/2/1 indicates strength of correlation) 3-Strong, 2-Medium, 1-Weak | | | | | | | | | | | | | | | | |
| Programme Outcomes (POs) and Programme Specific Outcome (PSOs) | | | | | | | | | | | | | | | | |
| Р | 01 F | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | P09 | PO10 | PO11 | PO12 | PSO1 | PSO2 | | |
| CO1 | 3 | 3 | 3 | | 3 | | | | | | | | 3 | 3 | | |
| CO2 | 3 | 3 | 3 | | 3 | | | | | | | | 3 | 3 | | |
| СОЗ | 3 | 3 | 3 | | 3 | | | | | | | | 3 | 3 | | |
| CO4 | 3 | 3 | 3 | | 3 | | | | | | | | 3 | 3 | | |
| CO5 | 3 | 3 | 3 | | 3 | | | | | | | | 3 | 3 | | |
| | • | • | • | | Cours | e Asse | essmei | nt met | hods | | ' | | | | | |
| | | | | D | irect | | | | | | | Indir | ect | | | |
| Internal t Internal t Internal t Assignme | est II (est III | (6 ma (6 ma | rks) arks) | Mod Atte | odle tes endanc | st (7 m e (5 ma | arks) arks) | marks |) 0 marks | s) | Cou | rse end | d surve | у | | |
| Jnit 01: | Int | trodu | ction | <u> </u> | | | | | | l | | | 9 Hou | ırs | | |
| Needs - Impact of AM and Rapid Tooling on Product Development - Distinction between AM and CNC Machining- The Generalized AM Process chain - CAD Model - Input file formats - Generation and Conversion of STL file - File Verification and Repair - Build File Creation - Part Cleaning and finishing - RP Benefits - Classification of RP systems | | | | | | | | | | | | | | | | |
| Stereolithography Apparatus (SLA), Digital Light Projection (DLP), Photo polymerization process, Solid Ground Curing (SGC), Fused Deposition Modeling (FDM) and Laminated Object Manufacturing (LOM) - | | | | | | | | | | | | | | | | |

Selective Laser Sintering (SLS), Three-dimensional Printing (3DP), Direct Metal Deposition (DMD), Ballistic Particle Manufacturing (BPM), Electron Beam Melting (EBM) and Laser Engineered Net Shaping (LENS)- Working Principle, Construction, Process Variables, Materials and Applications

Working Principle, Construction, Materials and Applications.

9 Hours

POWDER BASED SYSTEMS

Unit 03:

| Unit 04: OPEN SOURCE PRINTER AND RAPID TOOLING 9 Hours | | | | | | | | | | | | | | |
|---|---|-------------------|-----------------------|----------|---------------------|------|--|--|--|--|--|--|--|--|
| Introd tooling | Concept of open source 3D printer - Structural details, Control mechanism - Materials and Applications. Introduction to rapid tooling (RT) - Direct and Indirect tooling - Silicone rubber moulding, Epoxy tooling, Spray Metal Coating, Electro Optical Sintering (EOS) - Working Principle, Materials and Applications Unit 05: APPLICATIONS OF ADDITIVE MANUFACTURING 9 Hours | | | | | | | | | | | | | |
| Unit 05: APPLICATIONS OF ADDITIVE MANUFACTURING 9 Hours | | | | | | | | | | | | | | |
| | Application of Rapid prototyping in Medical field, Manufacturing, Automotive industries, Aerospace and Electronics and Retail industries. Leading manufacturer of RP systems | | | | | | | | | | | | | |
| Т | Theory: 45 Hrs Tutorial: Practical: Total Hours: 45 Hrs | | | | | | | | | | | | | |
| | Text Books | | | | | | | | | | | | | |
| 3. | C. K. Chua, K. F. Leo Cambridge University | - | n, Rapid prototyping: | Principl | es and application | ons, | | | | | | | | |
| 4. | D. T.Pham and S. S. | Dimov, Rapid ma | nufacturing, Springer | -Verla | g, London, 2001. | | | | | | | | | |
| | REFERENCES | | | | | | | | | | | | | |
| 4. | I. Gibson, D. W. Rose Prototyping to Direct | • | • | _ | lethodologies: Ra | apid | | | | | | | | |
| 5. | Prototyping to Direct Digital Manufacturing, Springer, 2010 5. L.W. Liou, F.W. Liou, Rapid Prototyping and Engineering applications: A toolbox for prototype development, CRC Press, 2013. | | | | | | | | | | | | | |
| 6. | A. K. Kamrani, E. A. | Nasr, Rapid Prote | otyping: Theory and p | ractice | e, Springer, 2006 | 5 | | | | | | | | |

Sona College of Technology, Salem (An Autonomous Institution)

Courses of Study for B.E/B.Tech. Semester VIII 2015R (CBCS)

Branch: Mechatronics Engineering

| S. No | Course Code | Course Title | Lecture | Tutorial | Practical | Credit | Total Contact Hours |
|-------|-------------|--------------|---------|----------|-------------|--------|---------------------------|
| | | Practical | | | | | |
| 1 | U15MC801R | Project Work | 0 | 0 | 24 | 12 | 360 |
| | | | | To | tal Credits | 12 | |

Approved By

Chairperson, Fashion Technology BoS

Dr.P.Suresh

Member Secretary, Academic Council Dr.R.Shivakumar Chairperson, Academic Council & Principal Dr.S.R.R.Senthil Kumar

Copy to:-

HOD/ Mechatronics Engineering, Eighth Semester BE MCT Students and Staff, COE